

# Lecture 6

## Discrete Time Series

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9/21/2018

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## Stationary Processes

A stochastic process (i.e. a time series) is considered to be *strictly stationary* if the properties of the process are not changed by a shift in origin.

In the time series context this means that the joint distribution of  $\{y_{t_1}, \dots, y_{t_n}\}$  must be identical to the distribution of  $\{y_{t_1+k}, \dots, y_{t_n+k}\}$  for any value of  $n$  and  $k$ .

Strict stationary is unnecessarily strong / restrictive for many applications, so instead we often opt for *weak stationary* which requires the following,

1. The process has finite variance

$$E(y_t^2) < \infty \text{ for all } t$$

2. The mean of the process is constant

$$E(y_t) = \mu \text{ for all } t$$

3. The second moment only depends on the lag

$$Cov(y_t, y_s) = Cov(y_{t+k}, y_{s+k}) \text{ for all } t, s, k$$

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When we say stationary in class we will almost always mean *weakly stationary*.

## Autocorrelation

For a stationary time series, where  $E(y_t) = \mu$  and  $\text{Var}(y_t) = \sigma^2$  for all  $t$ , we define the autocorrelation at lag  $k$  as

$$\begin{aligned}\rho_k &= \text{Cor}(y_t, y_{t+k}) \\ &= \frac{\text{Cov}(y_t, y_{t+k})}{\sqrt{\text{Var}(y_t)\text{Var}(y_{t+k})}} \\ &= \frac{E((y_t - \mu)(y_{t+k} - \mu))}{\sigma^2}\end{aligned}$$

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this is also sometimes written in terms of the autocovariance function ( $\gamma_k$ ) as

$$\begin{aligned}\gamma_k &= \gamma(t, t+k) = \text{Cov}(y_t, y_{t+k}) \\ \rho_k &= \frac{\gamma(t, t+k)}{\sqrt{\gamma(t, t)\gamma(t+k, t+k)}} = \frac{\gamma(k)}{\gamma(0)}\end{aligned}$$



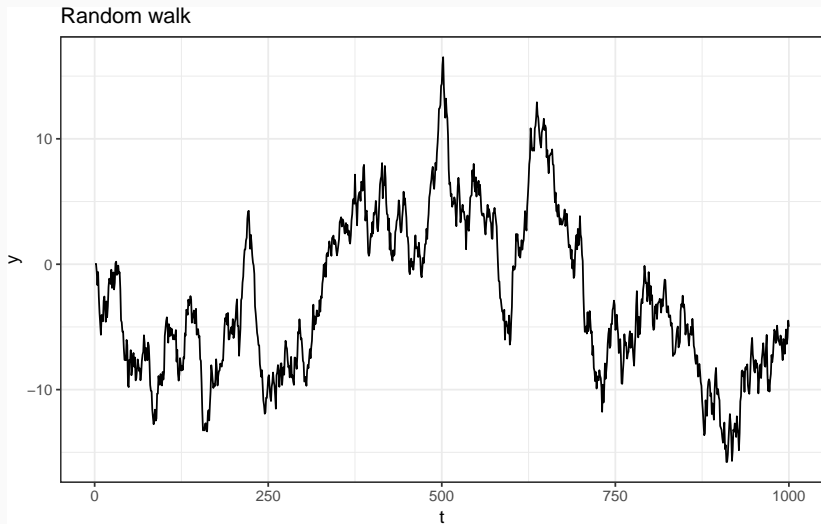
Based on our definition of a (weakly) stationary process, it implies a covariance of the following structure,

$$\Sigma = \begin{pmatrix} \gamma(0) & \gamma(1) & \gamma(2) & \gamma(3) & \cdots & \gamma(n-1) & \gamma(n) \\ \gamma(1) & \gamma(0) & \gamma(1) & \gamma(2) & \cdots & \gamma(n-2) & \gamma(n-1) \\ \gamma(2) & \gamma(1) & \gamma(0) & \gamma(1) & \cdots & \gamma(n-3) & \gamma(n-2) \\ \gamma(3) & \gamma(2) & \gamma(1) & \gamma(0) & \cdots & \gamma(n-4) & \gamma(n-3) \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \gamma(n-1) & \gamma(n-2) & \gamma(n-3) & \gamma(n-4) & \cdots & \gamma(0) & \gamma(1) \\ \gamma(n) & \gamma(n-1) & \gamma(n-2) & \gamma(n-3) & \cdots & \gamma(1) & \gamma(0) \end{pmatrix}$$

