

# Lecture 12

## Gaussian Process Models

---

10/17/2018

# Multivariate Normal

---

## Multivariate Normal Distribution

For an  $n$ -dimension multivariate normal distribution with covariance  $\Sigma$  (positive semidefinite) can be written as

$$\mathbf{Y}_{n \times 1} \sim N\left(\boldsymbol{\mu}_{n \times 1}, \boldsymbol{\Sigma}_{n \times n}\right) \text{ where } \{\boldsymbol{\Sigma}\}_{ij} = \sigma_{ij}^2 = \rho_{ij} \sigma_i \sigma_j$$

$$\begin{pmatrix} Y_1 \\ \vdots \\ Y_n \end{pmatrix} \sim N\left(\begin{pmatrix} \mu_1 \\ \vdots \\ \mu_n \end{pmatrix}, \begin{pmatrix} \rho_{11}\sigma_1\sigma_1 & \cdots & \rho_{1n}\sigma_1\sigma_n \\ \vdots & \ddots & \vdots \\ \rho_{n1}\sigma_n\sigma_1 & \cdots & \rho_{nn}\sigma_n\sigma_n \end{pmatrix}\right)$$

For the  $n$  dimensional multivariate normal given on the last slide, its density is given by

$$(2\pi)^{-n/2} \det(\boldsymbol{\Sigma})^{-1/2} \exp \left( -\frac{1}{2} (\mathbf{Y} - \boldsymbol{\mu})' \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \boldsymbol{\mu}) \right)$$

$1 \times n$        $n \times n$        $n \times 1$

and its log density is given by

$$-\frac{n}{2} \log 2\pi - \frac{1}{2} \log \det(\boldsymbol{\Sigma}) - \frac{1}{2} (\mathbf{Y} - \boldsymbol{\mu})' \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \boldsymbol{\mu})$$

$1 \times n$        $n \times n$        $n \times 1$

To generate draws from an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ ,

To generate draws from an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ ,

- Find a matrix  $\mathbf{A}$  such that  $\boldsymbol{\Sigma} = \mathbf{A} \mathbf{A}^t$ , most often we use  $\mathbf{A} = \text{Chol}(\boldsymbol{\Sigma})$  where  $\mathbf{A}$  is a lower triangular matrix.

To generate draws from an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ ,

- Find a matrix  $\mathbf{A}$  such that  $\boldsymbol{\Sigma} = \mathbf{A} \mathbf{A}^t$ , most often we use  $\mathbf{A} = \text{Chol}(\boldsymbol{\Sigma})$  where  $\mathbf{A}$  is a lower triangular matrix.
- Draw  $n$  iid unit normals ( $\mathcal{N}(0, 1)$ ) as  $\mathbf{z}$

# Sampling

To generate draws from an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ ,

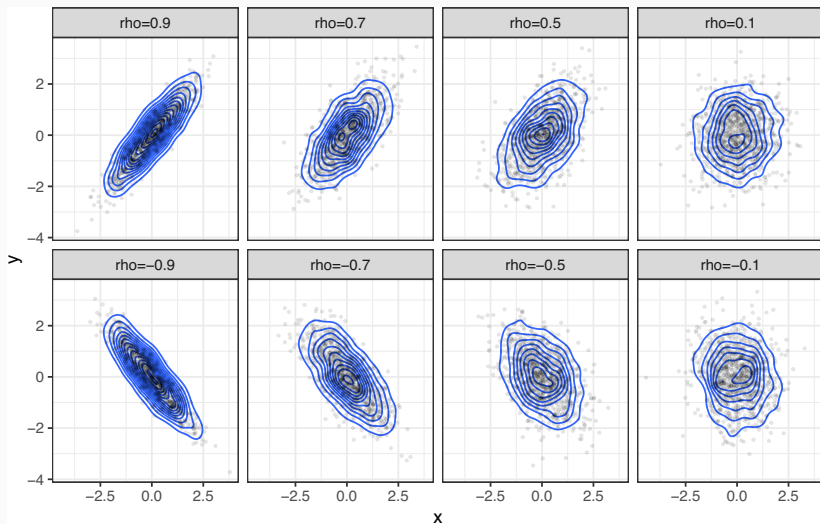
- Find a matrix  $\mathbf{A}$  such that  $\boldsymbol{\Sigma} = \mathbf{A} \mathbf{A}^t$ , most often we use  $\mathbf{A} = \text{Chol}(\boldsymbol{\Sigma})$  where  $\mathbf{A}$  is a lower triangular matrix.
- Draw  $n$  iid unit normals ( $\mathcal{N}(0, 1)$ ) as  $\mathbf{z}$
- Obtain multivariate normal draws using

$$\underset{n \times 1}{\mathbf{Y}} = \underset{n \times 1}{\boldsymbol{\mu}} + \underset{n \times n}{\mathbf{A}} \underset{n \times 1}{\mathbf{z}}$$



# Bivariate Example

$$\mu = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \Sigma = \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix}$$



## Marginal distributions

**Proposition** - For an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ , any marginal or conditional distribution of the  $y$ 's will also be (multivariate) normal.

## Marginal distributions

**Proposition** - For an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ , any marginal or conditional distribution of the  $y$ 's will also be (multivariate) normal.

For a univariate marginal distribution,

$$y_i = \mathcal{N}(\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_{ii})$$

## Marginal distributions

**Proposition** - For an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ , any marginal or conditional distribution of the  $y$ 's will also be (multivariate) normal.

For a univariate marginal distribution,

$$y_i = \mathcal{N}(\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_{ii})$$

For a bivariate marginal distribution,

$$\mathbf{y}_{ij} = \mathcal{N}\left(\begin{pmatrix} \boldsymbol{\mu}_i \\ \boldsymbol{\mu}_j \end{pmatrix}, \begin{pmatrix} \boldsymbol{\Sigma}_{ii} & \boldsymbol{\Sigma}_{ij} \\ \boldsymbol{\Sigma}_{ji} & \boldsymbol{\Sigma}_{jj} \end{pmatrix}\right)$$

## Marginal distributions

**Proposition** - For an  $n$ -dimensional multivariate normal with mean  $\boldsymbol{\mu}$  and covariance matrix  $\boldsymbol{\Sigma}$ , any marginal or conditional distribution of the  $y$ 's will also be (multivariate) normal.

