

# Lecture 19

Spatial GLM + Point Reference Spatial Data

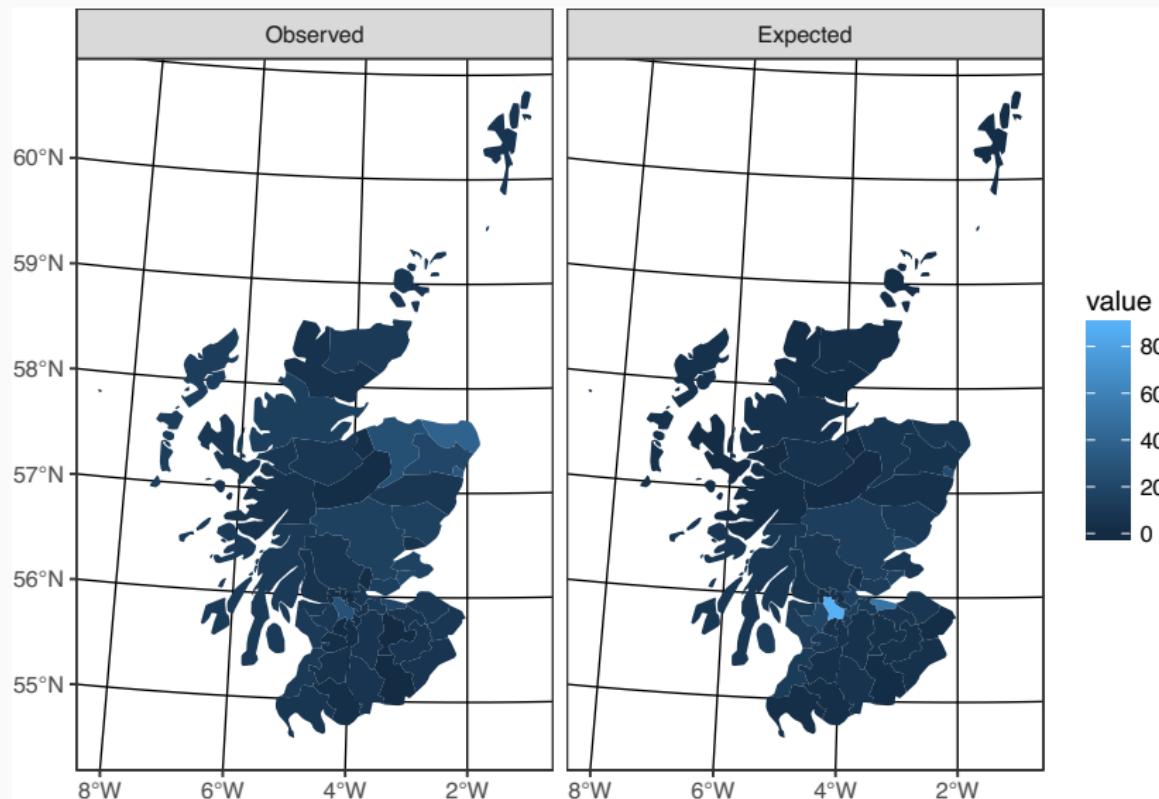
---

Colin Rundel

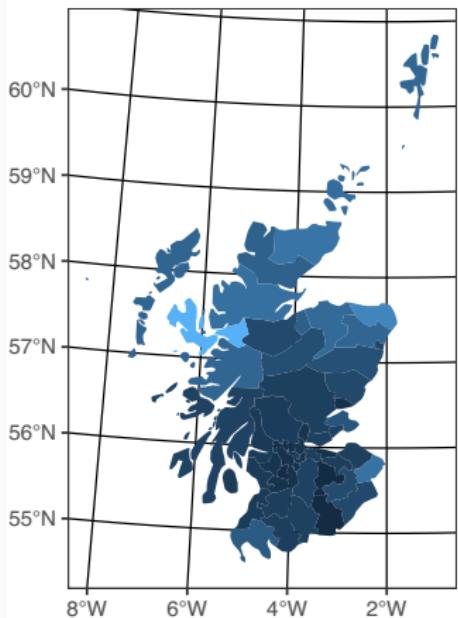
04/03/2017

# Spatial GLM Models

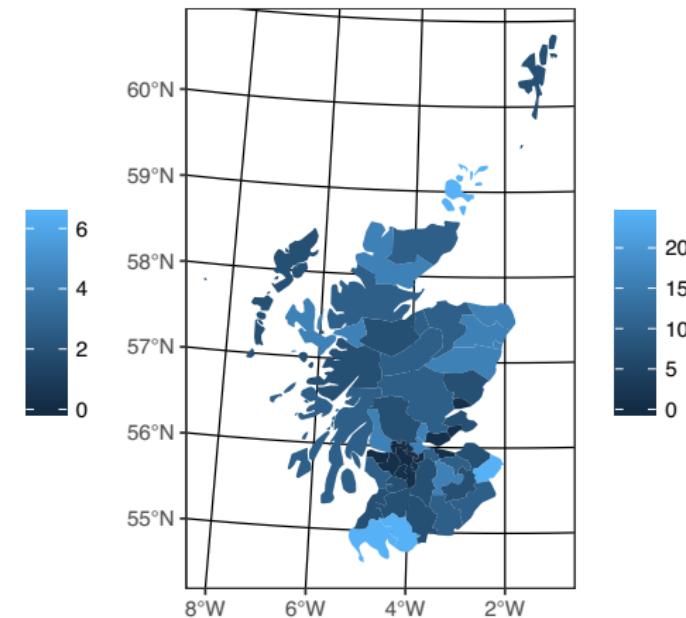
# Scottish Lip Cancer Data



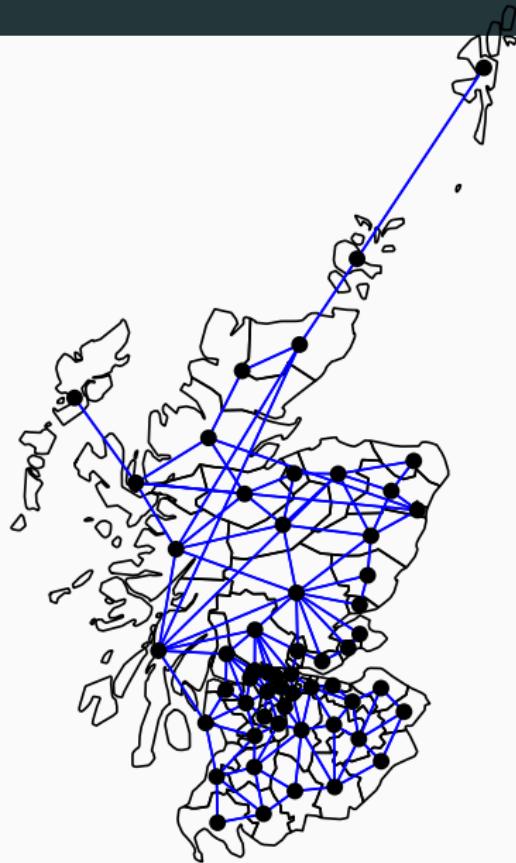
**Obs/Exp**



**% Agg Fish Forest**



## Neighborhood / weight matrix



## Moran's I

```
spdep::moran.test(lip_cancer$Observed, listw)
##
## Moran I test under randomisation
##
## data: lip_cancer$Observed
## weights: listw
##
## Moran I statistic standard deviate = 4.5416, p-value = 2.792e-06
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic      Expectation      Variance
## 0.311975396       -0.018181818       0.005284831

spdep::moran.test(lip_cancer$Observed / lip_cancer$Expected, listw)
##
## Moran I test under randomisation
##
## data: lip_cancer$Observed/lip_cancer$Expected
## weights: listw
##
## Moran I statistic standard deviate = 8.2916, p-value < 2.2e-16
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic      Expectation      Variance
## 0.589795225       -0.018181818       0.005376506
```

# GLM

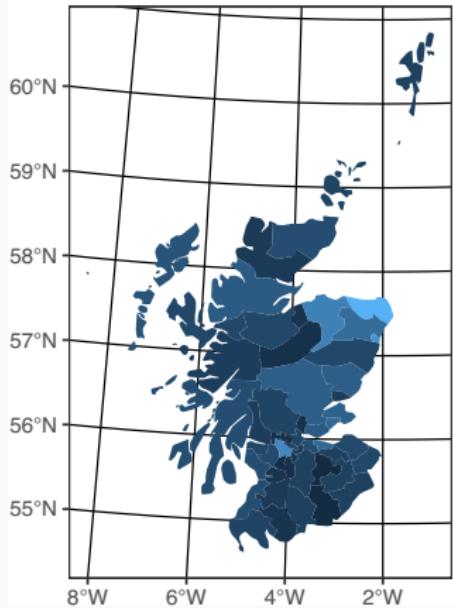
```
l = glm(Observed ~ offset(log(Expected)) + pcaff,
        family="poisson", data=lip_cancer)
summary(l)
##
## Call:
## glm(formula = Observed ~ offset(log(Expected)) + pcaff, family = "poisson",
##      data = lip_cancer)
##
## Deviance Residuals:
##      Min       1Q   Median       3Q      Max
## -4.7632  -1.2156   0.0967   1.3362   4.7130
##
## Coefficients:
##             Estimate Std. Error z value Pr(>|z|)
## (Intercept) -0.542268   