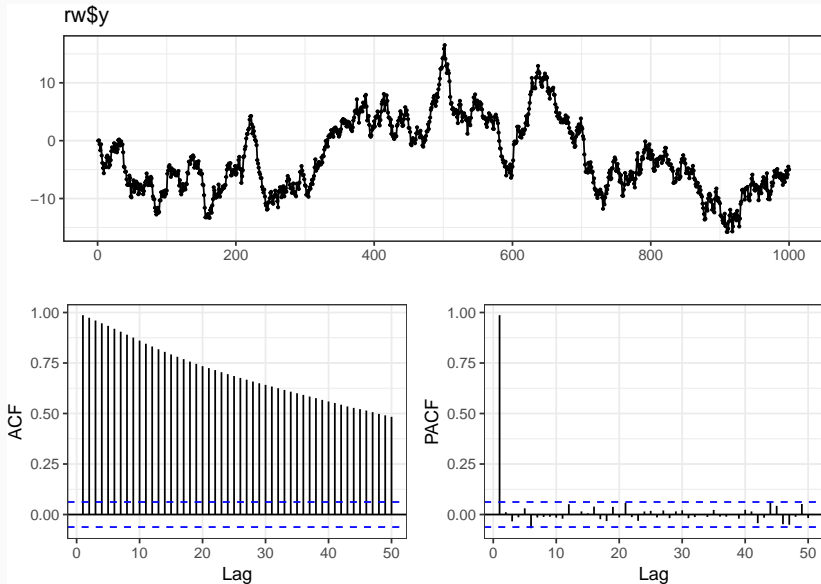
where  $P_{t,k}(\mathbf{y})$  is the project of  $\mathbf{y}$  onto the space spanned by  $\mathbf{y}_{t+1}, \dots, \mathbf{y}_{t+k-1}$ .

## Example - Random walk

Let  $y_t = y_{t-1} + w_t$  with  $y_0 = 0$  and  $w_t \sim \mathcal{N}(0, 1)$ .



# ACF + PACF



## Stationary?

Is  $y_t$  stationary?

Given these type of patterns in the autocorrelation we often want to examine the relationship between  $y_t$  and  $y_{t+k}$  with the (linear) dependence of  $y_t$  on  $y_{t+1}$  through  $y_{t+k-1}$  removed.

This is done through the calculation of a partial autocorrelation ( $\alpha(k)$ ), which is defined as follows:

$$\alpha(0) = 1$$

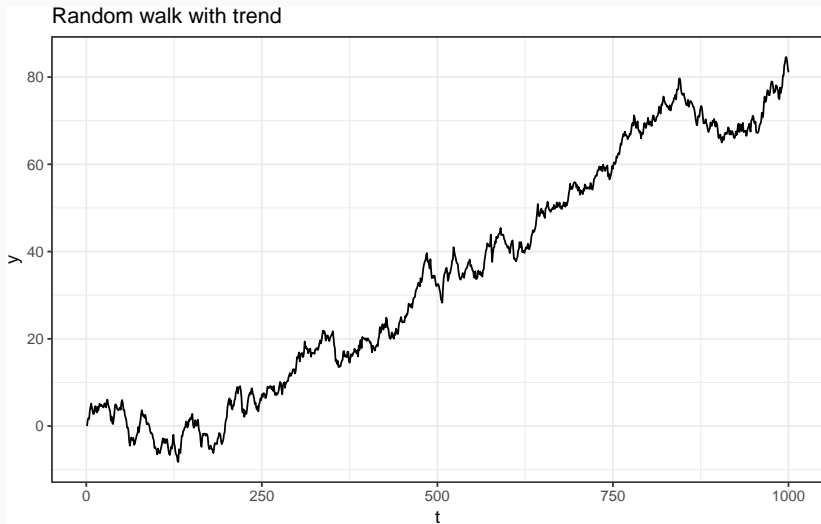
$$\alpha(1) = \rho(1) = \text{Cor}(y_t, y_{t+1})$$