For a univariate marginal distribution,

$$y_i = \mathcal{N}(\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_{ii})$$

For a bivariate marginal distribution,

$$\mathbf{y}_{ij} = \mathcal{N}\left(\begin{pmatrix} \boldsymbol{\mu}_i \\ \boldsymbol{\mu}_j \end{pmatrix}, \begin{pmatrix} \boldsymbol{\Sigma}_{ii} & \boldsymbol{\Sigma}_{ij} \\ \boldsymbol{\Sigma}_{ji} & \boldsymbol{\Sigma}_{jj} \end{pmatrix}\right)$$

For a  $k$ -dimensional marginal distribution,

$$\mathbf{y}_{i,\dots,k} = \mathcal{N}\left(\begin{pmatrix} \boldsymbol{\mu}_i \\ \vdots \\ \boldsymbol{\mu}_k \end{pmatrix}, \begin{pmatrix} \boldsymbol{\Sigma}_{ii} & \cdots & \boldsymbol{\Sigma}_{ik} \\ \vdots & \ddots & \vdots \\ \boldsymbol{\Sigma}_{ki} & \cdots & \boldsymbol{\Sigma}_{kk} \end{pmatrix}\right)$$

## Conditional Distributions

If we partition the  $n$ -dimensions into two pieces such that  $\mathbf{Y} = (\mathbf{Y}_1, \mathbf{Y}_2)^t$  then

$$\mathbf{Y}_{n \times 1} \sim \mathcal{N} \left( \begin{pmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{pmatrix}, \begin{pmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{pmatrix} \right)$$

$$\mathbf{Y}_{k \times 1} \sim \mathcal{N} \left( \begin{matrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{matrix}, \begin{matrix} \boldsymbol{\Sigma}_{11} \\ \boldsymbol{\Sigma}_{22} \end{matrix} \right)$$

$$\mathbf{Y}_{n-k \times 1} \sim \mathcal{N} \left( \begin{matrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{matrix}, \begin{matrix} \boldsymbol{\Sigma}_{11} \\ \boldsymbol{\Sigma}_{22} \end{matrix} \right)$$

## Conditional Distributions

If we partition the  $n$ -dimensions into two pieces such that  $\mathbf{Y} = (\mathbf{Y}_1, \mathbf{Y}_2)^t$  then

$$\mathbf{Y}_{n \times 1} \sim \mathcal{N} \left( \begin{pmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{pmatrix}, \begin{pmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{pmatrix} \right)$$

$$\mathbf{Y}_{k \times 1} \sim \mathcal{N} \left( \boldsymbol{\mu}_1, \boldsymbol{\Sigma}_{11} \right)$$

$$\mathbf{Y}_{n-k \times 1} \sim \mathcal{N} \left( \boldsymbol{\mu}_2, \boldsymbol{\Sigma}_{22} \right)$$

then the conditional distributions are given by

$$\mathbf{Y}_1 | \mathbf{Y}_2 = \mathbf{a} \sim \mathcal{N} \left( \boldsymbol{\mu}_1 + \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} (\mathbf{a} - \boldsymbol{\mu}_2), \boldsymbol{\Sigma}_{11} - \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} \boldsymbol{\Sigma}_{21} \right)$$

$k \times 1$        $k \times 1$      $k \times n-k$      $n-k \times 1$      $n-k \times k$      $k \times k$      $k \times n-k$      $n-k \times n-k$      $n-k \times k$

$$\mathbf{Y}_2 | \mathbf{Y}_1 = \mathbf{b} \sim \mathcal{N} \left( \boldsymbol{\mu}_2 + \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} (\mathbf{b} - \boldsymbol{\mu}_1), \boldsymbol{\Sigma}_{22} - \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} \boldsymbol{\Sigma}_{21} \right)$$

From Shumway,

A process,  $\mathbf{Y} = \{Y(t) : t \in T\}$ , is said to be a Gaussian process if all possible finite dimensional vectors  $\mathbf{y} = (y_{t_1}, y_{t_2}, \dots, y_{t_n})^t$ , for every collection of time points  $t_1, t_2, \dots, t_n$ , and every positive integer  $n$ , have a multivariate normal distribution.

$$\mathbf{y} = (y(t_1), y(t_2), \dots, y(t_n))$$



From Shumway,

*A process,  $\mathbf{Y} = \{Y(t) : t \in T\}$ , is said to be a Gaussian process if all possible finite dimensional vectors  $\mathbf{y} = (y_{t_1}, y_{t_2}, \dots, y_{t_n})^t$ , for every collection of time points  $t_1, t_2, \dots, t_n$ , and every positive integer  $n$ , have a multivariate normal distribution.*

So far we have only looked at examples of time series where  $T$  is discrete (and evenly spaced & contiguous), it turns out things get a lot more interesting when we explore the case where  $T$  is defined on a *continuous* space (e.g.  $\mathbb{R}$  or some subset of  $\mathbb{R}$ ).

# Gaussian Process Regression

---

## Parameterizing a Gaussian Process

Imagine we have a Gaussian process defined such that

$$\mathbf{Y} = \{Y(t) : t \in [0, 1]\},$$

## Parameterizing a Gaussian Process

Imagine we have a Gaussian process defined such that

$$\mathbf{Y} = \{Y(t) : t \in [0, 1]\},$$

- We now have an uncountably infinite set of possible  $t$ 's and  $Y(t)$ s.

## Parameterizing a Gaussian Process

Imagine we have a Gaussian process defined such that

$$\mathbf{Y} = \{Y(t) : t \in [0, 1]\},$$

- We now have an uncountably infinite set of possible  $t$ 's and  $Y(t)$ s.
- We will only have a (small) finite number of observations  $Y(t_1), \dots, Y(t_n)$  with which to say something useful about this infinite dimensional process.

