

Lecture 10

Forecasting and Model Fitting

Colin Rundel

02/20/2017

Forecasting

- Forecasts for stationary models necessarily revert to mean
 - Remember, $E(y_t) \neq \delta$ but rather $\delta / (1 - \sum_{i=1}^p \phi_i)$.
 - Differenced models revert to trend (usually a line)
 - Why? AR gradually damp out, MA terms disappear
- Like any other model, accuracy decreases as we extrapolate / prediction interval increases

One step ahead forecasting

Take a fitted ARMA(1,1) process where we know both δ , ϕ , and θ then

$$\hat{y}_n = \delta + \phi y_{n-1} + \theta w_{n-1} + w_n$$

$$\begin{aligned}\hat{y}_{n+1} &= \delta + \phi y_n + \theta w_n + w_{n+1} \\ &\approx \delta + \phi y_n + \theta (y_n - \hat{y}_n) + 0\end{aligned}$$

$$\begin{aligned}\hat{y}_{n+2} &= \delta + \phi y_{n+1} + \theta w_{n+1} + w_{n+2} \\ &\approx \delta + \phi \hat{y}_{n+1} + \theta 0 + 0\end{aligned}$$

Model Fitting

For an $ARIMA(p, d, q)$ model

- Requires that the data be stationary after differencing
- Handling d is straight forward, just difference the original data d times (leaving $n - d$ observations)

$$y'_t = \Delta^d y_t$$

- After differencing fit an $ARMA(p, q)$ model to y'_t .
- To keep things simple we'll assume $w_t \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_w^2)$

If both of these conditions are met, then the time series y_t will also be normal.

In general, the vector $\mathbf{y} = (y_1, y_2, \dots, y_t)'$ will have a multivariate normal distribution with mean $\boldsymbol{\mu}$ and covariance $\boldsymbol{\Sigma}$ where

$$\Sigma_{ij} = \text{Cov}(y_t, y_{t+i-j}) = \gamma_{i-j}.$$

The joint density of \mathbf{y} is given by

$$f_{\mathbf{y}}(\mathbf{y}) = \frac{1}{(2\pi)^{t/2} \det(\boldsymbol{\Sigma})^{1/2}} \times \exp\left(-\frac{1}{2}(\mathbf{y} - \boldsymbol{\mu})' \boldsymbol{\Sigma}^{-1} (\mathbf{y} - \boldsymbol{\mu})\right)$$

$$y_t = \delta + \phi y_{t-1} + w_t$$

Need to estimate three parameters: δ , ϕ , and σ_w^2 , we know

$$E(y_t) = \frac{\delta}{1 - \phi}$$

$$\text{Var}(y_t) = \frac{\sigma_w^2}{1 - \phi^2}$$

$$\text{Cov}(y_t, y_{t+h}) = \frac{\sigma_w^2}{1 - \phi^2} \phi^{|h|}$$

Using these properties it is possible to write down the MVN distribution of \mathbf{y} but not that easy to write down a closed form density which we can then use to find the MLE.

Conditional Density

We can rewrite the density as follows,

$$\begin{aligned}f_{\mathbf{y}} &= f_{y_t, y_{t-1}, \dots, y_2, y_1} \\&= f_{y_t | y_{t-1}, \dots, y_2, y_1} f_{y_{t-1} | y_{t-2}, \dots, y_2, y_1} \cdots f_{y_2 | y_1} f_{y_1} \\&= f_{y_t | y_{t-1}} f_{y_{t-1} | y_{t-2}} \cdots f_{y_2 | y_1} f_{y_1}\end{aligned}$$

where,

$$\begin{aligned}y_1 &\sim \mathcal{N}\left(\delta, \frac{\sigma_w^2}{1 - \phi^2}\right) \\y_t | y_{t-1} &\sim \mathcal{N}(\delta + \phi y_{t-1}, \sigma_w^2) \\f_{y_t | y_{t-1}}(y_t) &= \frac{1}{\sqrt{2\pi \sigma_w^2}} \exp\left(-\frac{1}{2} \frac{(y_t - \delta + \phi y_{t-1})^2}{\sigma_w^2}\right)\end{aligned}$$