0.069525  -7.80 6.21e-15 ***
## pcaff       0.073732   0.005956   12.38 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## (Dispersion parameter for poisson family taken to be 1)
##
## Null deviance: 380.73 on 55 degrees of freedom
## Residual deviance: 238.62 on 54 degrees of freedom
## AIC: 450.6
##
## Number of Fisher Scoring iterations: 5
```

$$\log(\text{obs}) = \log(\text{Exp}) + \beta_0 + \beta_1 X$$

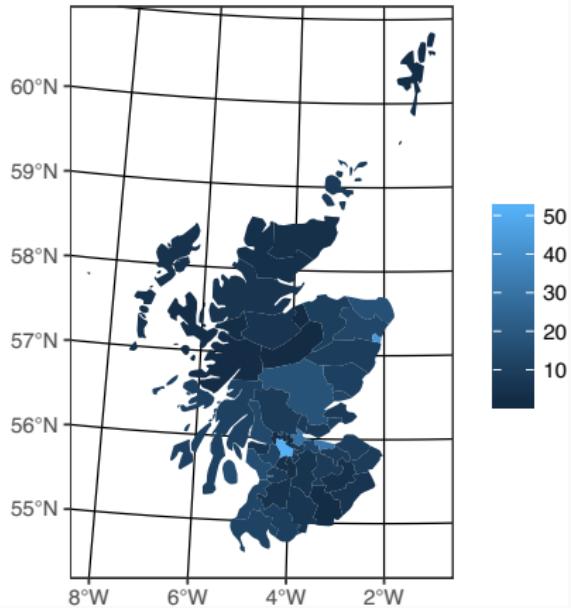
$$\log\left(\frac{\text{obs}}{\text{exp}}\right) = \beta_0 + \beta_1 X$$

# GLM Fit

Observed Cases

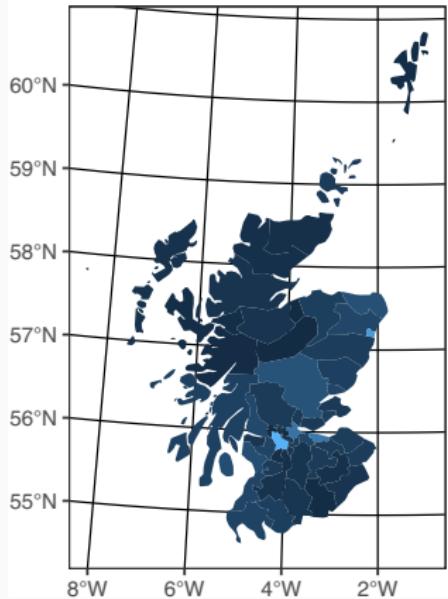


GLM Predicted Cases

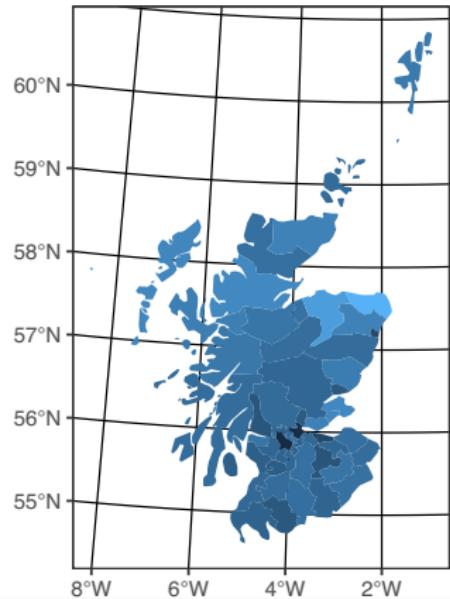


# GLM Residuals

GLM Predicted Cases



GLM Residuals



## Model Results

```
#RMSE
lip_cancer$glm_resid %>% .^2 %>% mean() %>% sqrt()
## [1] 7.480889

#Moran's I
spdep::moran.test(lip_cancer$glm_resid, listw)
##
## Moran I test under randomisation
##
## data: lip_cancer$glm_resid
## weights: listw
##
## Moran I statistic standard deviate = 4.8186, p-value = 7.228e-07
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic      Expectation      Variance
##          0.333403223     -0.018181818     0.005323717
```

## A hierarchical model for lip cancer

We have observed counts of lip cancer for 56 districts in Scotland. Let  $y_i$  represent the number of lip cancer for district  $i$ .

$$y_i \sim \text{Poisson}(\lambda_i)$$

$$\log(\lambda_i) = \log(E_i) + x_i\beta + \omega_i$$

$$\boldsymbol{\omega} \sim \mathcal{N}(\mathbf{0}, \sigma^2(\mathbf{D} - \phi \mathbf{W})^{-1})$$

where  $E_i$  is the expected counts for each region (and serves as an offset).