## Parameterizing a Gaussian Process

Imagine we have a Gaussian process defined such that

$$\mathbf{Y} = \{Y(t) : t \in [0, 1]\},$$

- We now have an uncountably infinite set of possible  $t$ 's and  $Y(t)$ s.
- We will only have a (small) finite number of observations  $Y(t_1), \dots, Y(t_n)$  with which to say something useful about this infinite dimensional process.
- The unconstrained covariance matrix for the observed data can have up to  $n(n + 1)/2$  unique values\*



## Parameterizing a Gaussian Process

Imagine we have a Gaussian process defined such that

$$\mathbf{Y} = \{Y(t) : t \in [0, 1]\},$$

- We now have an uncountably infinite set of possible  $t$ 's and  $Y(t)$ 's.
- We will only have a (small) finite number of observations  $Y(t_1), \dots, Y(t_n)$  with which to say something useful about this infinite dimensional process.
- The unconstrained covariance matrix for the observed data can have up to  $n(n+1)/2$  unique values\*

• Necessary to make some simplifying assumptions:

- Stationarity  $\rightarrow$  Const  $E(Y)$ , Finite  $Vc(Y)$ , Cov depends on distance
- Simple parameterization of  $\Sigma$

More on these next week, but for now some simple / common examples



## Covariance Functions

More on these next week, but for now some simple / common examples

Exponential Covariance:

$$\Sigma(y_t, y_{t'}) = \sigma^2 \exp(-|t - t'| l)$$

Handwritten annotations: "scale" with an arrow pointing to  $\sigma^2$ , "dist." with an arrow pointing to  $|t - t'|$ , and "range" with an arrow pointing to  $l$ .

## Covariance Functions

More on these next week, but for now some simple / common examples

Exponential Covariance:

$$\Sigma(y_t, y_{t'}) = \sigma^2 \exp(-|t - t'| l)$$

Squared Exponential Covariance:

$$\Sigma(y_t, y_{t'}) = \sigma^2 \exp(-(|t - t'| l)^2)$$

## Covariance Functions

More on these next week, but for now some simple / common examples

Exponential Covariance:

$$\Sigma(y_t, y_{t'}) = \sigma^2 \exp(-|t - t'| / l)$$

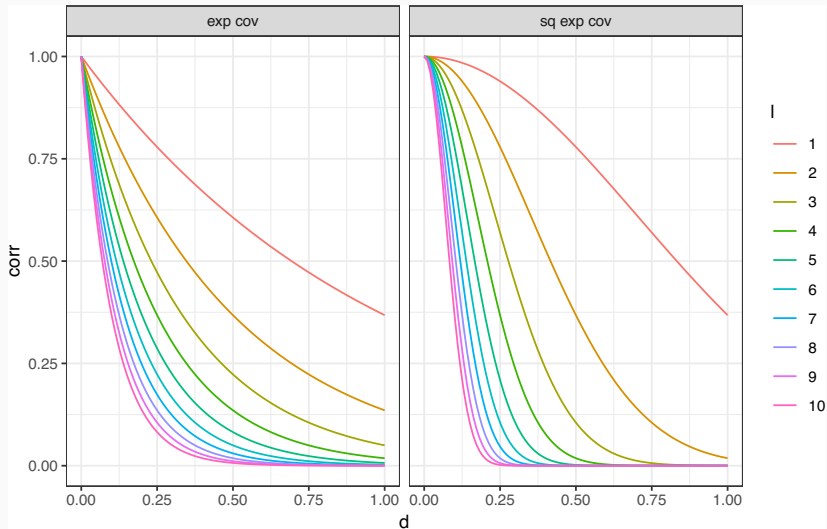
Squared Exponential Covariance:

$$\Sigma(y_t, y_{t'}) = \sigma^2 \exp(-(|t - t'| / l)^2)$$

Powered Exponential Covariance ( $p \in (0, 2]$ ):

$$\Sigma(y_t, y_{t'}) = \sigma^2 \exp(-(|t - t'| / l)^p)$$

# Covariance Function - Correlation Decay

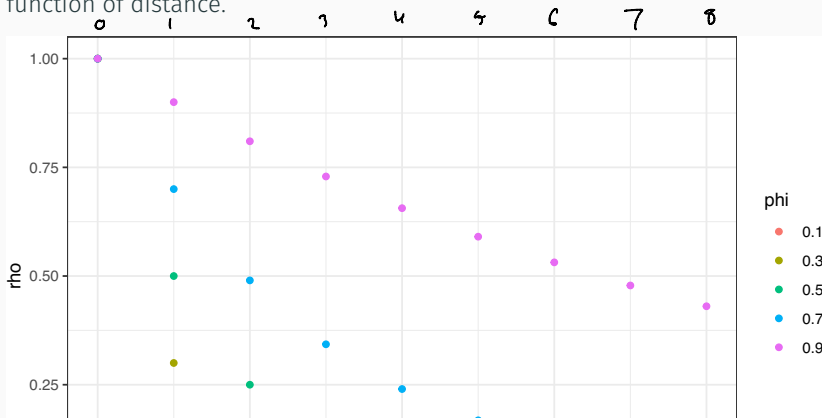


## Correlation Decay - AR(1)

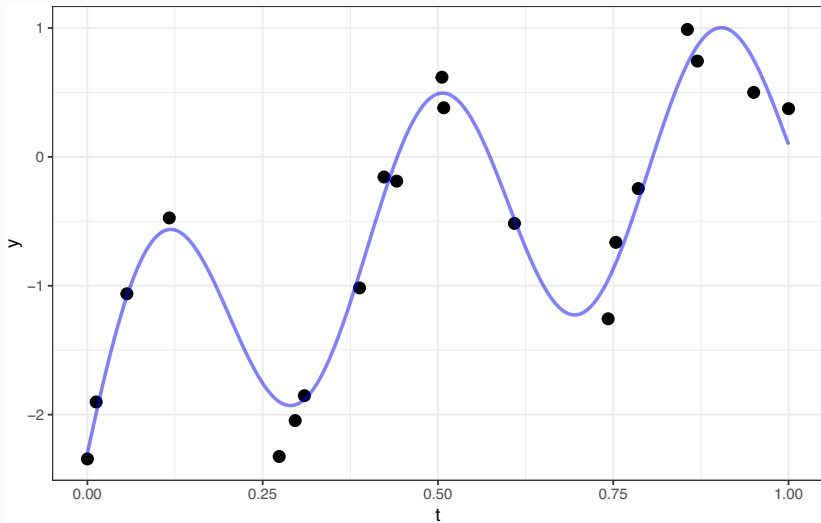
Recall that for a stationary AR(1) process:

$$\gamma(h) = \sigma_w^2 \phi^{|h|} \text{ and } \rho(h) = \phi^{|h|}$$

therefore we can draw a somewhat similar picture about the decay of  $\rho$  as a function of distance.



