Lecture 6

Discrete Time Series

2/06/2018

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Weak Stationary

Strict stationary is unnecessarily strong / restrictive for many applications, so instead we often opt for *weak stationary* which requires the following,

1. The process has finite variance

$$E(y_t^2) < \infty \text{ for all } t$$

2. The mean of the process is constant

$$E(y_t) = \mu \text{ for all } t$$

3. The second moment only depends on the lag

$$Cov(y_t, y_s) = Cov(y_{t+k}, y_{s+k}) \text{ for all } t, s, k$$

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When we say stationary in class we will almost always mean *weakly stationary*.

For a stationary time series, where $E(y_t) = \mu$ and Var$(y_t) = \sigma^2$ for all t, we define the autocorrelation at lag k as

$$\begin{aligned} \rho_k &= Cor(y_t,\, y_{t+k}) \\ &= \frac{Cov(y_t, y_{t+k})}{\sqrt{Var(y_t)Var(y_{t+k})}} \\ &= \frac{E\left((y_t - \mu)(y_{t+k} - \mu)\right)}{\sigma^2} \end{aligned}$$

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this is also sometimes written in terms of the autocovariance function (γ_k) as

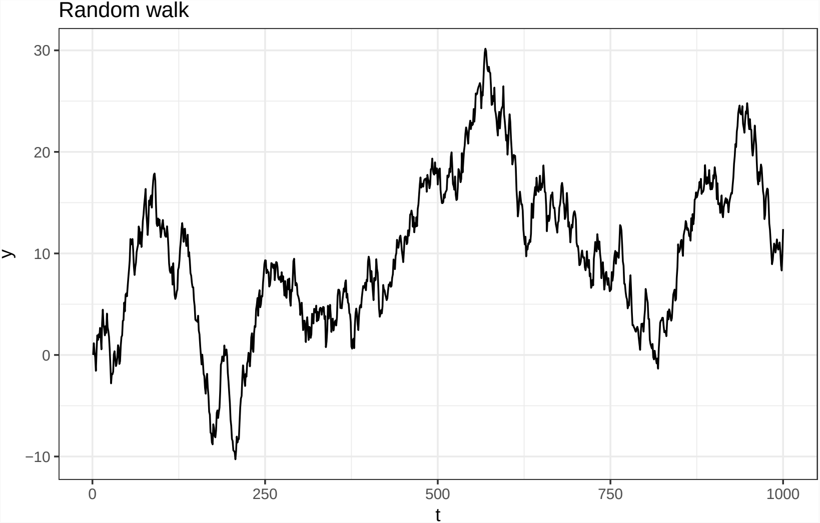
$$\begin{aligned}\gamma_k &= \gamma(t, t+k) = Cov(y_t, y_{t+k}) \\ \rho_k &= \frac{\gamma(t, t+k)}{\sqrt{\gamma(t,t)\gamma(t+k, t+k)}} = \frac{\gamma(k)}{\gamma(0)}\end{aligned}$$

Based on our definition of a (weakly) stationary process, it implies a covariance of the following structure,

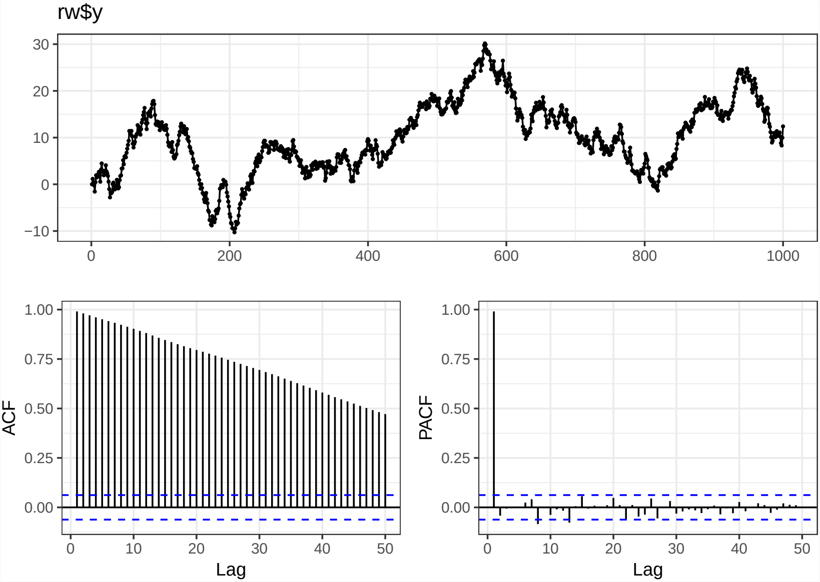
$$\mathbf{\Sigma} = \begin{pmatrix} \gamma(0) & \gamma(1) & \gamma(2) & \gamma(3) & \cdots & \gamma(n) \\ \gamma(1) & \gamma(0) & \gamma(1) & \gamma(2) & \cdots & \gamma(n-1) \\ \gamma(2) & \gamma(1) & \gamma(0) & \gamma(1) & \cdots & \gamma(n-2) \\ \gamma(3) & \gamma(2) & \gamma(1) & \gamma(0) & \cdots & \gamma(n-3) \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \gamma(n) & \gamma(n-1) & \gamma(n-2) & \gamma(n-3) & \cdots & \gamma(0) \end{pmatrix}$$