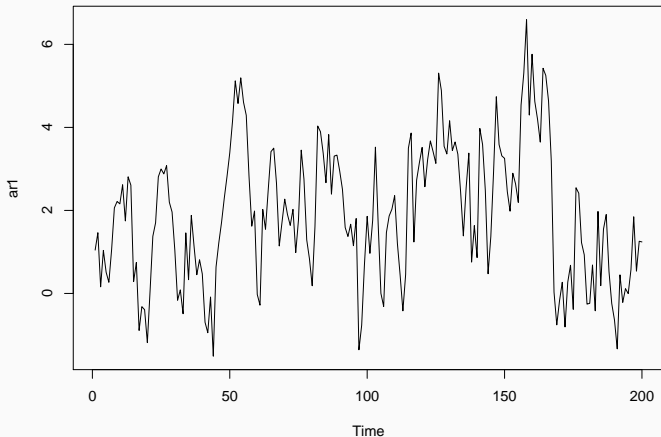
Log likelihood of AR(1)

$$\log f_{y_t|y_{t-1}}(y_t) = -\frac{1}{2} \left(\log 2\pi + \log \sigma_w^2 + \frac{1}{\sigma_w^2} (y_t - \delta + \phi y_{t-1})^2 \right)$$

$$\begin{aligned} \ell(\delta, \phi, \sigma_w^2) &= \log f_y = \log f_{y_1} + \sum_{i=2}^t \log f_{y_i|y_{i-1}} \\ &= -\frac{1}{2} \left(\log 2\pi + \log \sigma_w^2 - \log(1 - \phi^2) + \frac{(1 - \phi^2)}{\sigma_w^2} (y_1 - \delta)^2 \right) \\ &\quad - \frac{1}{2} \left((n-1) \log 2\pi + (n-1) \log \sigma_w^2 + \frac{1}{\sigma_w^2} \sum_{i=2}^n (y_i - \delta + \phi y_{i-1})^2 \right) \\ &= -\frac{1}{2} \left(n \log 2\pi + n \log \sigma_w^2 - \log(1 - \phi^2) + \frac{1}{\sigma_w^2} \left((1 - \phi^2)(y_1 - \delta)^2 + \sum_{i=2}^n (y_i - \delta + \phi y_{i-1})^2 \right) \right) \end{aligned}$$

AR(1) Example

with $\phi = -0.75$, $\delta = 0.5$, and $\sigma_w^2 = 1$,



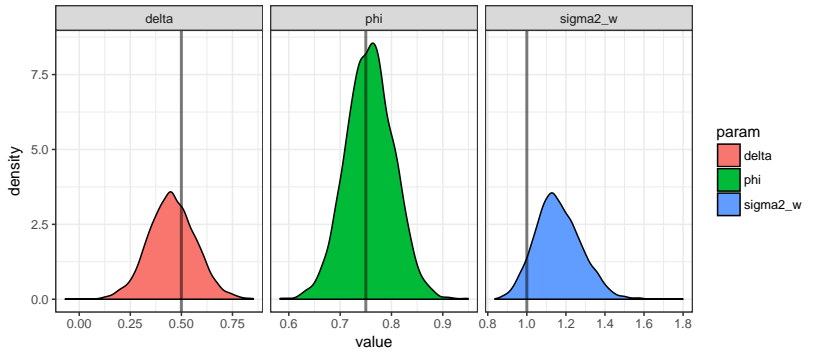
```
Arima(ar1, order = c(1,0,0)) %>% summary()
## Series: ar1
## ARIMA(1,0,0) with non-zero mean
##
## Coefficients:
##          ar1      mean
##      0.7593  1.8734
## s.e.  0.0454  0.3086
##
## sigma^2 estimated as 1.149:  log likelihood=-297.14
## AIC=600.28  AICc=600.4  BIC=610.17
##
## Training set error measures:
##              ME      RMSE      MAE      MPE      MAPE
## Training set 0.004616374  1.066741  0.8410635 -327.6919  664.3204
##              MASE      ACF1
## Training set 0.9186983 -0.00776572
```

```
lm(ar1~lag(ar1)) %>% summary()
##
## Call:
## lm(formula = ar1 ~ lag(ar1))
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -3.1863 -0.7596  0.0779  0.6099  2.8638
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)   0.4530     0.1161   3.904 0.00013 ***
## lag(ar1)      0.7621     0.0461  16.530 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.074 on 197 degrees of freedom
## (1 observation deleted due to missingness)
## Multiple R-squared:  0.5811, Adjusted R-squared:  0.5789
## F-statistic: 273.2 on 1 and 197 DF,  p-value: < 2.2e-16
```