$$\vdots$$

$$\alpha(k) = \text{Cor}(y_t - P_{t,k}(y_t), y_{t+k} - P_{t,k}(y_{t+k}))$$

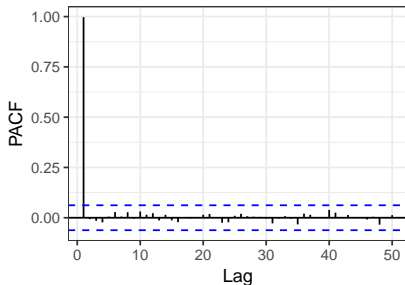
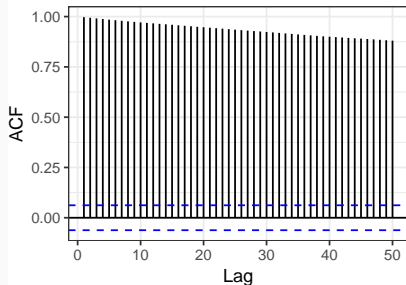
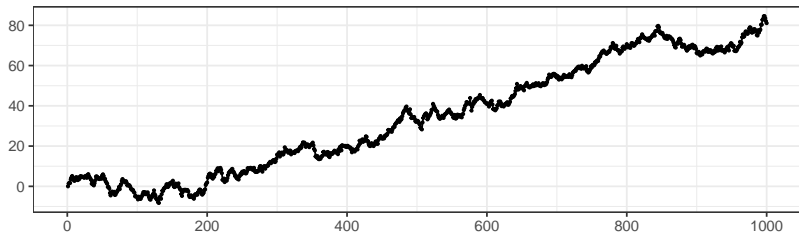
## Example - Random walk with drift

Let  $y_t = \delta + y_{t-1} + w_t$  with  $y_0 = 0$  and  $w_t \sim \mathcal{N}(0, 1)$ .



# ACF + PACF

rwt\$y



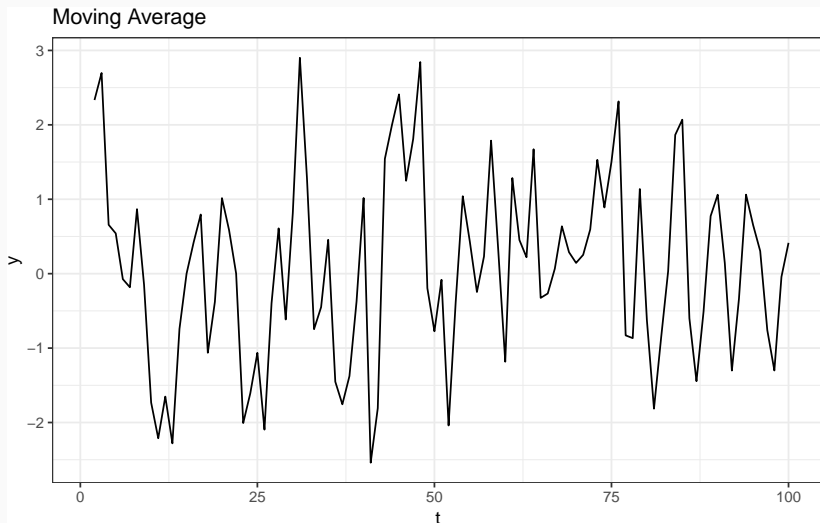
## Stationary?

Is  $y_t$  stationary?

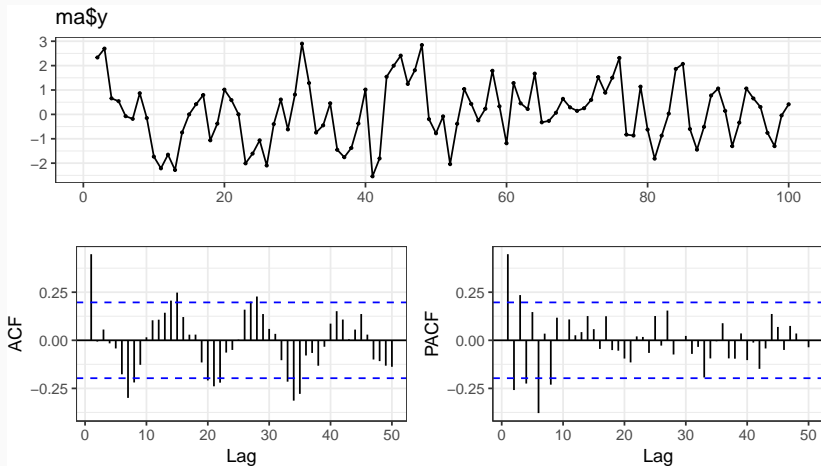


## Example - Moving Average

Let  $w_t \sim \mathcal{N}(0, 1)$  and  $y_t = w_{t-1} + w_t$ .