Example - Random walk

Let $y_t = y_{t-1} + w_t$ with $y_0 = 0$ and $w_t \sim \mathcal{N}(0, 1)$.



ACF + PACF



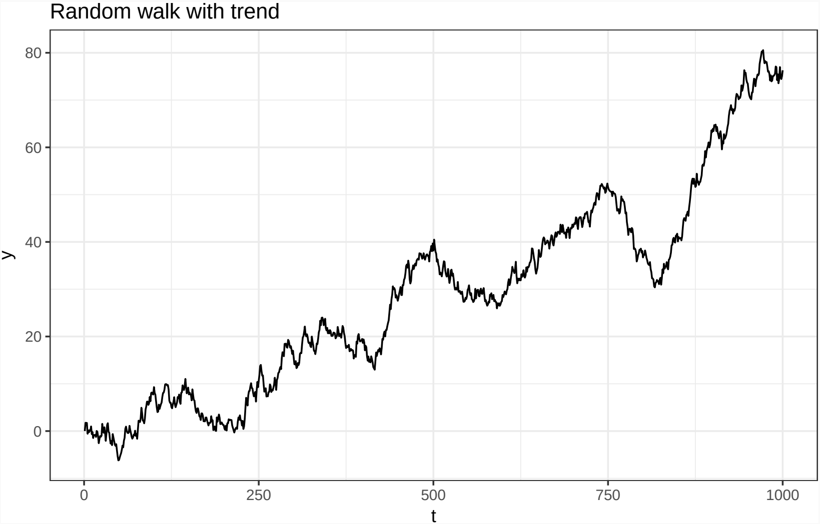
rw$y
30
20
10
0
−10
0
200
400
600
800
1000
ACF
1.00
0.75
0.50
0.25
0.00
0
10
20
30
40
50
Lag
PACF
1.00
0.75
0.50
0.25
0.00
0
10
20
30
40
50
Lag

Stationary?

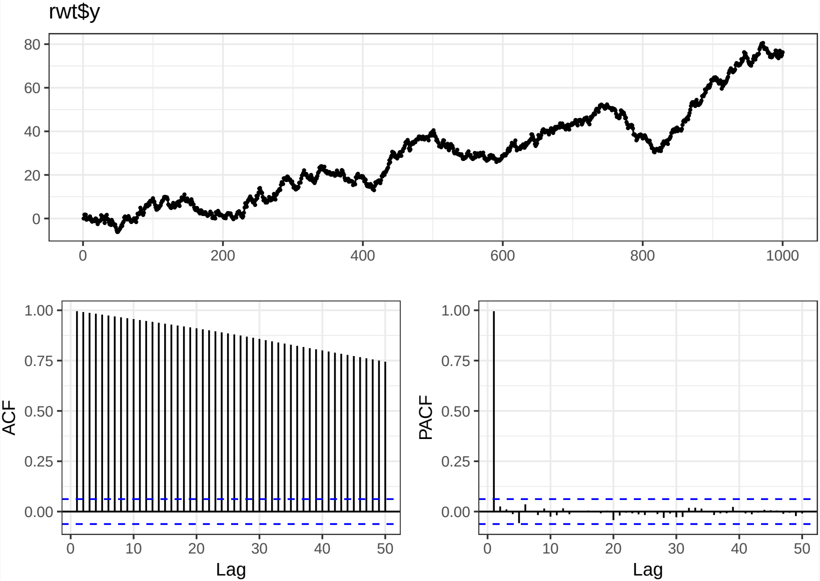
Is y_t stationary?