Bayesian AR(1) Model

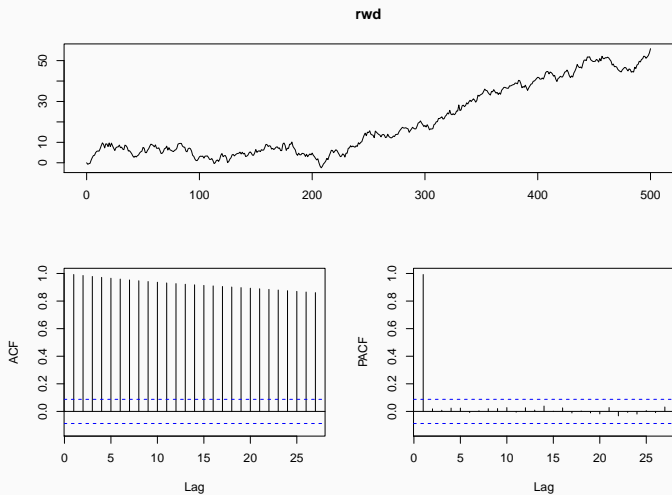
```
## model{
## # likelihood
## y[1] ~ dnorm(delta/(1-phi), (sigma2_w/(1-phi^2))^-1)
## y_hat[1] ~ dnorm(delta/(1-phi), (sigma2_w/(1-phi^2))^-1)
##
## for (t in 2:length(y)) {
##   y[t] ~ dnorm(delta + phi*y[t-1], 1/sigma2_w)
##   y_hat[t] ~ dnorm(delta + phi*y[t-1], 1/sigma2_w)
## }
##
## mu <- delta/(1-phi)
##
## # priors
## delta ~ dnorm(0,1/1000)
## phi ~ dnorm(0,1)
## tau ~ dgamma(0.001,0.001)
## sigma2_w <- 1/tau
## }
```