## Data prep & CAR model

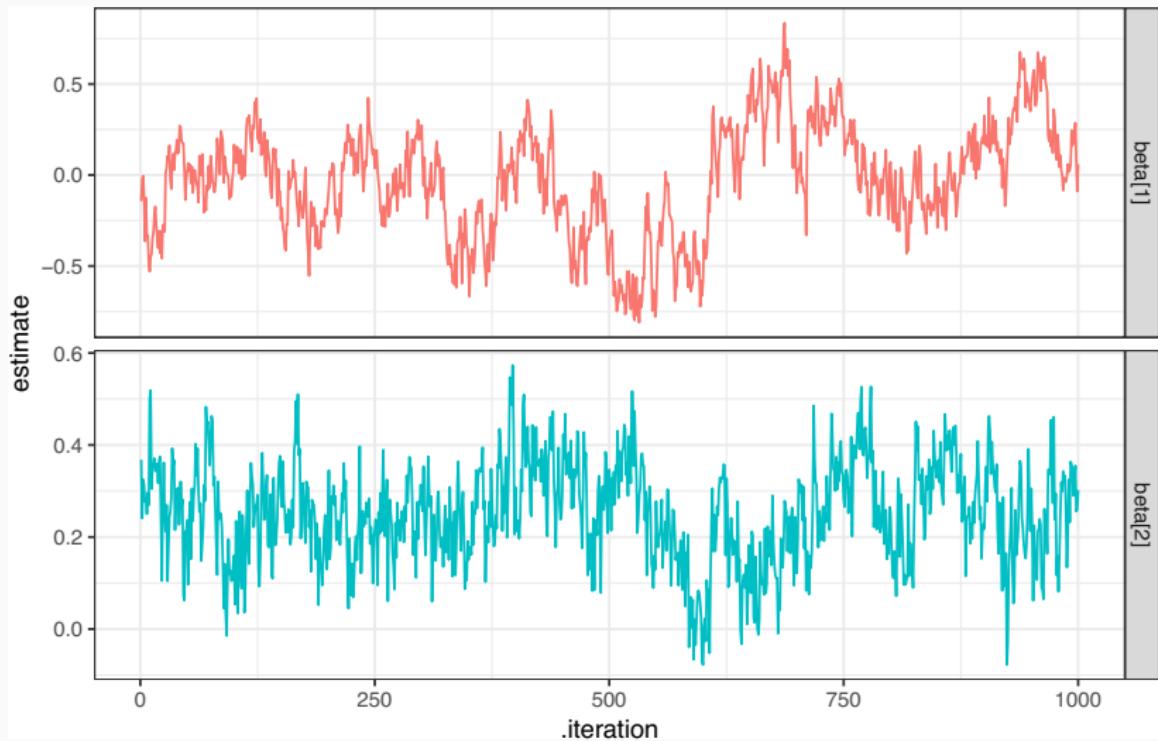
```
D = diag(rowSums(W))
X = model.matrix(~scale(lip_cancer$pcaff))
log_offset = log(lip_cancer$Expected)
y = lip_cancer$Observed

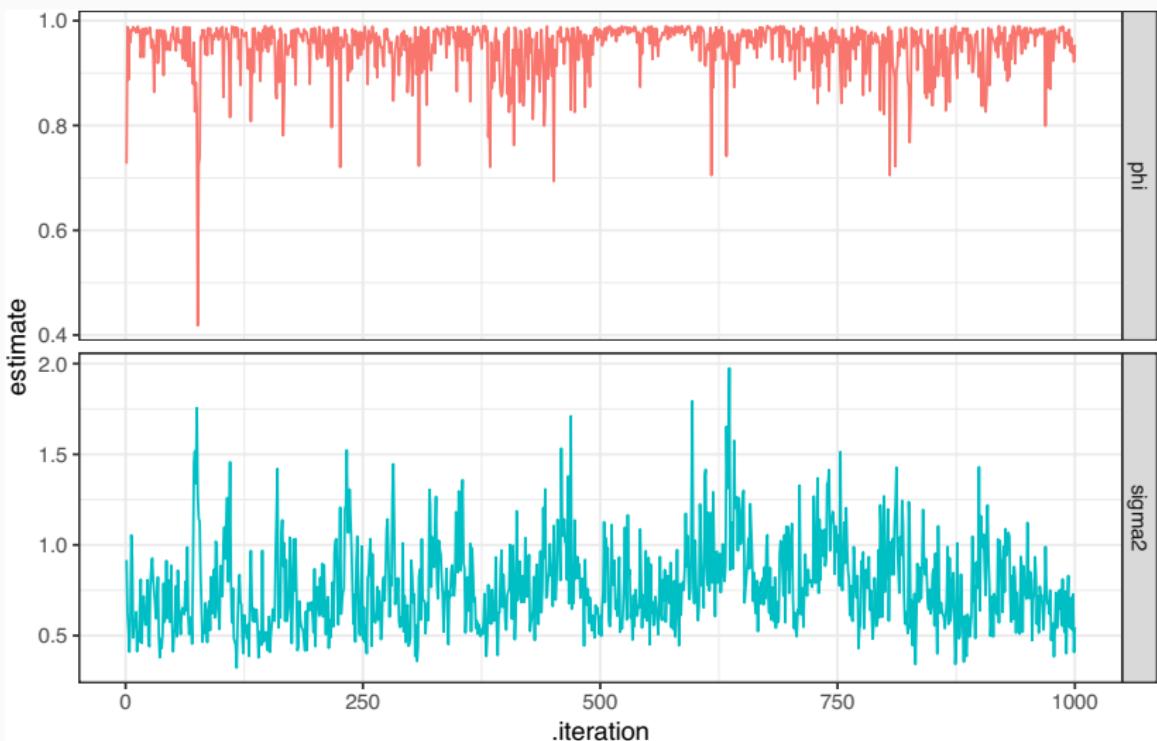
car_model = "model{
  for(i in 1:length(y)) {
    y[i] ~ dpois(lambda[i])
    y_pred[i] ~ dpois(lambda[i])
    log(lambda[i]) = log_offset[i] + X[i,] %*% beta + omega[i]
  }

  for(i in 1:2) {
    beta[i] ~ dnorm(0,1)
  }

  omega ~ dmnorm(rep(0,length(y)), tau * (D - phi*W))
  sigma2 = 1/tau
  tau ~ dgamma(2, 2)
  phi ~ dunif(0,0.99)
}"
```