# Example



## Prediction

Our example has 15 observations which we would like to use as the basis for predicting  $\hat{Y}(t)$  at other values of  $t$  (say a sequence of values from 0 to 1).

## Prediction

Our example has 15 observations which we would like to use as the basis for predicting  $Y(t)$  at other values of  $t$  (say a sequence of values from 0 to 1).

For now lets use a square exponential covariance with  $\sigma^2 = \frac{16}{10}$  and  $l = \frac{15}{5}$



## Prediction

Our example has 15 observations which we would like to use as the basis for predicting  $Y(t)$  at other values of  $t$  (say a sequence of values from 0 to 1).

For now lets use a square exponential covariance with  $\sigma^2 = 10$  and  $l = 5$

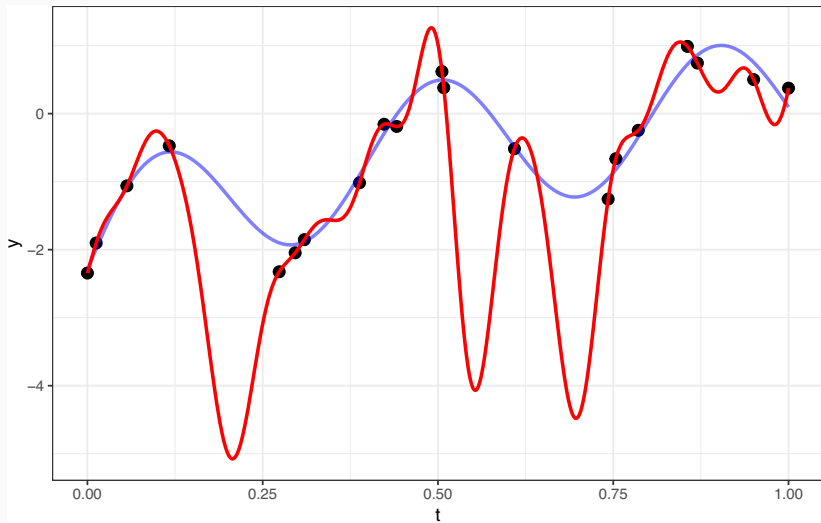
We therefore want to sample from  $\mathbf{Y}_{pred} | \mathbf{Y}_{obs}$ .

$$\mathbf{Y}_{pred} | \mathbf{Y}_{obs} = \mathbf{y} \sim \mathcal{N}(\Sigma_{po} \Sigma_{obs}^{-1} \mathbf{y}, \Sigma_{pred} - \Sigma_{po} \Sigma_{obs}^{-1} \Sigma_{op})$$

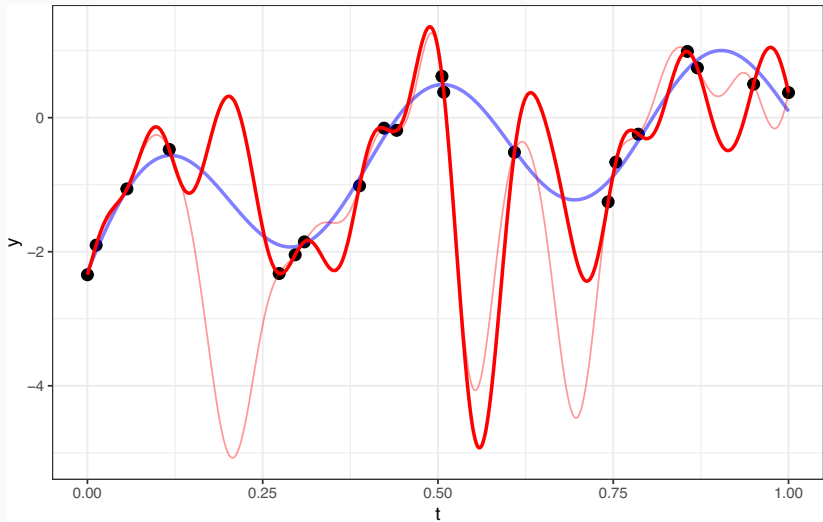
$n_p \times n$        $n \times n$        $n \times n_p$

$$y_i \sim \mathcal{N}(0, \Sigma)$$
$$\{\Sigma\}_{ij} = 10 \exp\left(-\left(\frac{|t_i - t_j|}{5}\right)^2\right)$$