Posteriors



Random Walk with Drift

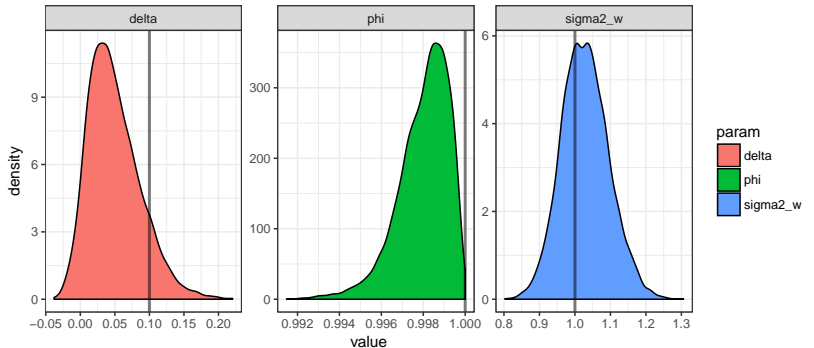
with $\phi = 1$, $\delta = 0.1$, and $\sigma_w^2 = 1$ using the same models



```
lm(rwd~lag(rwd)) %>% summary()
##
## Call:
## lm(formula = rwd ~ lag(rwd))
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -2.83634 -0.71725  0.00629  0.69476  3.13117
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  0.083981   0.068588   1.224   0.221
## lag(rwd)     1.001406   0.002632 380.494 <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.004 on 498 degrees of freedom
## (1 observation deleted due to missingness)
## Multiple R-squared:  0.9966, Adjusted R-squared:  0.9966
## F-statistic: 1.448e+05 on 1 and 498 DF, p-value: < 2.2e-16
```

```
Arima(rwd, order = c(1,0,0), include.constant = TRUE) %>% summary()
## Series: rwd
## ARIMA(1,0,0) with non-zero mean
##
## Coefficients:
##          ar1      mean
##    0.9992  26.4894
## s.e.  0.0010  23.5057
##
## sigma^2 estimated as 1.021:  log likelihood=-718.33
## AIC=1442.66  AICc=1442.7  BIC=1455.31
##
## Training set error measures:
##              ME      RMSE      MAE  MPE  MAPE      MASE
## Training set 0.1041264 1.008427 0.8142404 -Inf  Inf  0.9996364
##              ACF1
## Training set 0.01365841
```

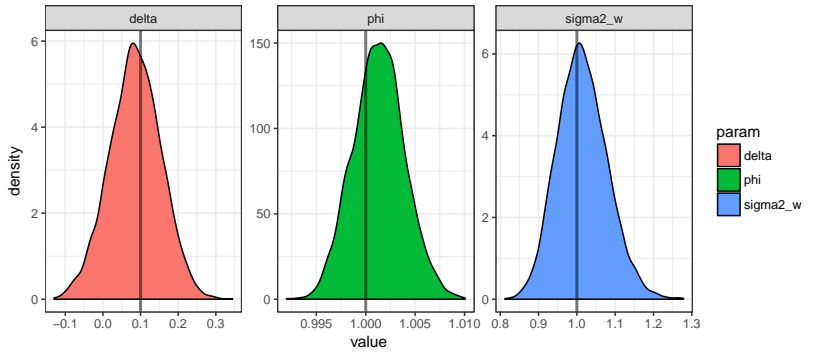
Bayesian Posteriors



Non-stationary Bayesian Model

```
## model{
## # likelihood
## #y[1] ~ dnorm(delta/(1-phi), (sigma2_w/(1-phi^2))^(-1))
## #y_hat[1] ~ dnorm(delta/(1-phi), (sigma2_w/(1-phi^2))^(-1))
##
## for (t in 2:length(y)) {
##   y[t] ~ dnorm(delta + phi*y[t-1], 1/sigma2_w)
##   y_hat[t] ~ dnorm(delta + phi*y[t-1], 1/sigma2_w)
## }
##
## mu <- delta/(1-phi)
##
## # priors
## delta ~ dnorm(0,1/1000)
## phi ~ dnorm(0,1)
## tau ~ dgamma(0.001,0.001)
## sigma2_w <- 1/tau
## }
```

NS Bayesian Posteriors



Probability of being stationary

```
rwd_params$phi %>% abs() %>% {. < 1} %>% {sum(.) / length(.)}  
## [1] 0.3046
```



```
Arima(rwd, order = c(0,1,0), include.constant = TRUE) %>% summary()
## Series: rwd
## ARIMA(0,1,0) with drift
##
## Coefficients:
##      drift
##      0.1117
## s.e.  0.0448
##
## sigma^2 estimated as 1.007:  log likelihood=-710.63
## AIC=1425.26  AICc=1425.29  BIC=1433.69
##
## Training set error measures:
##
##              ME      RMSE      MAE  MPE  MAPE      MASE
## Training set -2.228961e-07  1.001325  0.8082318  -Inf  Inf  0.9922597
##              ACF1
## Training set 0.01027574
```