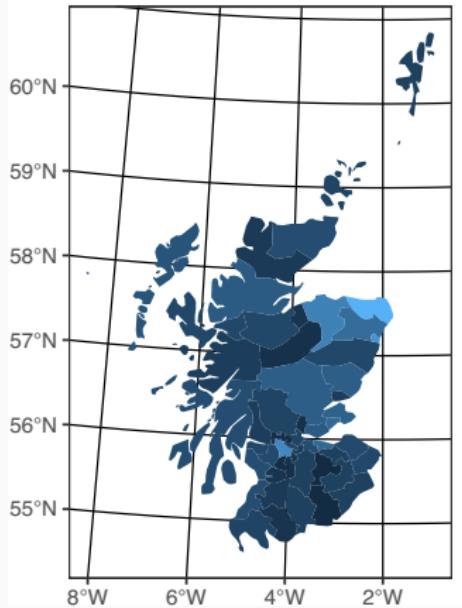
## CAR Results



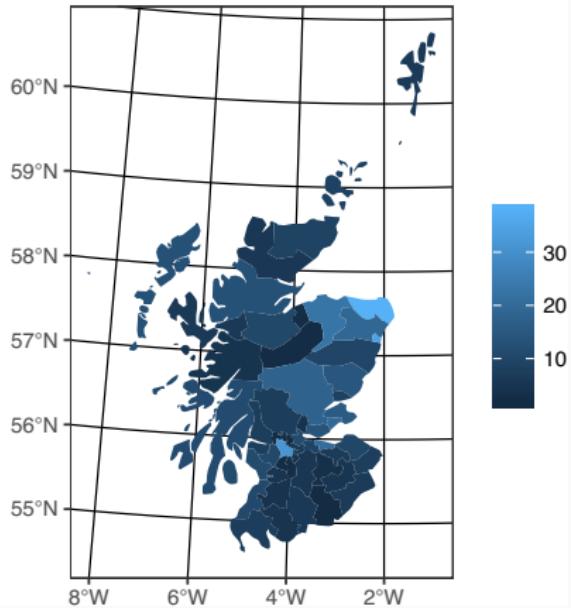


# CAR Predictions

Observed Cases

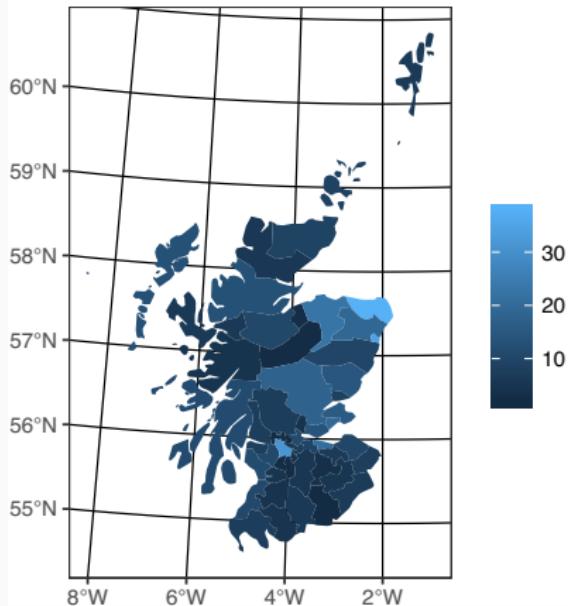


Predicted Cases

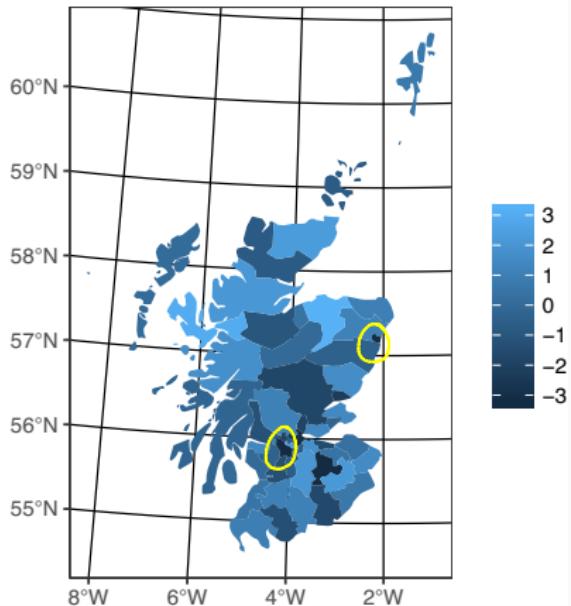


# CAR Residuals

Predicted Cases



Residuals



## CAR Results

```
#RMSE
lip_cancer$car_resid %>% .^2 %>% mean() %>% sqrt()
## [1] 1.586241

#Moran's I
spdep::moran.test(lip_cancer$car_resid, listw)
##
## Moran I test under randomisation
##
## data: lip_cancer$car_resid
## weights: listw
##
## Moran I statistic standard deviate = 1.0633, p-value = 0.1438
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic      Expectation      Variance
##          0.061804482     -0.018181818     0.005658742
```