Example - Random walk with drift

Let $y_t = \delta + y_{t-1} + w_t$ with $y_0 = 0$ and $w_t \sim \mathcal{N}(0, 1)$.



ACF + PACF



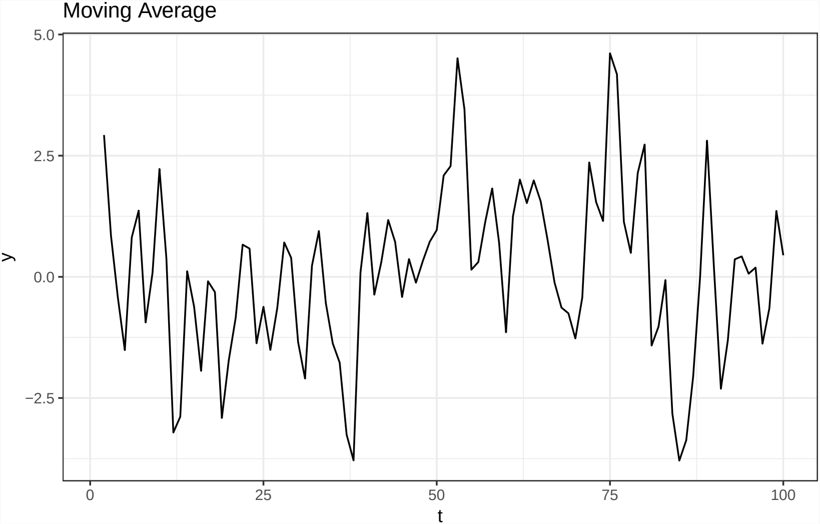
rwt$y
80
60
40
20
0
0
200
400
600
800
1000
1.00
0.75
0.50
0.25
0.00
ACF
0
10
20
30
40
50
Lag
1.00
0.75
0.50
0.25
0.00
PACF
0
10
20
30
40
50
Lag

Stationary?

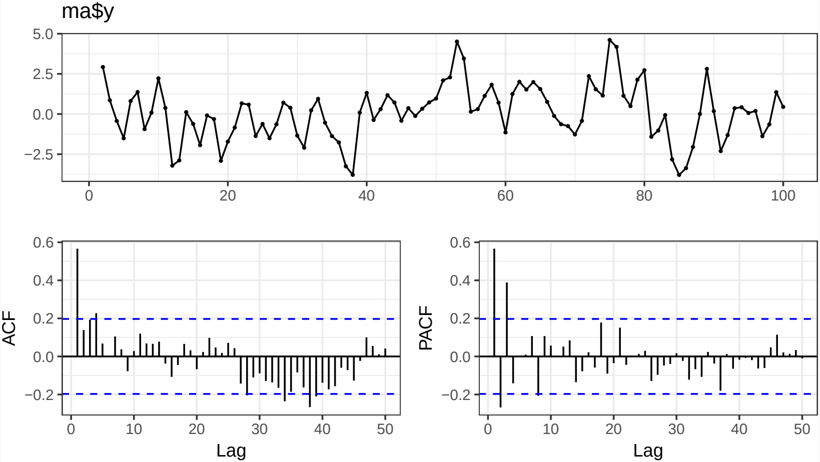
Is y_t stationary?

Example - Moving Average

Let $w_t \sim \mathcal{N}(0, 1)$ and $y_t = w_{t-1} + w_t$.