# ACF + PACF

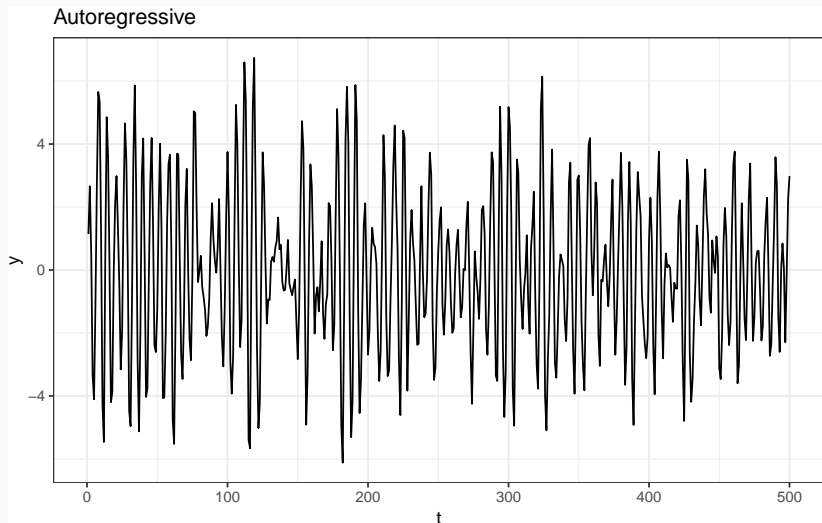


## Stationary?

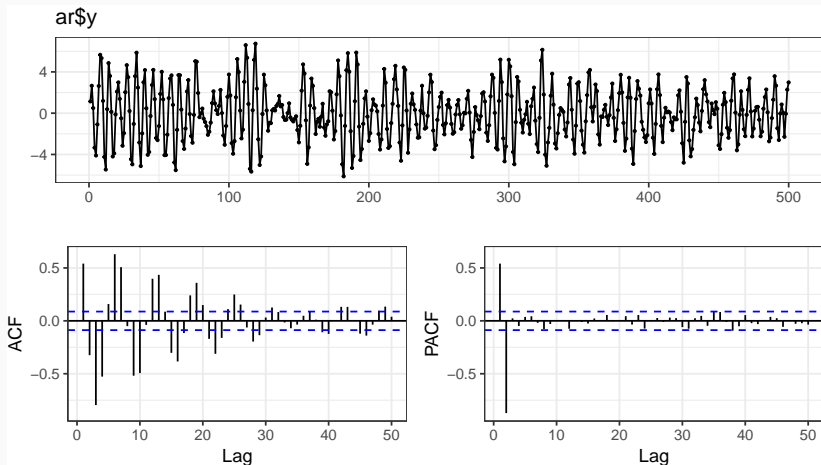
Is  $y_t$  stationary?

# Autoregressive

Let  $w_t \sim \mathcal{N}(0, 1)$  and  $y_t = y_{t-1} - 0.9y_{t-2} + w_t$  with  $y_t = 0$  for  $t < 1$ .