## Intrinsic Autoregressive Model

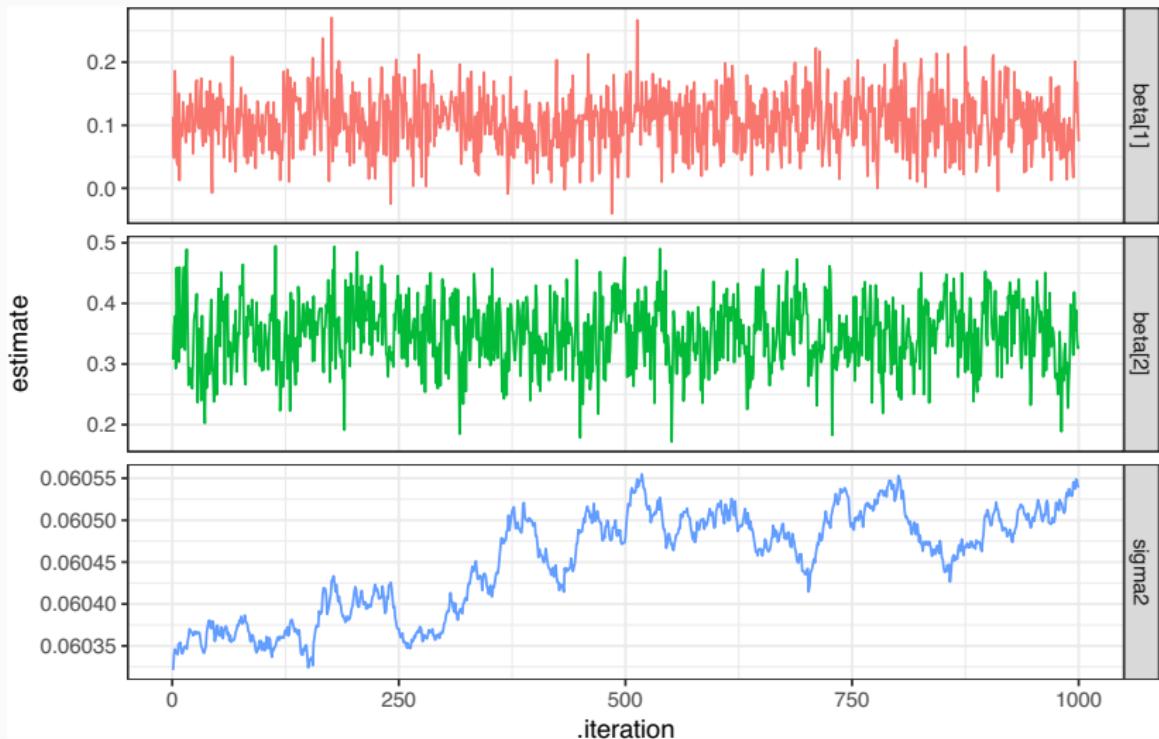
$$\zeta_{v_i^t} = \left( v_i^t - \frac{\sum v_j^t}{n} \right)$$

```
iar_model = "model{
  for(i in 1:length(y)) {
    y[i] ~ dpois(lambda[i])
    y_pred[i] ~ dpois(lambda[i])
    log(lambda[i]) = log_offset[i] + X[i,] %*% beta + omega[i]
  }

  for(i in 1:2) {
    beta[i] ~ dnorm(0,1)
  }

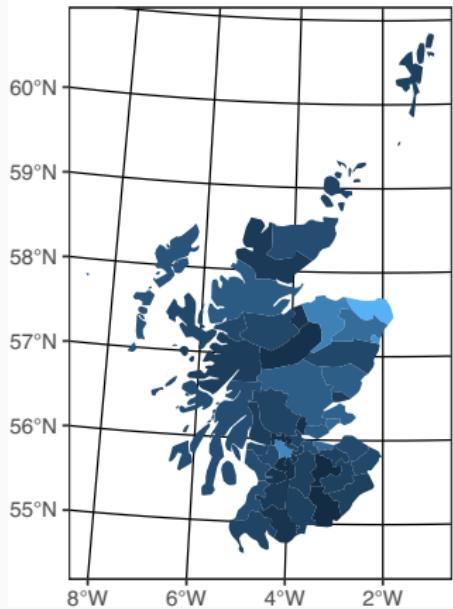
  omega_free ~ dmnorm(rep(0,length(y)), tau * (D - W))
  omega = omega_free - mean(omega_free)
  sigma2 = 1/tau
  tau ~ dgamma(2, 2)
}"
```

## Model Parameters

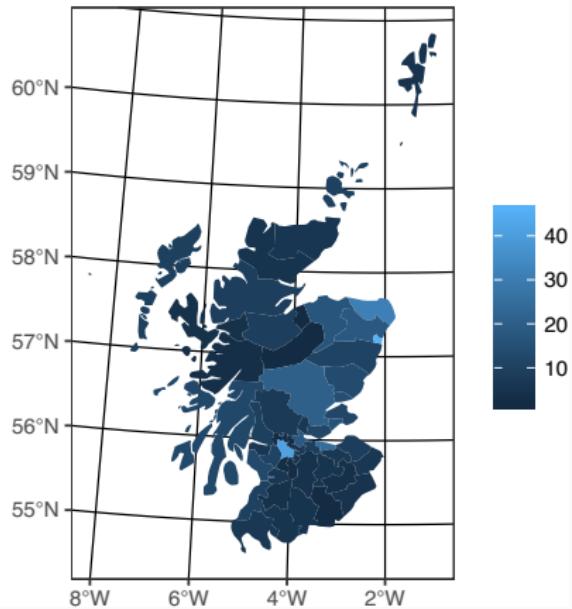


# Predictions

Observed Cases

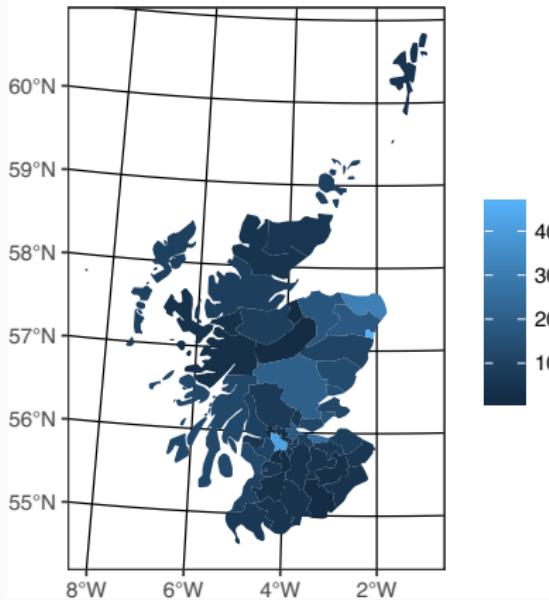


Predicted Cases

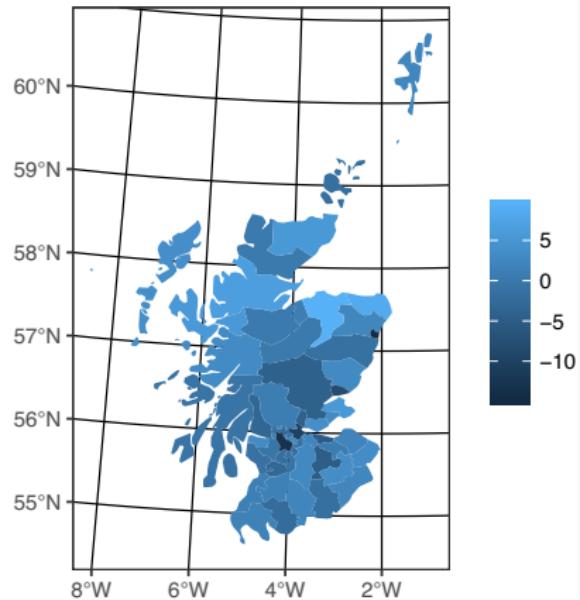


# Residuals

Predicted Cases



Residuals



## IAR Results

```
#RMSE
lip_cancer$iar_resid %>% .^2 %>% mean() %>% sqrt()
## [1] 4.473069

#Moran's I
spdep::moran.test(lip_cancer$iar_resid, listw)
##
## Moran I test under randomisation
##
## data: lip_cancer$iar_resid
## weights: listw
##
## Moran I statistic standard deviate = 2.6377, p-value = 0.004174
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic      Expectation      Variance
##          0.175216401     -0.018181818     0.005375965
```