ACF + PACF

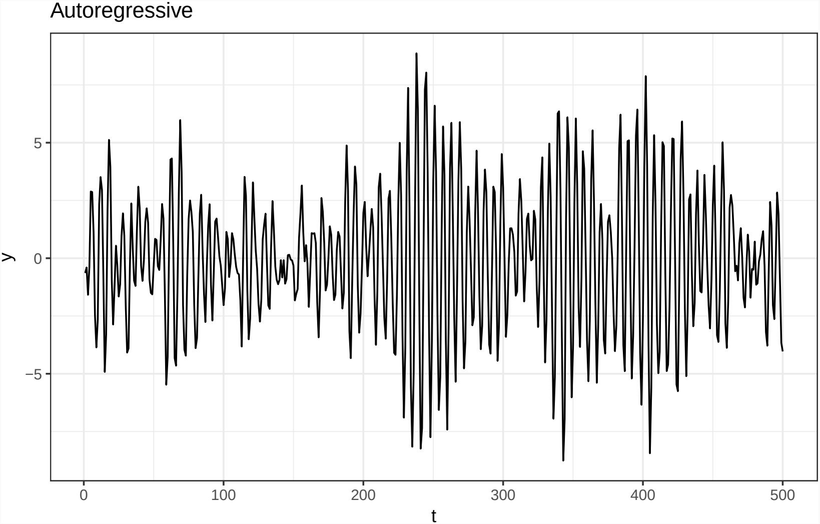


ma$y
5.0
2.5
0.0
−2.5
0
20
40
60
80
100
ACF
0.6
0.4
0.2
0.0
−0.2
0
10
20
30
40
50
Lag
PACF
0.6
0.4
0.2
0.0
−0.2
0
10
20
30
40
50
Lag

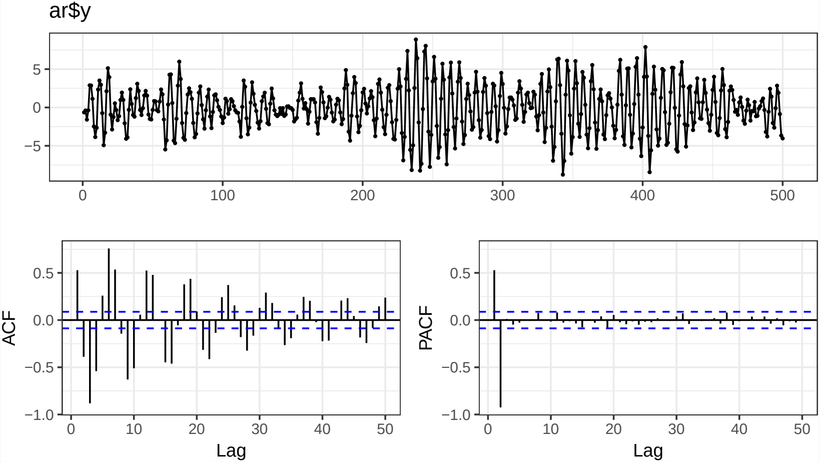
Stationary?

Is y_t stationary?

Let $w_t \sim \mathcal{N}(0,1)$ and $y_t = y_{t-1} - 0.9y_{t-2} + w_t$ with $y_t = 0$ for $t < 1$.



ACF + PACF

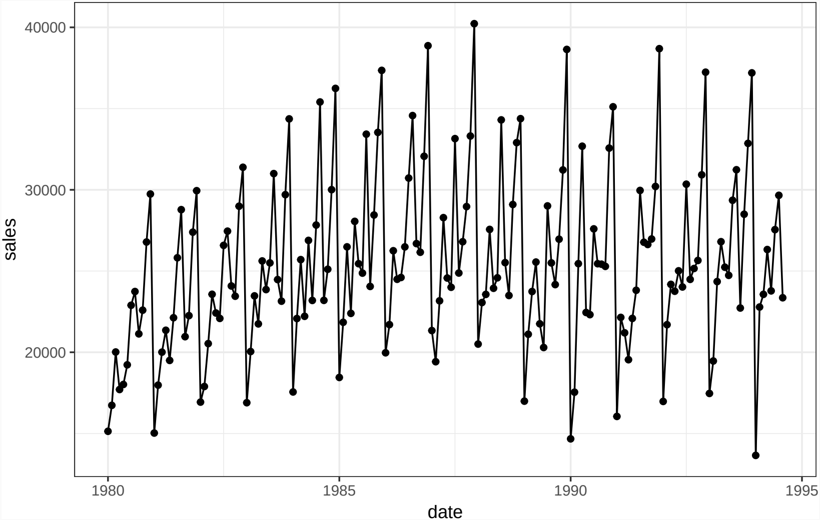

ar$y
5
0
−5
0
100
200
300
400
500
ACF
0.5
0.0
−0.5
−1.0
0
10
20
30
40
50
Lag
PACF
0.5
0.0
−0.5
−1.0
0
10
20
30
40
50
Lag