We can rewrite the density as follows,

$$\begin{aligned} f(\mathbf{y}) &= f(y_1, y_2, \dots, y_{t-1}, y_t) \\ &= f(y_1, y_2, \dots, y_p) f(y_{p+1}|y_1, \dots, y_p) \cdots f(y_n|y_{n-p}, \dots, y_{n-1}) \end{aligned}$$

We can rewrite the density as follows,

$$\begin{aligned} f(\mathbf{y}) &= f(y_1, y_2, \dots, y_{t-1}, y_t) \\ &= f(y_1, y_2, \dots, y_p) f(y_{p+1}|y_1, \dots, y_p) \cdots f(y_n|y_{n-p}, \dots, y_{n-1}) \end{aligned}$$

Regressing y_t on y_{t-p}, \dots, y_{t-1} gets us an approximate solution, but it ignores the $f(y_1, y_2, \dots, y_p)$ part of the likelihood.

How much does this matter (vs. using the full likelihood)?

- If p is not much smaller than n then probably a lot
- If $p \ll n$ then probably not much

ARMA

$$y_t = \delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \theta_1 w_{t-1} + \theta_2 w_{t-2} + w_t$$

Need to estimate six parameters: δ , ϕ_1 , ϕ_2 , θ_1 , θ_2 and σ_w^2 .

$$y_t = \delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \theta_1 w_{t-1} + \theta_2 w_{t-2} + w_t$$

Need to estimate six parameters: δ , ϕ_1 , ϕ_2 , θ_1 , θ_2 and σ_w^2 .

We could figure out $E(y_t)$, $Var(y_t)$, and $Cov(y_t, y_{t+h})$, but the last two are going to likely be pretty nasty and the full MVN likelihood is similarly going to be unpleasant to work with.

$$y_t = \delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \theta_1 w_{t-1} + \theta_2 w_{t-2} + w_t$$

Need to estimate six parameters: δ , ϕ_1 , ϕ_2 , θ_1 , θ_2 and σ_w^2 .

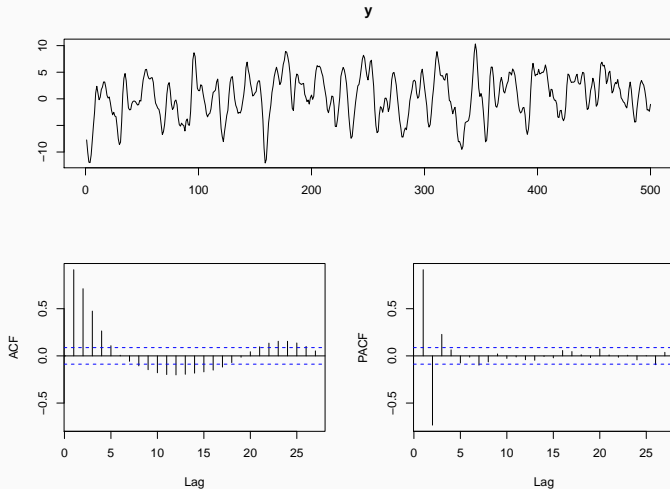
We could figure out $E(y_t)$, $Var(y_t)$, and $Cov(y_t, y_{t+h})$, but the last two are going to likely be pretty nasty and the full MVN likelihood is similarly going to be unpleasant to work with.

Like the AR(1) and AR(p) processes we want to use conditioning to simplify things.

$$y_t | \delta, y_{t-1}, y_{t-2}, w_{t-1}, w_{t-2} \sim \mathcal{N}(\delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \theta_1 w_{t-1} + \theta_2 w_{t-2}, \sigma_w^2)$$