# ACF + PACF

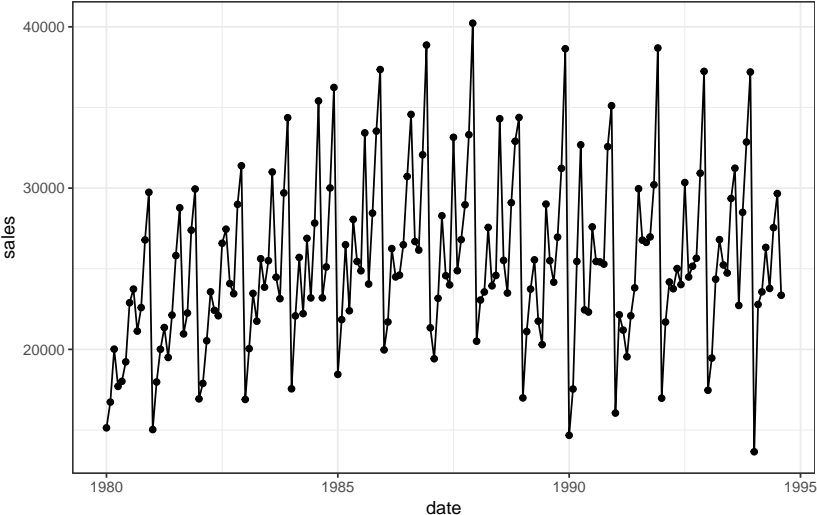


## Example - Australian Wine Sales

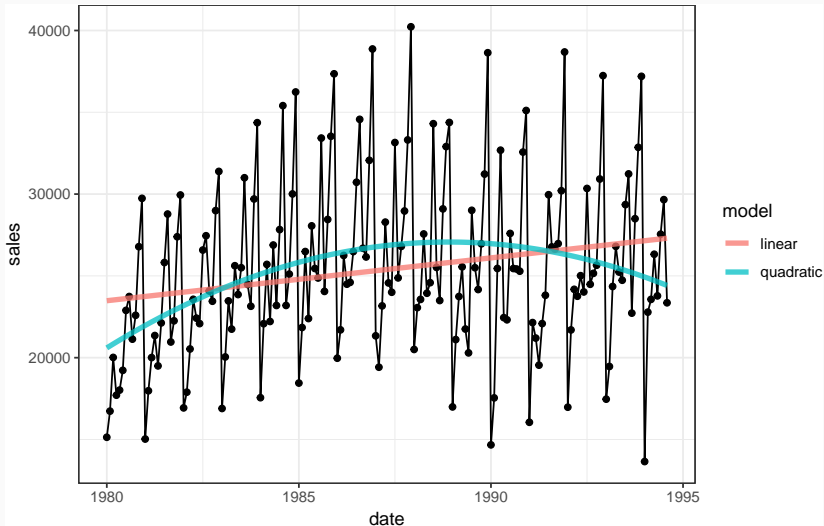
Australian total wine sales by wine makers in bottles  $\leq$  1 litre. Jan 1980 – Aug 1994.

```
aus_wine = readRDS("../data/aus_wine.rds")
aus_wine
## # A tibble: 176 x 2
##   date sales
##   <dbl> <dbl>
## 1 1980 15136
## 2 1980. 16733
## 3 1980. 20016
## 4 1980. 17708
## 5 1980. 18019
## 6 1980. 19227
## 7 1980. 22893
## 8 1981. 23739
## 9 1981. 21133
## 10 1981. 22591
## # ... with 166 more rows
```