Example - Australian Wine Sales

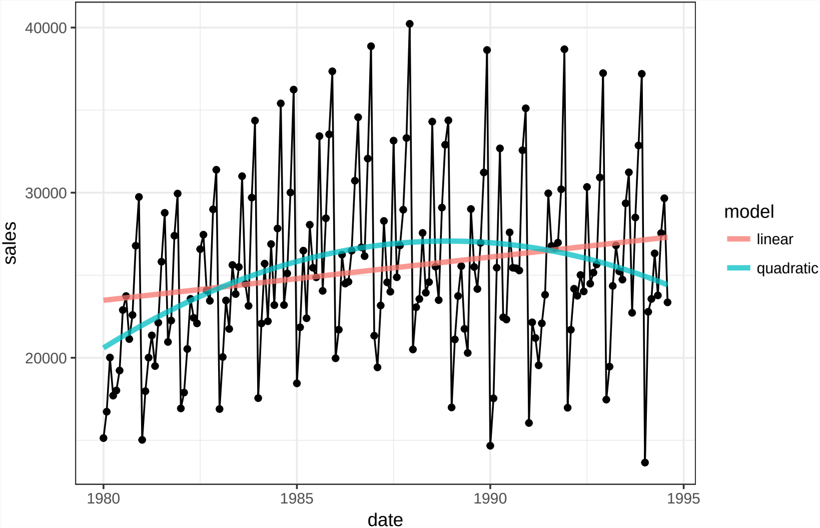
Australian total wine sales by wine makers in bottles <= 1 litre. Jan 1980 – Aug 1994.

```
aus_wine = readRDS("../data/aus_wine.rds")
aus_wine
## # A tibble: 176 x 2
##      date sales
##     <dbl> <dbl>
##  1  1980 15136
##  2  1980 16733
##  3  1980 20016
##  4  1980 17708
##  5  1980 18019
##  6  1980 19227
##  7  1980 22893
##  8  1981 23739
##  9  1981 21133
## 10  1981 22591
## # ... with 166 more rows
```