ARMA(2,2) Example

with $\phi = (1.3, -0.5)$, $\theta = (0.5, 0.2)$, $\delta = 0$, and $\sigma_w^2 = 1$ using the same models




```
Arima(y, order = c(2,0,2), include.mean = FALSE) %>% summary()
## Series: y
## ARIMA(2,0,2) with zero mean
##
## Coefficients:
##          ar1          ar2          ma1          ma2
##          1.3154      -0.4991      0.5200      0.2481
## s.e.      0.0725       0.0677      0.0793      0.0633
##
## sigma^2 estimated as 1.067:  log likelihood=-725.52
## AIC=1461.04   AICc=1461.16   BIC=1482.11
##
## Training set error measures:
##              ME      RMSE      MAE      MPE      MAPE
## Training set 0.05502909 1.028655 0.8260218 13.65446 86.84326
##              MASE      ACF1
## Training set 0.6224348 -0.004832567
```

```

(lm_ar = lm(y ~ lag(y,1) + lag(y,2))) %>% summary()
##
## Call:
## lm(formula = y ~ lag(y, 1) + lag(y, 2))
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -3.3908 -0.7164 -0.0235  0.7502  3.0950
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  0.08661    0.04867   1.779  0.0758 .
## lag(y, 1)    1.59893    0.02947  54.262 <2e-16 ***
## lag(y, 2)   -0.74823    0.02936 -25.482 <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.078 on 495 degrees of freedom
## (2 observations deleted due to missingness)
## Multiple R-squared:  0.9307, Adjusted R-squared:  0.9304
## F-statistic: 3324 on 2 and 495 DF, p-value: < 2.2e-16

```

1. Estimate a high order AR (remember $AR \Leftrightarrow MA$ when stationary + invertible)
2. Use AR to estimate values for unobserved w_t
3. Regress y_t onto $y_{t-1}, \dots, y_{t-p}, \hat{w}_{t-1}, \dots, \hat{w}_{t-q}$
4. Update $\hat{w}_{t-1}, \dots, \hat{w}_{t-q}$ based on current model, refit and then repeat until convergence

Hannan-Rissanen - Step 1 & 2

```
ar = ar.mle(y, order.max = 20)
ar
##
## Call:
## ar.mle(x = y, order.max = 20)
##
## Coefficients:
##      1      2      3      4      5      6      7
##  1.8272 -1.1903  0.1643  0.2110 -0.2331  0.2143 -0.1158
##
## Order selected 7  sigma^2 estimated as  1.041
ar$resid
## Time Series:
## Start = 1
## End = 500
## Frequency = 1
## [1] NA NA NA NA NA
## [6] NA NA 0.013771505 1.815385143 -1.523601485
## [11] -1.482175624 0.257910962 0.779526070 0.500584221 -0.874932004
## [16] 1.000773447 -0.403367540 -0.432516832 -0.213762215 0.419791693
## [21] 0.256815097 -1.532807297 -0.385121768 -0.074529360 0.545797695
## [26] -1.622523443 0.190508558 -2.276038961 -1.218302454 -0.165499325
## [31] -0.422165854 2.284211482 1.090020206 -0.831161663 0.147961063
## [36] -0.913676024 -1.060367233 -0.313198281 0.401868246 -0.752567843
## [41] 0.615242705 -0.630185112 -0.017926780 0.127457456 -0.382266477
## [46] -0.212700408 0.045666952 0.373128585 -0.946750691 2.386716523
## [51] -0.097543980 0.081058896 1.264579915 -0.312389635 -0.226815185
## [56] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [61] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [66] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [71] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [76] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [81] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [86] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [91] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [96] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [101] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [106] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [111] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [116] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [121] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [126] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [131] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [136] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [141] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [146] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [151] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [156] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [161] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [166] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [171] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [176] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [181] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [186] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [191] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [196] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [201] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [206] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [211] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [216] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [221] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [226] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [231] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [236] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [241] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [246] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [251] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [256] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [261] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [266] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [271] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [276] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [281] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [286] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [291] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [296] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [301] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [306] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [311] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [316] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [321] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [326] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [331] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [336] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [341] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [346] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [351] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [356] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [361] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [366] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [371] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [376] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [381] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [386] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [391] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [396] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [401] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [406] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [411] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [416] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [421] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [426] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [431] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [436] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [441] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [446] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [451] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [456] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [461] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [466] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [471] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [476] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [481] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [486] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [491] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [496] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
## [501] 0.000000000 0.000000000 0.000000000 0.000000000 0.000000000
```