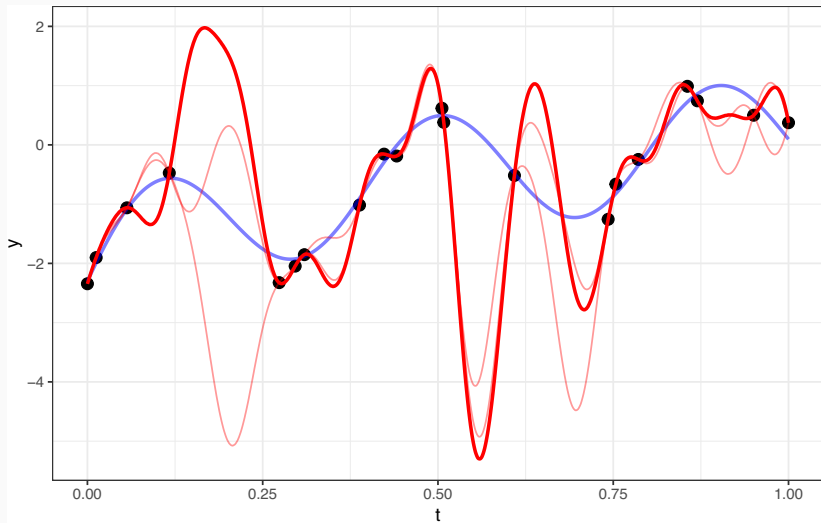
# Draw 1



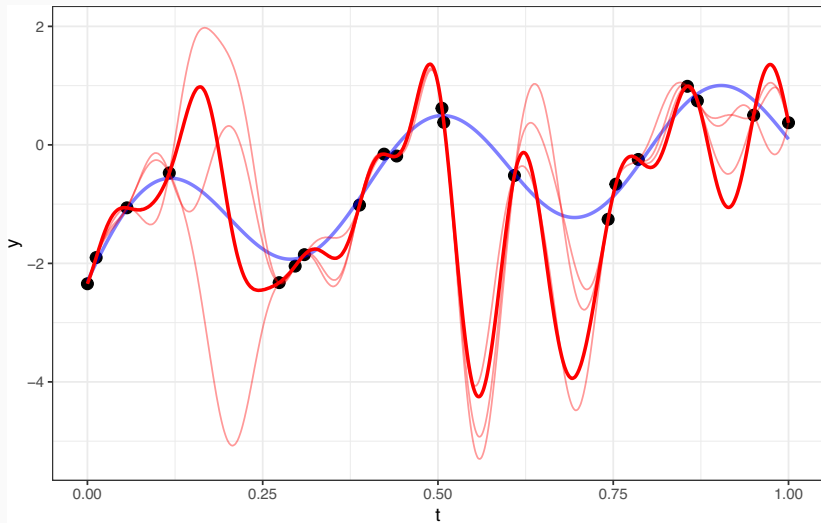
# Draw 2



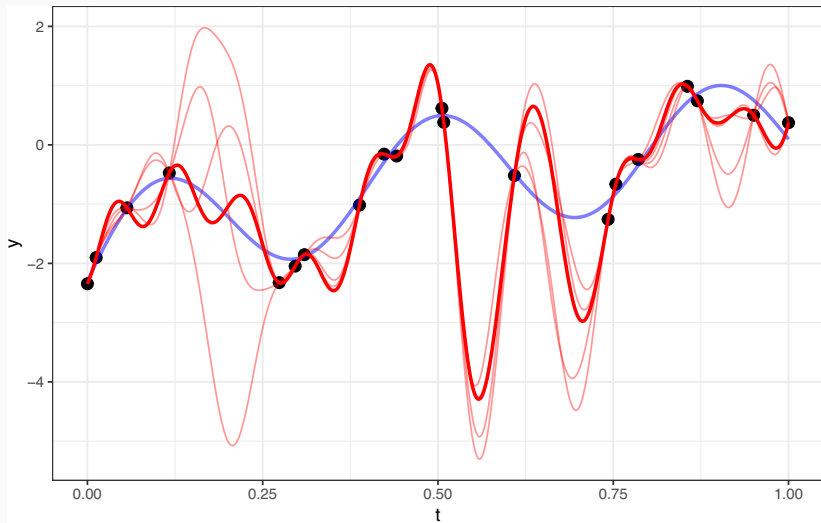
# Draw 3



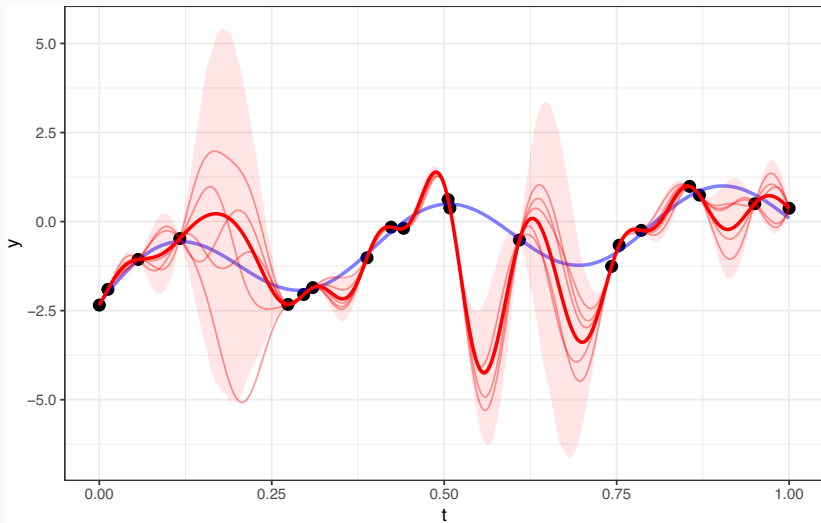
# Draw 4



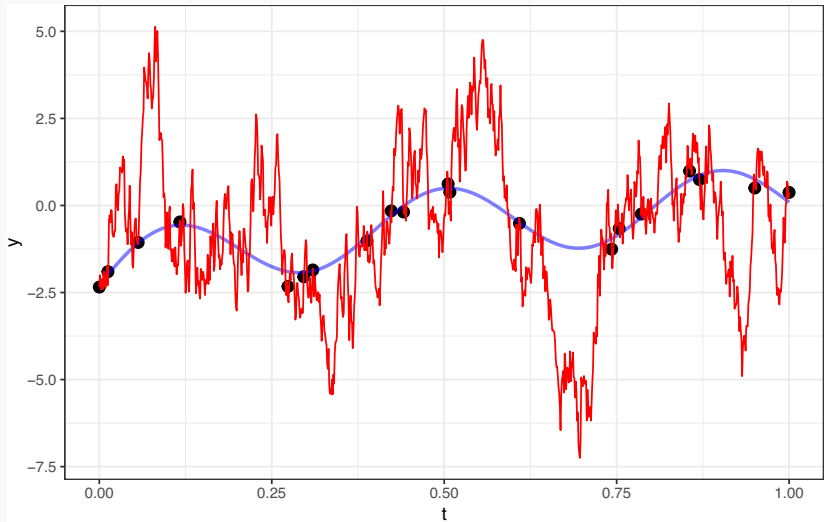
# Draw 5



Many draws later

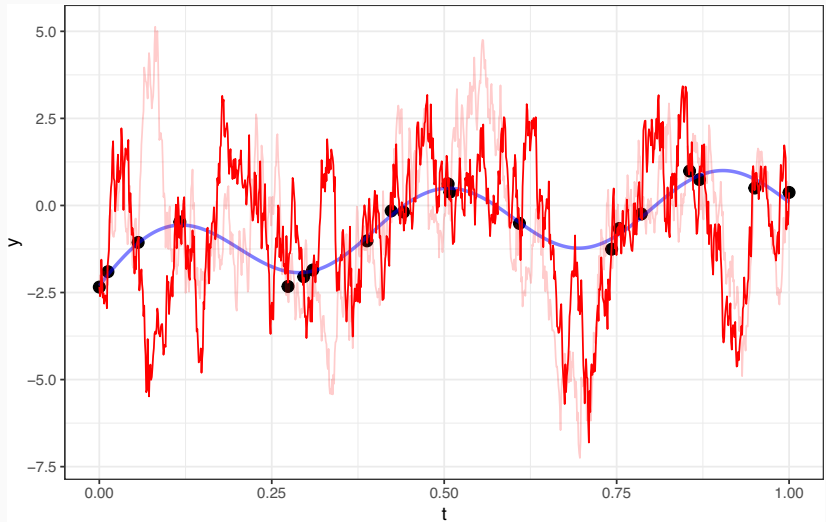


# Exponential Covariance

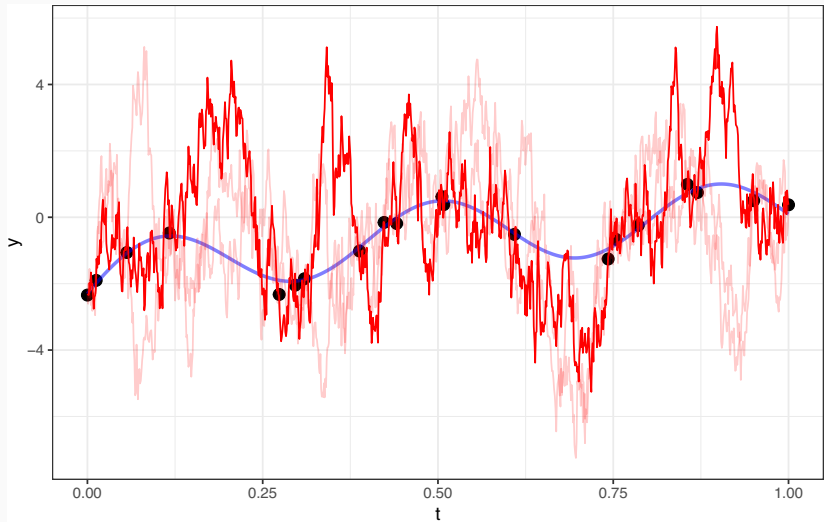




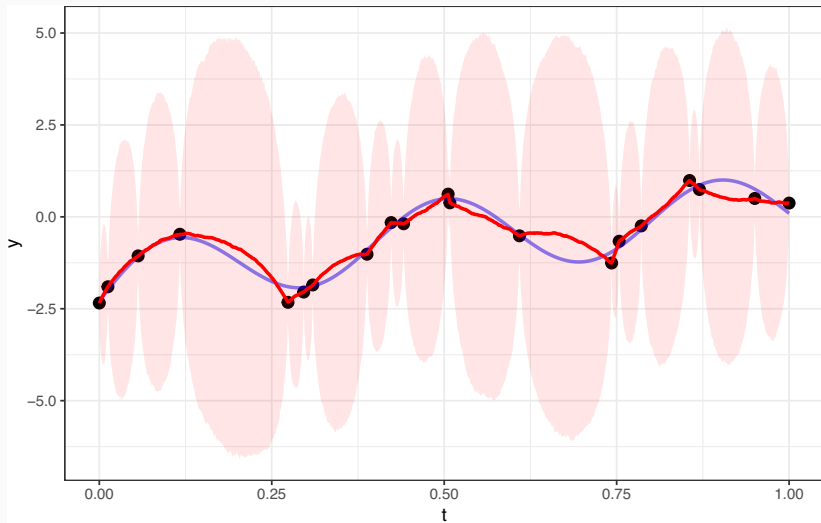
## Exponential Covariance - Draw 2



# Exponential Covariance - Draw 3

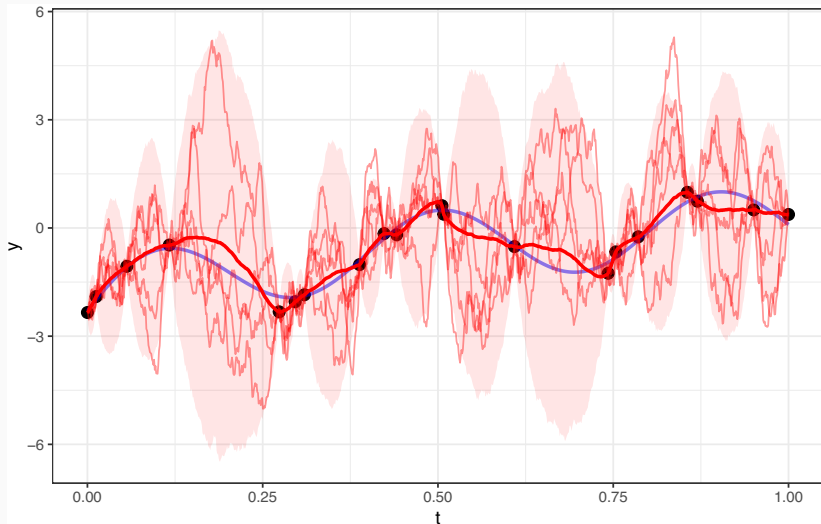


# Exponential Covariance - Posterior

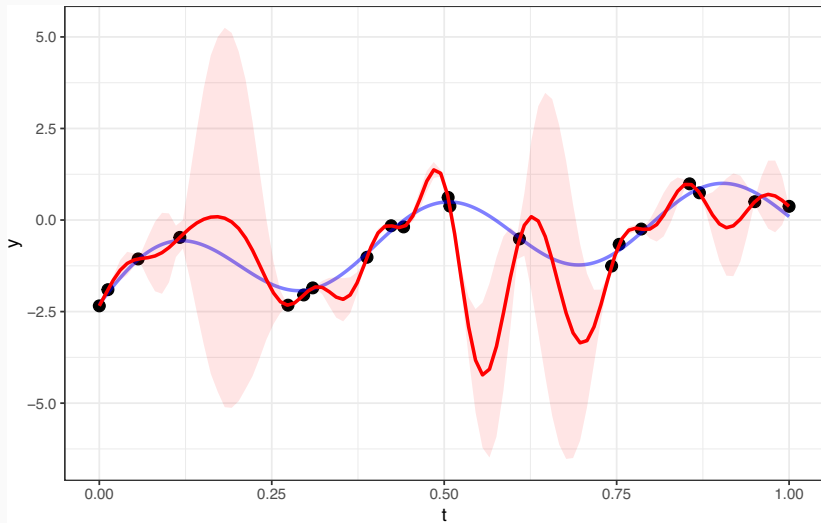