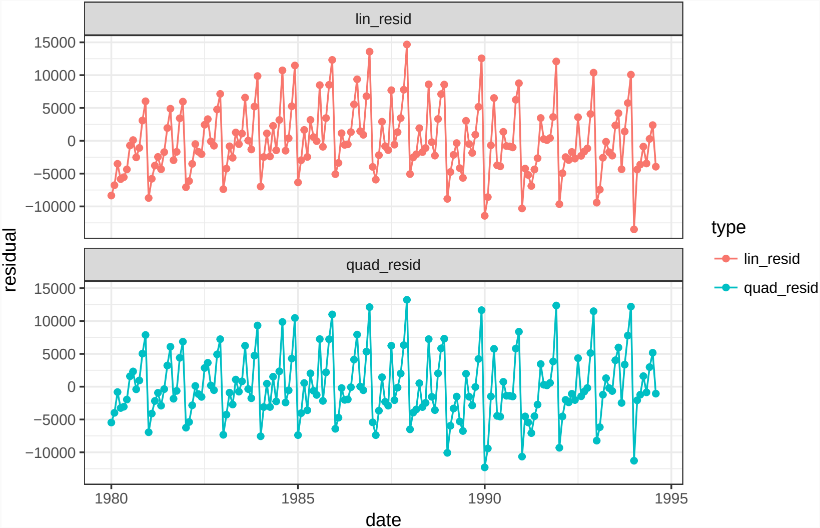
Time series



Basic Model Fit

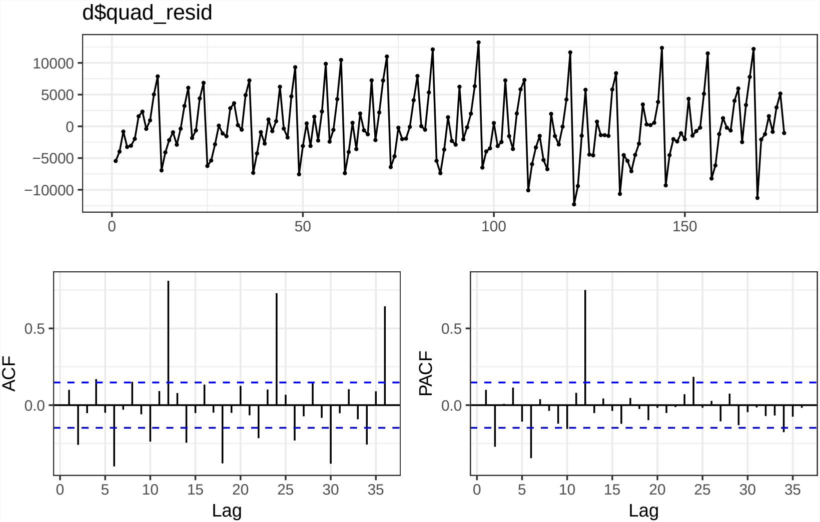


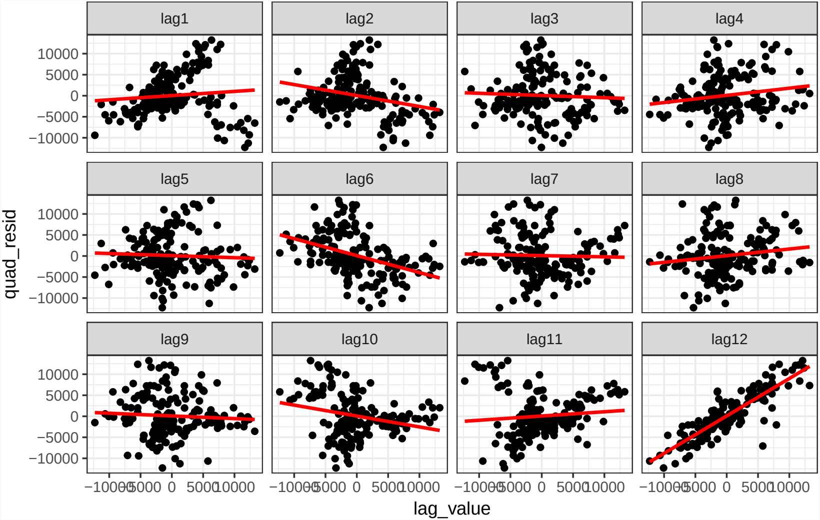
Residuals



lin_resid
quad_resid
15000
10000
5000
0
−5000
−10000
residual
1980
1985
1990
1995
date
type
lin_resid
quad_resid

Autocorrelation Plot

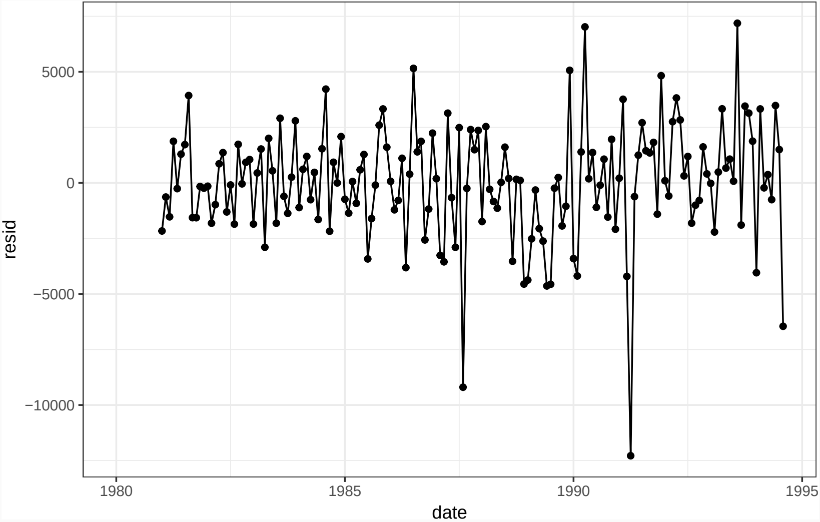



lag1
lag2
lag3
lag4
lag5
lag6
lag7
lag8
lag9
lag10
lag11
lag12
quad_resid
lag_value
10000
5000
0
−5000
−10000
−10000
−5000
0
5000
10000