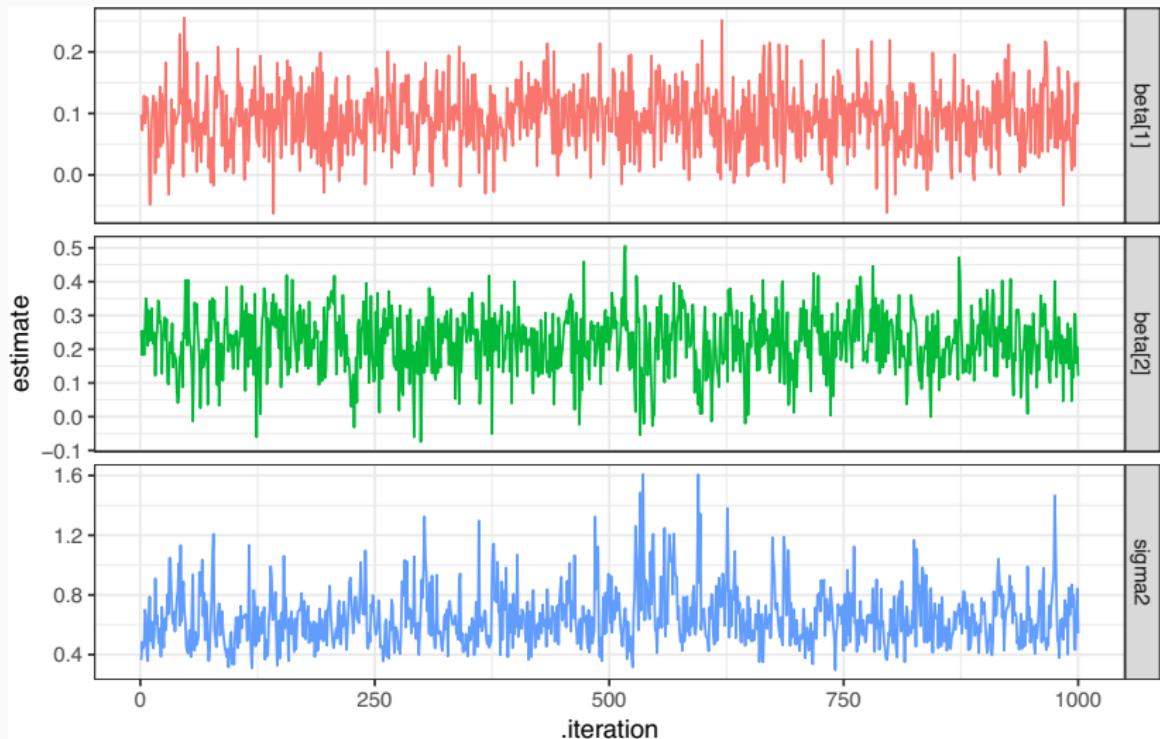
## Intrinsic Autoregressive Model - Reparameterized

```
iar_model2 = "model{
  for(i in 1:length(y)) {
    y[i] ~ dpois(lambda[i])
    y_pred[i] ~ dpois(lambda[i])
    log(lambda[i]) = log_offset[i] + X[i,] %*% beta + sigma * omega[i]
  }

  for(i in 1:2) {
    beta[i] ~ dnorm(0,1)
  }

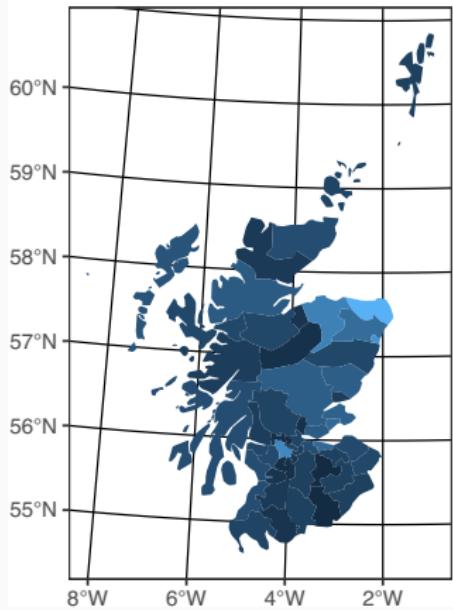
  omega_free ~ dmnorm(rep(0,length(y)), (D - w))
  omega = omega_free - mean(omega_free)
  sigma2 = 1/tau
  sigma = sqrt(sigma2)
  tau ~ dgamma(2, 2)
}"
```