# Powered Exponential Covariance ( $p = 1.5$ )

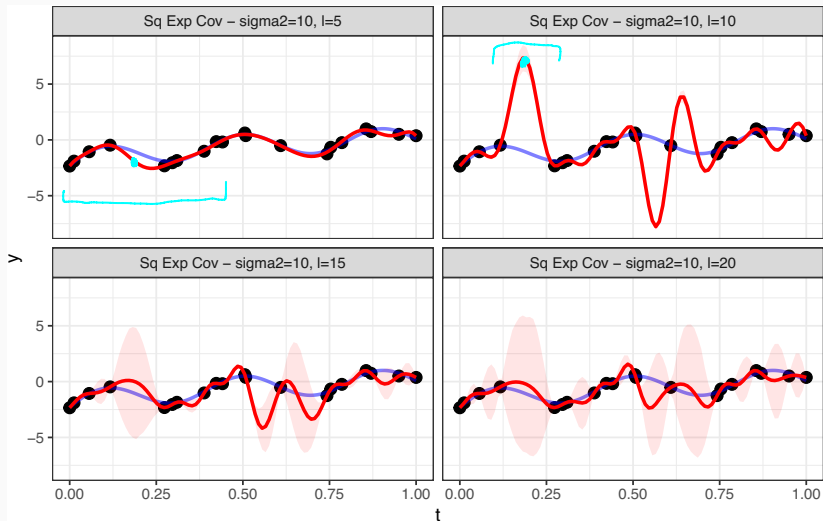
↳ smoothness



## Back to the square exponential



# Changing the range ( $l$ )



## Effective Range

For the square exponential covariance

$$\text{Cov}(d) = \sigma^2 \exp(-l \cdot d)^2$$

$$\text{Corr}(d) = \exp(-l \cdot d)^2$$

we would like to know, for a given value of  $l$ , beyond what distance apart must observations be to have a correlation less than 0.05?

$$\text{Corr}(d) = \exp(-l \cdot d)^2 < 0.05$$

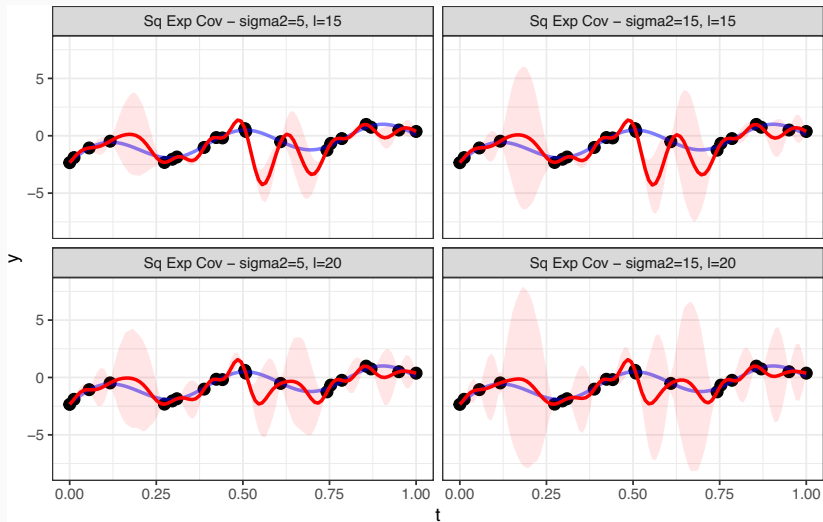
$$-(l \cdot d)^2 < \ln(0.05) = -3$$