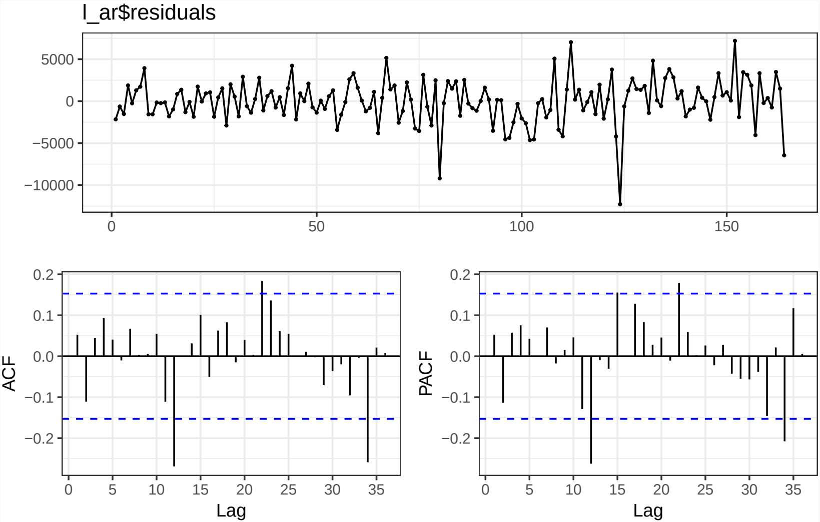
Auto regressive errors

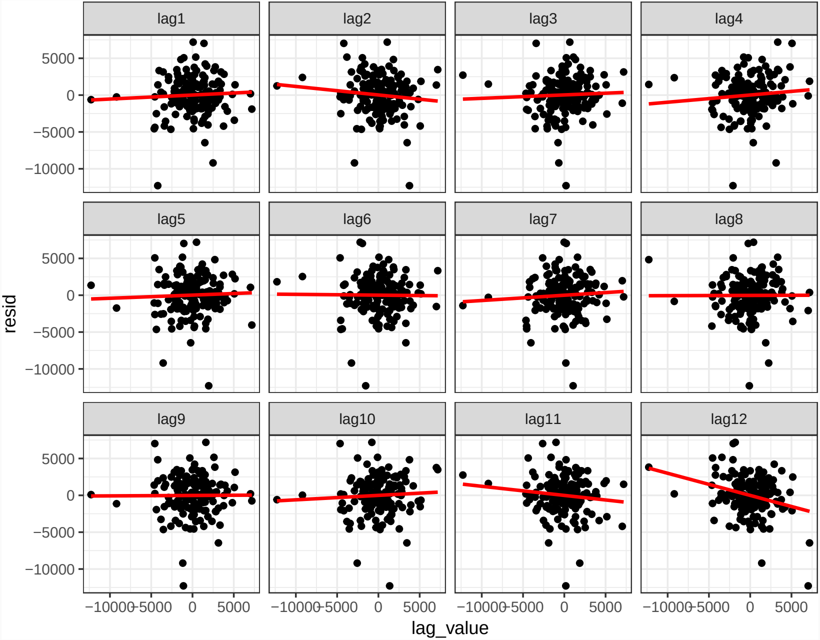
```
##
## Call:
## lm(formula = quad_resid ~ lag_12, data = d_ar)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -12286.5  -1380.5     73.4   1505.2   7188.1
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept)  83.65080  201.58416   0.415    0.679
## lag_12        0.89024    0.04045  22.006   <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 2581 on 162 degrees of freedom
##   (12 observations deleted due to missingness)
## Multiple R-squared:  0.7493, Adjusted R-squared:  0.7478
## F-statistic: 484.3 on 1 and 162 DF,  p-value: < 2.2e-16
```

Residual residuals



Residual residuals - acf




lag1
lag2
lag3
lag4
lag5
lag6
lag7
lag8
lag9
lag10
lag11
lag12
5000
0
−5000
−10000
resid
−10000
−5000
0
5000
lag_value

Writing down the model?

So, is our EDA suggesting that we fit the following model?

$$\text{sales}(t) = \beta_0 + \beta_1 \, t + \beta_2 \, t^2 + \beta_3 \, \text{sales}(t-12) + \epsilon_t$$

. . .

the model we actually fit is,

$$\text{sales}(t) = \beta_0 + \beta_1 \, t + \beta_2 \, t^2 + w_t$$

where

$$w_t = \delta \, w_{t-12} + \epsilon_t$$