## IAR(2) Parameters

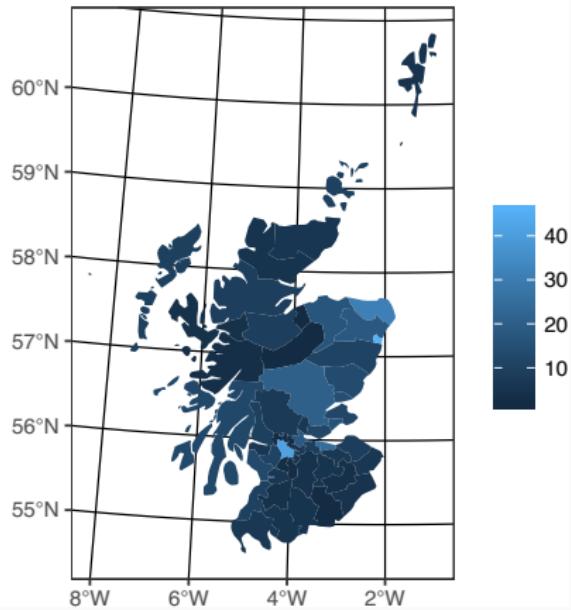


# Predictions

Observed Cases

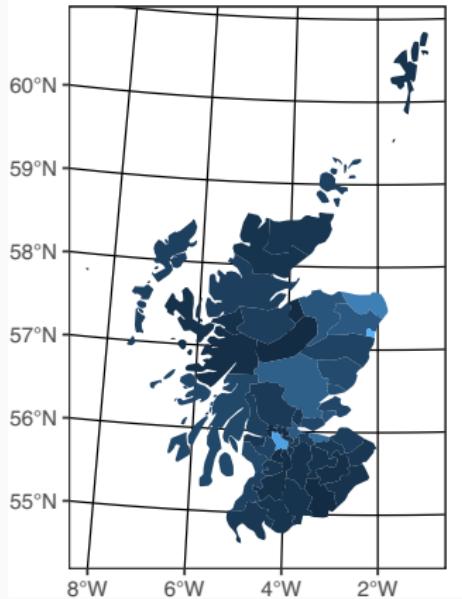


Predicted Cases

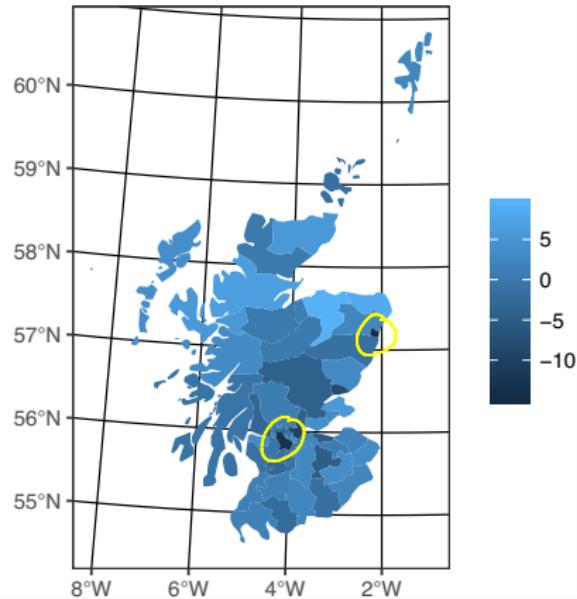


# Residuals

Predicted Cases



Residuals



## IAR(2) Results

```
#RMSE
lip_cancer$iar2_resid %>% .^2 %>% mean() %>% sqrt()
## [1] 1.654235

#Moran's I
spdep::moran.test(lip_cancer$iar2_resid, listw)
##
## Moran I test under randomisation
##
## data: lip_cancer$iar2_resid
## weights: listw
##
## Moran I statistic standard deviate = 0.39186, p-value = 0.3476
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic      Expectation      Variance
##          0.011188088     -0.018181818     0.005617437
```

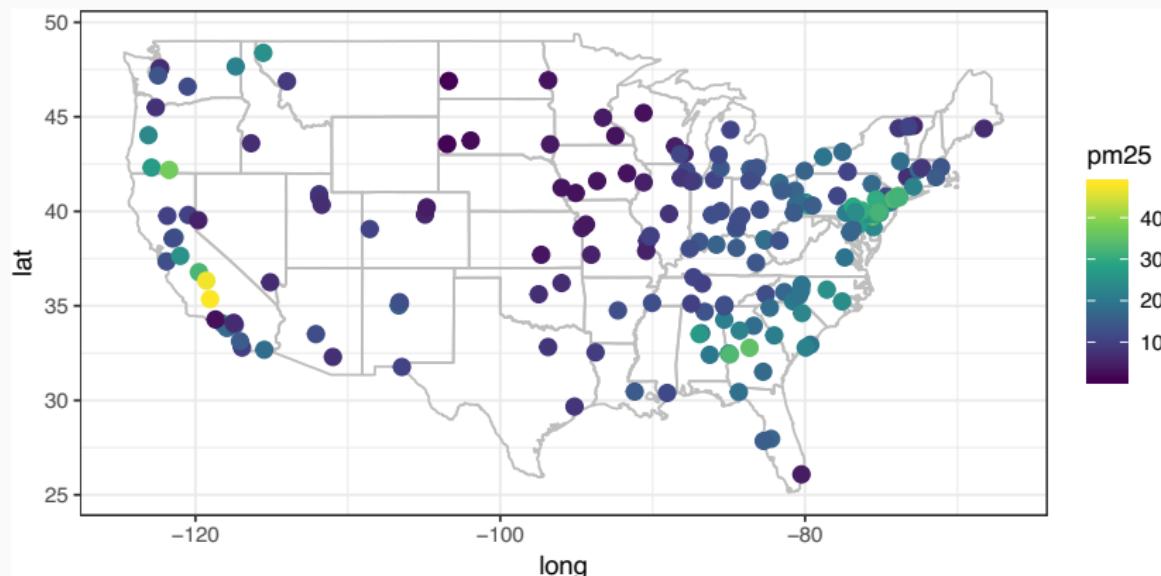
## Overall Results

model	rmse	moran
glm	7.4809	0.3334
car	1.5862	0.0618
iar	4.4731	0.1752
iar2	1.6542	0.0112

## Point Referenced Data

## Example - PM2.5 from CSN

The Chemical Speciation Network are a series of air quality monitors run by EPA (221 locations in 2007). We'll look at a subset of the data from Nov 11th, 2007 ( $n=191$ ) for just PM2.5.



```
csn
## # A tibble: 191 x 5
##       site longitude latitude date      pm25
##       <int>     <dbl>    <dbl> <dttm>
## 1 10730023     -86.8    33.6 2007-11-14 00:00:00 19.4
## 2 10732003     -86.9    33.5 2007-11-14 00:00:00 26.4
## 3 10890014     -86.6    34.7 2007-11-14 00:00:00 13.4
## 4 11011002     -86.3    32.4 2007-11-14 00:00:00 19.7
## 5 11130001     -85.0    32.5 2007-11-14 00:00:00 22.6
## 6 40139997    -112.     33.5 2007-11-14 00:00:00 12.3
## 7 40191028    -111.     32.3 2007-11-14 00:00:00  7.20
## 8 51190007    -92.3    34.8 2007-11-14 00:00:00 12.7
## 9 60070002   -122.     39.8 2007-11-14 00:00:00 10.0
## 10 60190008   -120.     36.8 2007-11-14 00:00:00 32.3
## # ... with 181 more rows
```

## Aside - Splines



## Splines in 1d - Smoothing Splines

These are a mathematical analogue to the drafting splines represented using a penalized regression model.

## Splines in 1d - Smoothing Splines

These are a mathematical analogue to the drafting splines represented using a penalized regression model.

We want to find a function  $f(x)$  that best fits our observed data  $\mathbf{y} = y_1, \dots, y_n$  while being as *smooth* as possible.

$$\arg \min_{f(x)} \sum_{i=1}^n (y_i - f(x_i))^2 + \lambda \int f''(x)^2 dx$$

Interestingly, this minimization problem has an exact solution which is given by a mixture of weighted natural cubic splines (cubic splines that are linear in the tails) with knots at the observed data locations ( $xs$ ).