$$d < \frac{\sqrt{3}}{l}$$

EXP Cov  
 $P(d) = \exp(-l \cdot d) < 0.05$

$$d < \frac{3}{l}$$

# Changing the scale ( $\sigma^2$ )





## Fitting

```
gp_sq_exp_model = "model{
  y ~ dnorm(mu, inverse(Sigma))

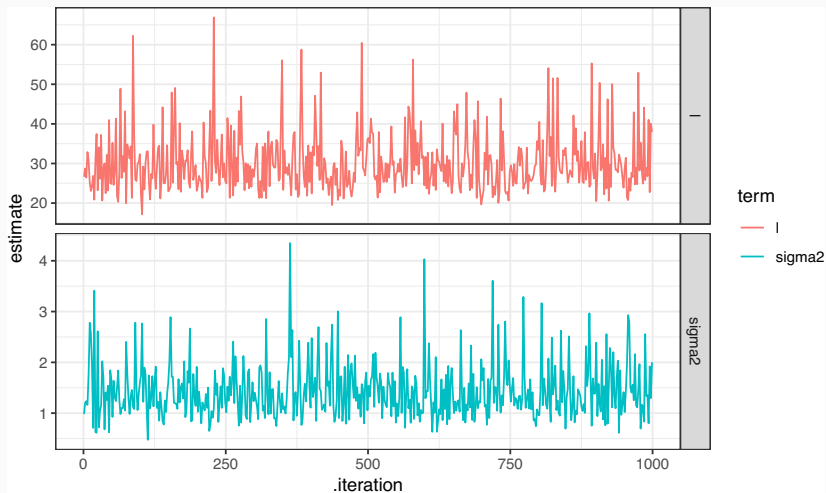
  for (i in 1:N) {
    mu[i] <- 0
  }

  for (i in 1:(N-1)) {
    for (j in (i+1):N) {
      Sigma[i,j] <- sigma2 * exp(- pow(l*d[i,j],2))
      Sigma[j,i] <- Sigma[i,j]
    }
  }

  for (k in 1:N) {
    Sigma[k,k] <- sigma2 + 0.00001
  }

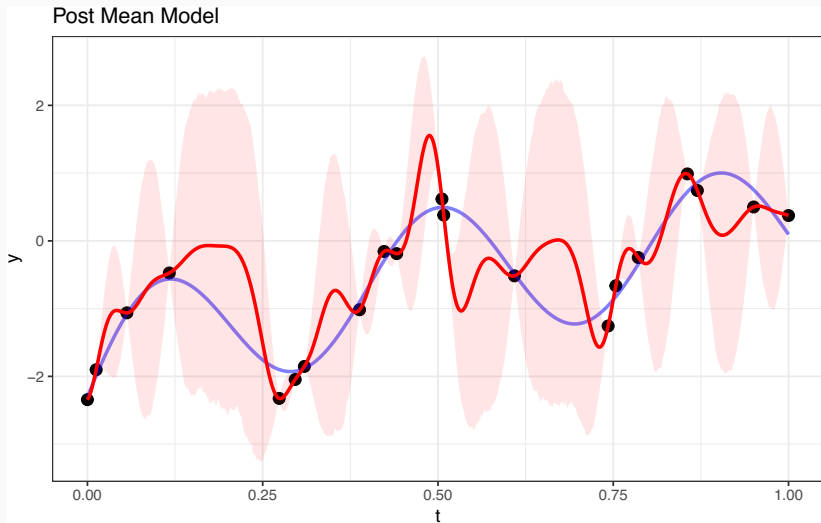
  sigma2 ~ dlnorm(0, 1.5)
  l ~ dt(0, 2.5, 1) T(0,) # Half-cauchy(0,2.5)
}"
```