Hannan-Rissanen - Step 3

```
d = data_frame(y = y %>% strip_attrs(), w_hat1 = ar$resid %>% strip_attrs())

(lm1 = lm(y ~ lag(y,1) + lag(y,2) + lag(w_hat1,1) + lag(w_hat1,2), data=d)) %>%
  summary()
##
## Call:
## lm(formula = y ~ lag(y, 1) + lag(y, 2) + lag(w_hat1, 1) + lag(w_hat1,
##      2), data = d)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -3.3756 -0.7172 -0.0223  0.6697  3.1330
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)   0.10594   0.04752   2.229  0.02625 *
## lag(y, 1)     1.33911   0.05421  24.702 < 2e-16 ***
## lag(y, 2)    -0.52481   0.04817 -10.894 < 2e-16 ***
## lag(w_hat1, 1) 0.46734   0.07103   6.579 1.23e-10 ***
## lag(w_hat1, 2) 0.21347   0.07057   3.025  0.00262 **
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.036 on 486 degrees of freedom
## (9 observations deleted due to missingness)
## Multiple R-squared:  0.9326, Adjusted R-squared:  0.9321
## F-statistic: 1681 on 4 and 486 DF, p-value: < 2.2e-16
```

Hannan-Rissanen - Step 4.1

```
d = add_residuals(d,lm1,"w_hat2")

(lm2 = lm(y ~ lag(y,1) + lag(y,2) + lag(w_hat2,1) + lag(w_hat2,2), data=d)) %>%
  summary()
##
## Call:
## lm(formula = y ~ lag(y, 1) + lag(y, 2) + lag(w_hat2, 1) + lag(w_hat2,
##      2), data = d)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -3.3589 -0.7487 -0.0288  0.6471  3.1058
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)   0.12429   0.04735   2.625 0.008948 **
## lag(y, 1)     1.31028   0.05624  23.299 < 2e-16 ***
## lag(y, 2)    -0.50471   0.04923 -10.252 < 2e-16 ***
## lag(w_hat2, 1) 0.50130   0.07125   7.036 6.8e-12 ***
## lag(w_hat2, 2) 0.23462   0.07086   3.311 0.000999 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.027 on 484 degrees of freedom
## (11 observations deleted due to missingness)
## Multiple R-squared:  0.9341, Adjusted R-squared:  0.9335
## F-statistic: 1714 on 4 and 484 DF, p-value: < 2.2e-16
```

Hannan-Rissanen - Step 4.2

```
d = add_residuals(d,lm2,"w_hat3")

(lm3 = lm(y ~ lag(y,1) + lag(y,2) + lag(w_hat3,1) + lag(w_hat3,2), data=d)) %>%
  summary()
##
## Call:
## lm(formula = y ~ lag(y, 1) + lag(y, 2) + lag(w_hat3, 1) + lag(w_hat3,
##      2), data = d)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -3.3717 -0.7489 -0.0311  0.6465  3.0557
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)    0.12529    0.04754   2.636 0.008672 **
## lag(y, 1)      1.31322    0.05588  23.501 < 2e-16 ***
## lag(y, 2)     -0.50769    0.04897 -10.367 < 2e-16 ***
## lag(w_hat3, 1) 0.50220    0.07190   6.985 9.52e-12 ***
## lag(w_hat3, 2) 0.24635    0.07173   3.435 0.000645 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.028 on 482 degrees of freedom
## (13 observations deleted due to missingness)
## Multiple R-squared:  0.9342, Adjusted R-squared:  0.9336
## F-statistic: 1710 on 4 and 482 DF, p-value: < 2.2e-16
```