# Time series

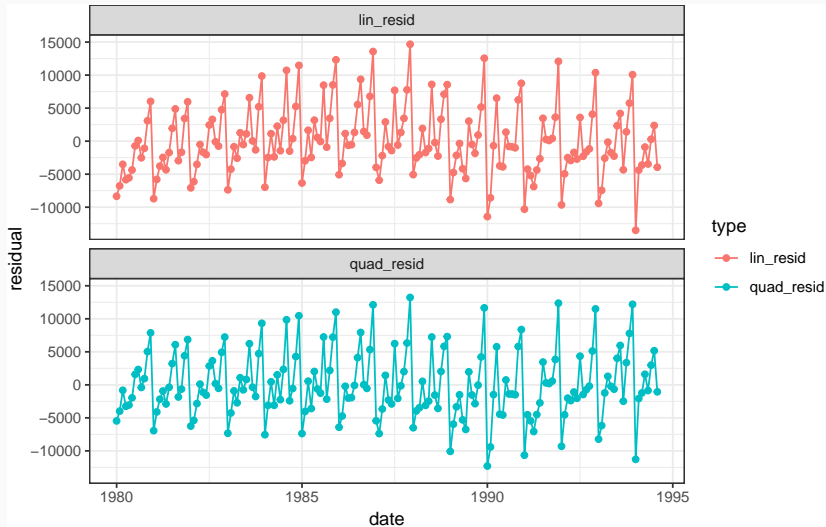


# Basic Model Fit

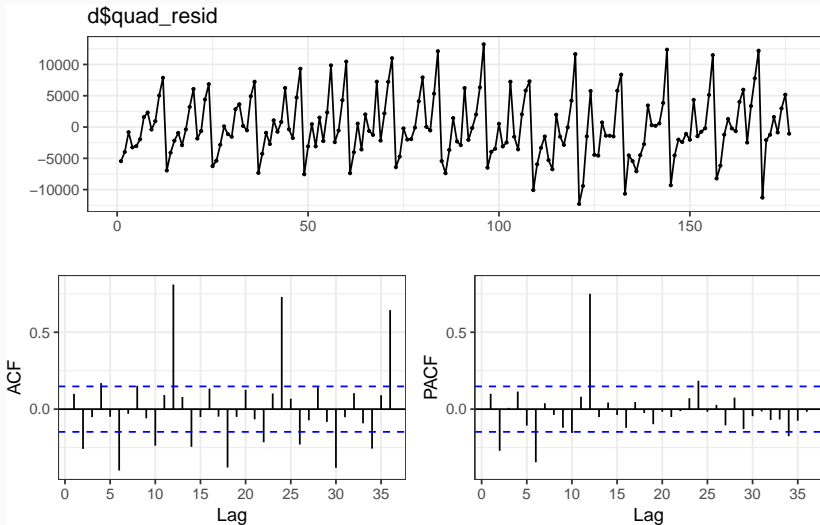


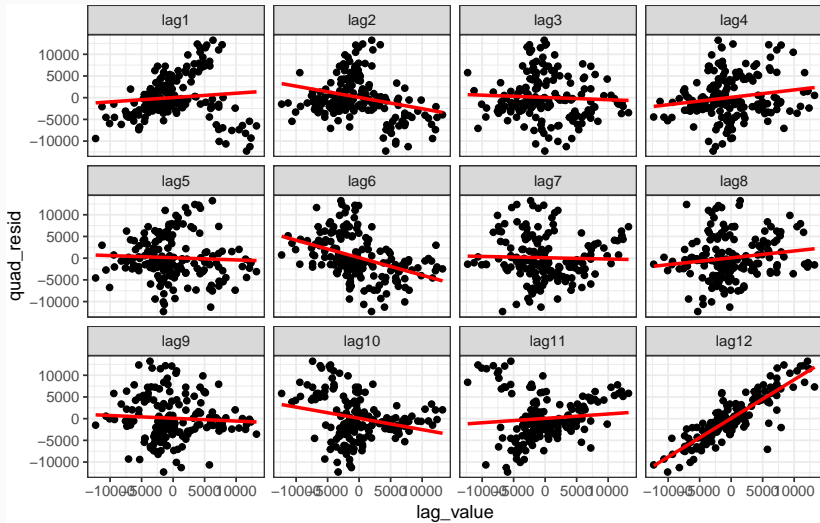


# Residuals



# Autocorrelation Plot

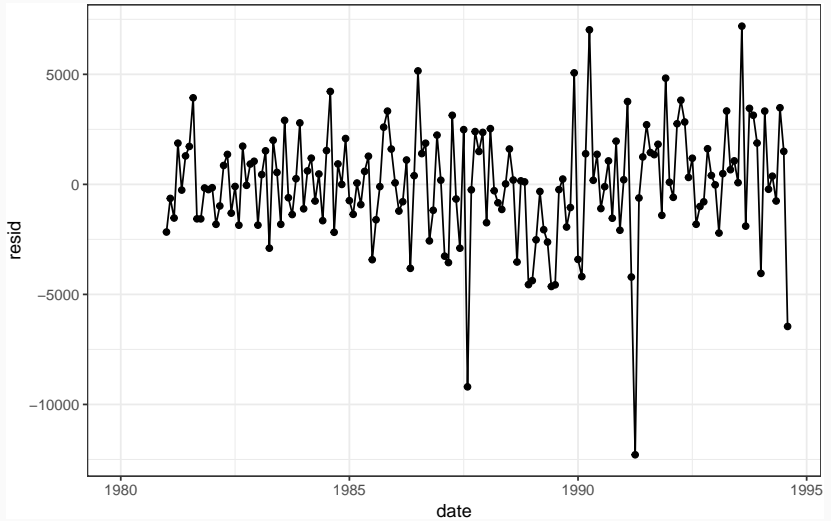




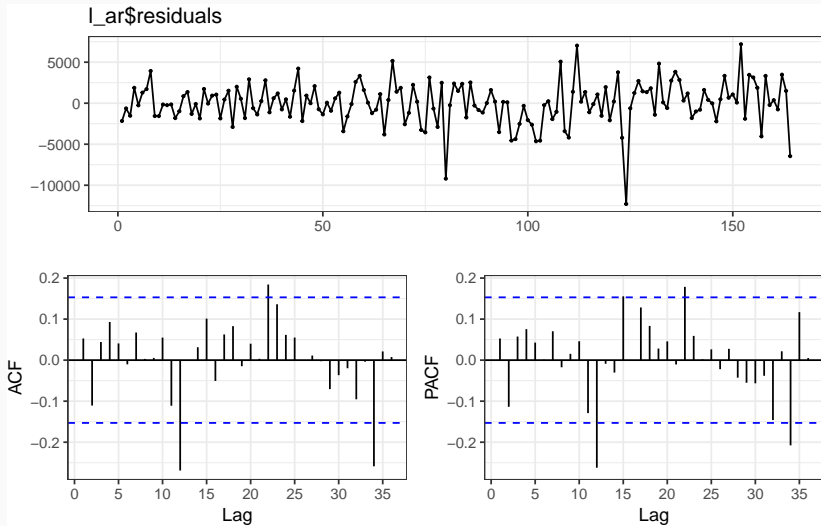
## Auto regressive errors

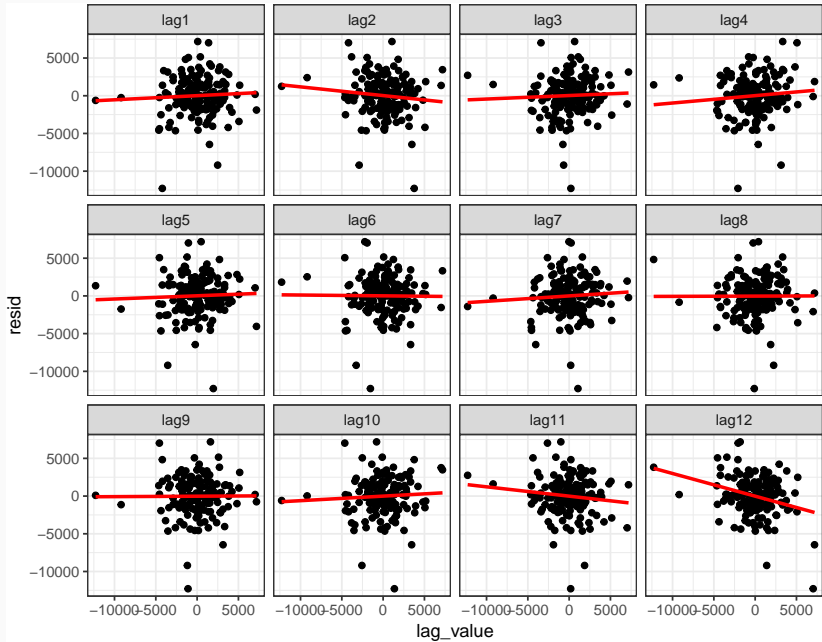
```
##  
## Call:  
## lm(formula = quad_resid ~ lag_12, data = d_ar)  
##  
## Residuals:  
##      Min       1Q   Median       3Q      Max  
## -12286.5  -1380.5    73.4   1505.2   7188.1  
##  
## Coefficients:  
##              Estimate Std. Error t value Pr(>|t|)  
## (Intercept)  83.65080   201.58416    0.415   0.679  
## lag_12       0.89024     0.04045   22.006 <2e-16 ***  
## ---  
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1  
##  
## Residual standard error: 2581 on 162 degrees of freedom  
## (12 observations deleted due to missingness)  
## Multiple R-squared:  0.7493, Adjusted R-squared:  0.7478  
## F-statistic: 484.3 on 1 and 162 DF,  p-value: < 2.2e-16
```

# Residual residuals



# Residual residuals - acf





## Writing down the model?

So, is our EDA suggesting that we fit the following model?

$$\text{sales}(t) = \beta_0 + \beta_1 t + \beta_2 t^2 + \beta_3 \text{sales}(t - 12) + \epsilon_t$$



## Writing down the model?

So, is our EDA suggesting that we fit the following model?

$$\text{sales}(t) = \beta_0 + \beta_1 t + \beta_2 t^2 + \beta_3 \text{sales}(t - 12) + \epsilon_t$$

the model we actually fit is,

$$\text{sales}(t) = \beta_0 + \beta_1 t + \beta_2 t^2 + w_t$$

where

$$w_t = \delta w_{t-12} + \epsilon_t$$