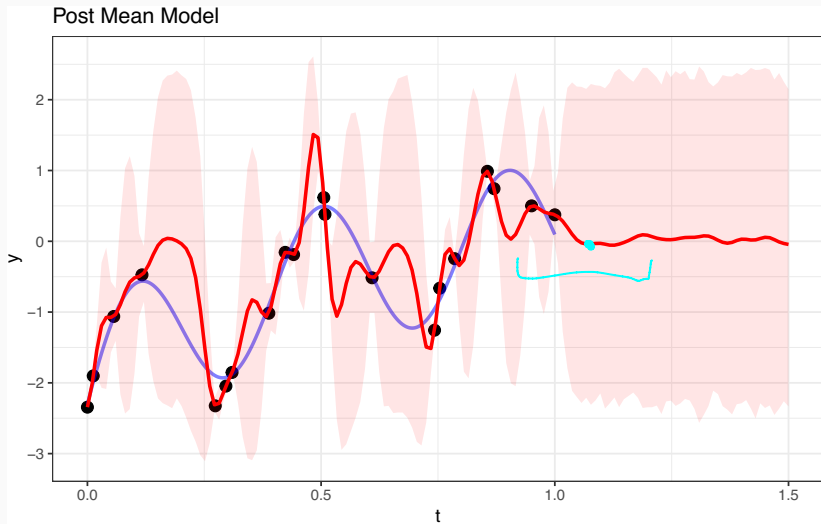
## Trace plots



param	post_mean	post_med	post_lower	post_upper
l	30.20	28.70	20.63	51.51
sigma2	1.44	1.33	0.72	2.78

# Fitted models





## Improving the model

```
gp_sq_exp_model2 = "model{
  y ~ dnorm(mu, inverse(Sigma))

  for (i in 1:N) {
    mu[i] <- 0
  }

  for (i in 1:(N-1)) {
    for (j in (i+1):N) {
      Sigma[i,j] <- sigma2 * exp(- pow(l*d[i,j],2))
      Sigma[j,i] <- Sigma[i,j]
    }
  }

  for (k in 1:N) {
    Sigma[k,k] <- sigma2 + nugget
  }

  sigma2 ~ dlnorm(0, 1.5)
  l ~ dt(0, 2.5, 1) T(0,) # Half-cauchy(0,2.5)

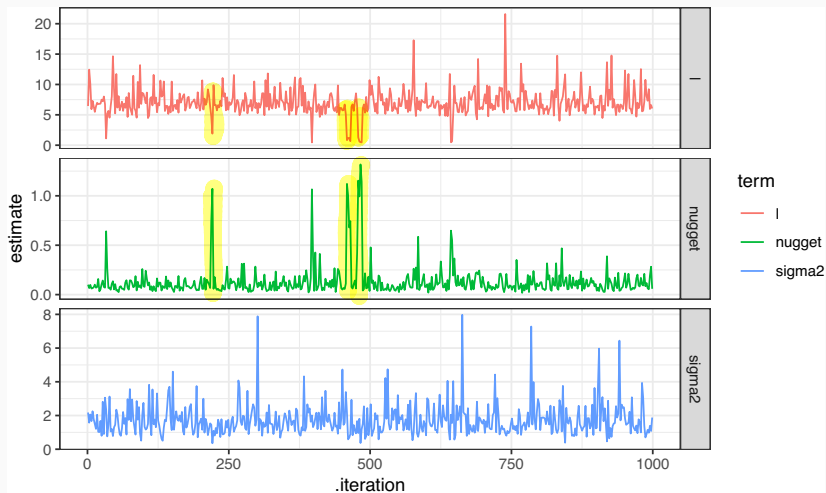
  nugget ~ dlnorm(0, 1)
}"
```

$$Y(t) = v(t) + \epsilon(t)$$

$$v(t) \sim \text{mvn}(0, \Sigma)$$

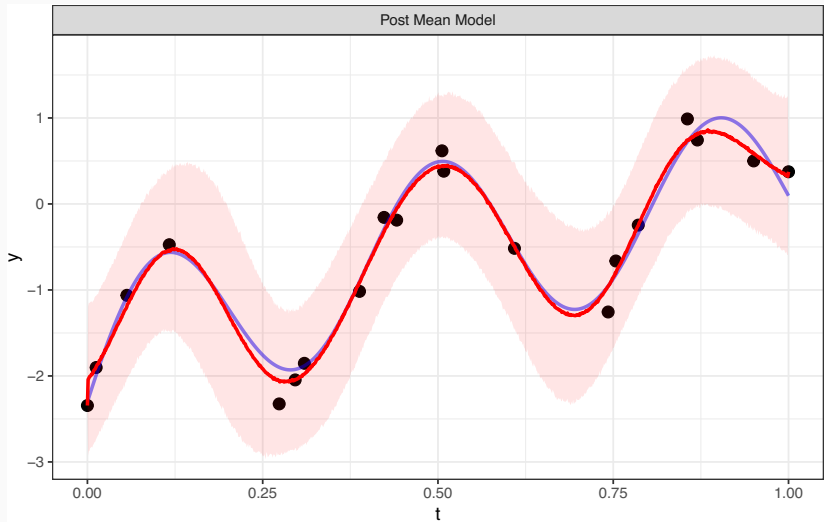
$$\epsilon(t) \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$$

# Trace plots



param	post_mean	post_med	post_lower	post_upper
l	7.01	6.75	2.17	11.79
nugget	0.13	0.09	0.03	0.57
sigma2	1.73	1.53	0.64	4.04

# Fitted models



# Forecasting