Hannan-Rissanen - Step 4.3

```
d = add_residuals(d,lm3,"w_hat4")

(lm4 = lm(y ~ lag(y,1) + lag(y,2) + lag(w_hat4,1) + lag(w_hat4,2), data=d)) %>%
  summary()
##
## Call:
## lm(formula = y ~ lag(y, 1) + lag(y, 2) + lag(w_hat4, 1) + lag(w_hat4,
##      2), data = d)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -3.3167 -0.7553 -0.0292  0.6503  3.1417
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)    0.12368    0.04761   2.598  0.00968 **
## lag(y, 1)      1.30982    0.05578  23.481 < 2e-16 ***
## lag(y, 2)     -0.50496    0.04889 -10.328 < 2e-16 ***
## lag(w_hat4, 1) 0.50657    0.07184   7.051 6.21e-12 ***
## lag(w_hat4, 2) 0.25342    0.07172   3.534 0.00045 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.028 on 480 degrees of freedom
## (15 observations deleted due to missingness)
## Multiple R-squared:  0.9344, Adjusted R-squared:  0.9339
## F-statistic: 1710 on 4 and 480 DF, p-value: < 2.2e-16
```


Hannan-Rissanen - Step 4.4

```
d = add_residuals(d,lm4,"w_hat5")

(lm5 = lm(y ~ lag(y,1) + lag(y,2) + lag(w_hat5,1) + lag(w_hat5,2), data=d)) %>%
  summary()
##
## Call:
## lm(formula = y ~ lag(y, 1) + lag(y, 2) + lag(w_hat5, 1) + lag(w_hat5,
##      2), data = d)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -3.3614 -0.7620 -0.0282  0.6656  3.1229
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)    0.12142    0.04778   2.541 0.011353 *
## lag(y, 1)      1.31454    0.05590  23.517 < 2e-16 ***
## lag(y, 2)     -0.50870    0.04900 -10.382 < 2e-16 ***
## lag(w_hat5, 1) 0.50350    0.07219   6.975 1.02e-11 ***
## lag(w_hat5, 2) 0.24604    0.07203   3.416 0.000691 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.03 on 478 degrees of freedom
## (17 observations deleted due to missingness)
## Multiple R-squared:  0.9343, Adjusted R-squared:  0.9338
## F-statistic: 1700 on 4 and 478 DF, p-value: < 2.2e-16
```

```
rmse(lm_ar, data = d)  
## [1] 1.074382
```

```
rmse(lm1, data = d)  
## [1] 1.030996
```

```
rmse(lm2, data = d)  
## [1] 1.021696
```

```
rmse(lm3, data = d)  
## [1] 1.022922
```

```
rmse(lm4, data = d)  
## [1] 1.022807
```

```
rmse(lm5, data = d)  
## [1] 1.024861
```

Bayesian Model

```
## model{
## # Likelihood
## for (t in 1:length(y)) {
##   y[t] ~ dnorm(mu[t], 1/sigma2_e)
## }
##
## mu[1] <- phi[1] * y_0 + phi[2] * y_n1 + w[1] + theta[1]*w_0 - theta[2]*w_n1
## mu[2] <- phi[1] * y[1] + phi[2] * y_0 + w[2] + theta[1]*w[1] - theta[2]*w_0
## for (t in 3:length(y)) {
##   mu[t] <- phi[1] * y[t-1] + phi[2] * y[t-2] + w[t] + theta[1] * w[t-1] + theta[2] * w[t-2]
## }
##
## # Priors
## for(t in 1:length(y)){
##   w[t] ~ dnorm(0,1/sigma2_w)
## }
##
## sigma2_w = 1/tau_w; tau_w ~ dgamma(0.001, 0.001)
## sigma2_e = 1/tau_e; tau_e ~ dgamma(0.001, 0.001)
## for(i in 1:2) {
##   phi[i] ~ dnorm(0,1)
##   theta[i] ~ dnorm(0,1)
## }
##
## # Latent errors and series values
## w_0 ~ dt(0,tau_w,2)
## w_n1 ~ dt(0,tau_w,2)
## y_0 ~ dnorm(0,1/1000)
## y_n1 ~ dnorm(0,1/1000)
## }
```

Bayesian Fit