## Splines in 2d - Thin Plate Splines

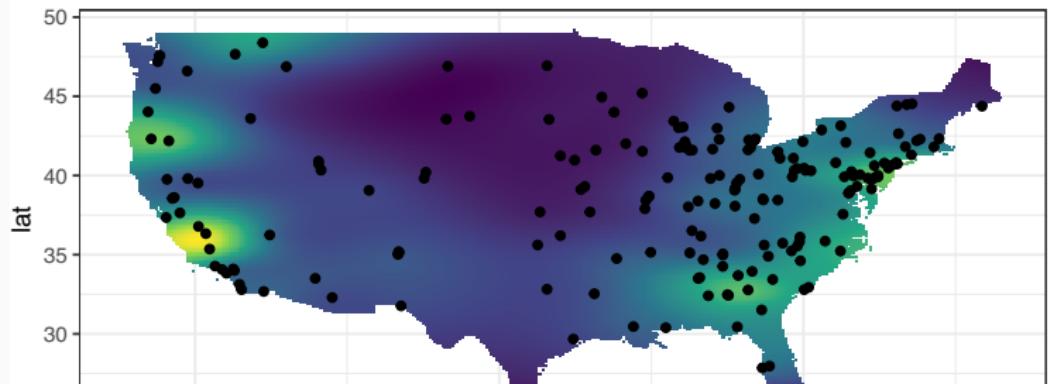
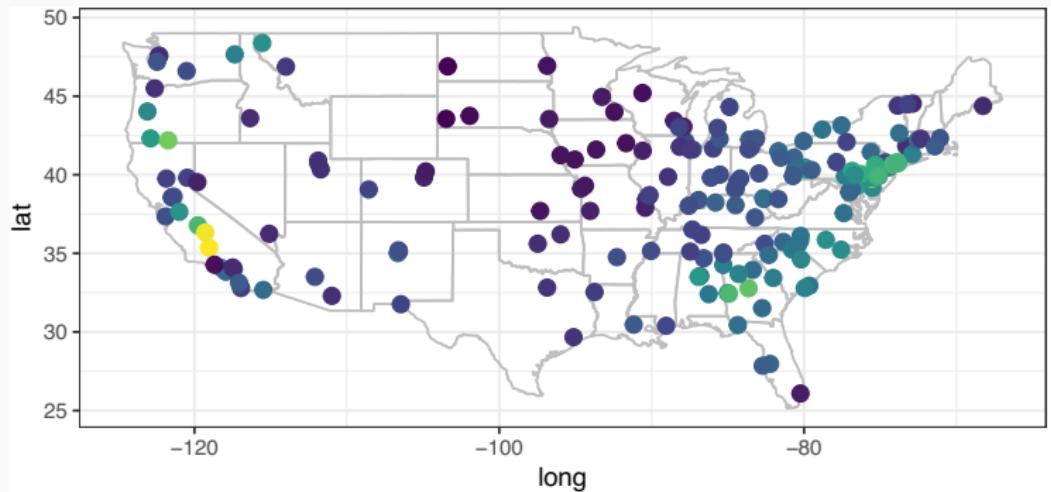
Now imagine we have observed data of the form  $(x_i, y_i, z_i)$  where we wish to predict  $z_i$  given  $x_i$  and  $y_i$  for all  $i$ . We can naturally extend the smoothing spline model in two dimensions,

$$\arg \min_{f(x,y)} \sum_{i=1}^n (z_i - f(x_i, y_i))^2 + \lambda \int \int \left( \frac{\partial^2 f}{\partial x^2} + 2 \frac{\partial^2 f}{\partial x \partial y} + \frac{\partial^2 f}{\partial y^2} \right) dx dy$$

The solution to this equation has a natural representation using a weighted sum of *radial basis functions* with knots at the observed data locations

$$f(x, y) = \sum_{i=1}^n w_i d(x_i, y_i)^2 \log d(x_i, y_i).$$

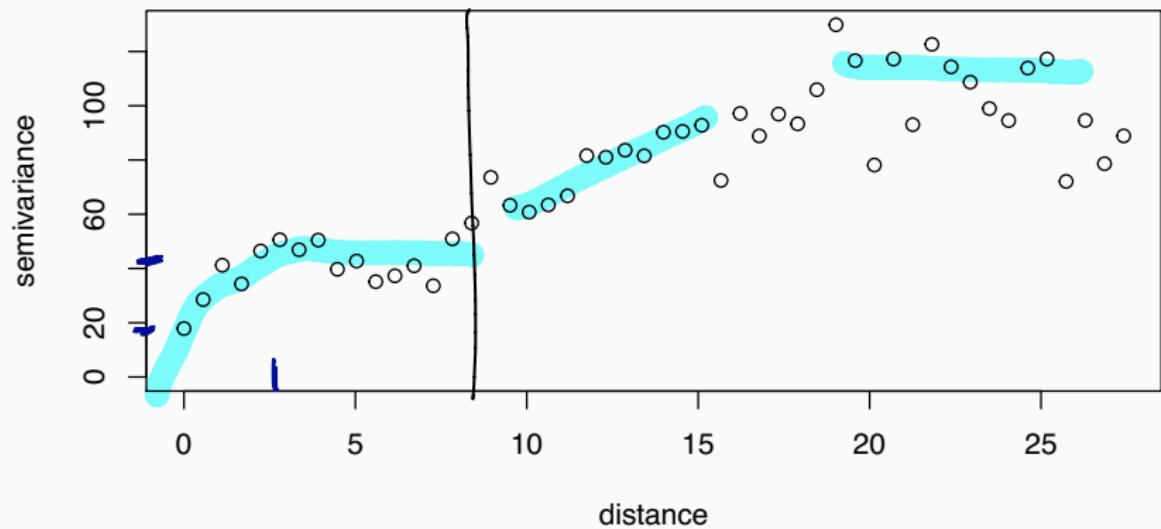
## Fitting a TPS



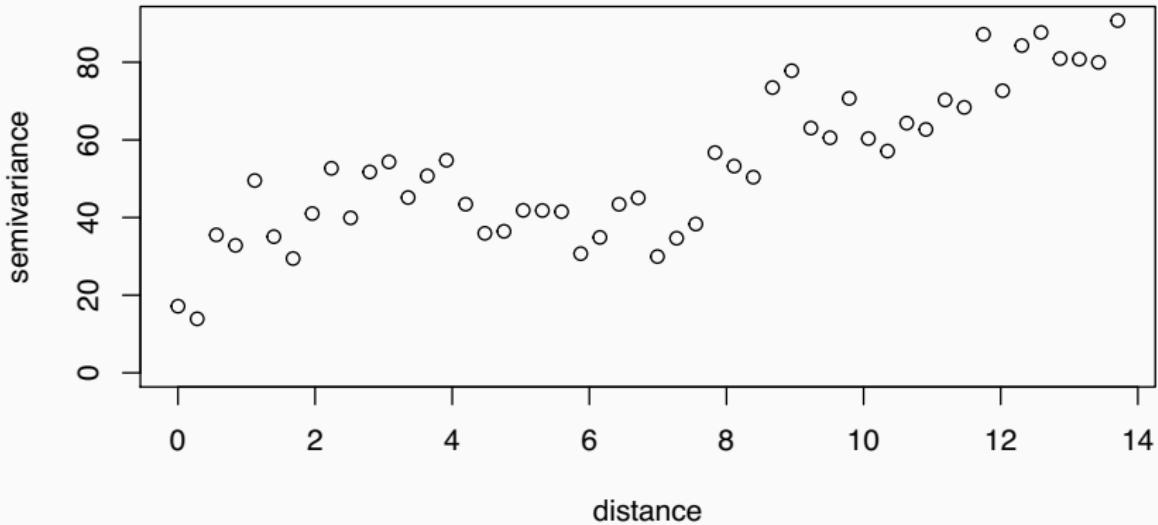
## Gaussian Process Models / Kriging

# Variogram

```
coords = csn %>% select(latitude, longitude) %>% as.matrix()  
d = fields::rdist(coords)  
  
geoR::variog(coords = coords, data = csn$pm25, messages = FALSE,  
    uvec = seq(0, max(d)/2, length.out=50)) %>% plot()
```

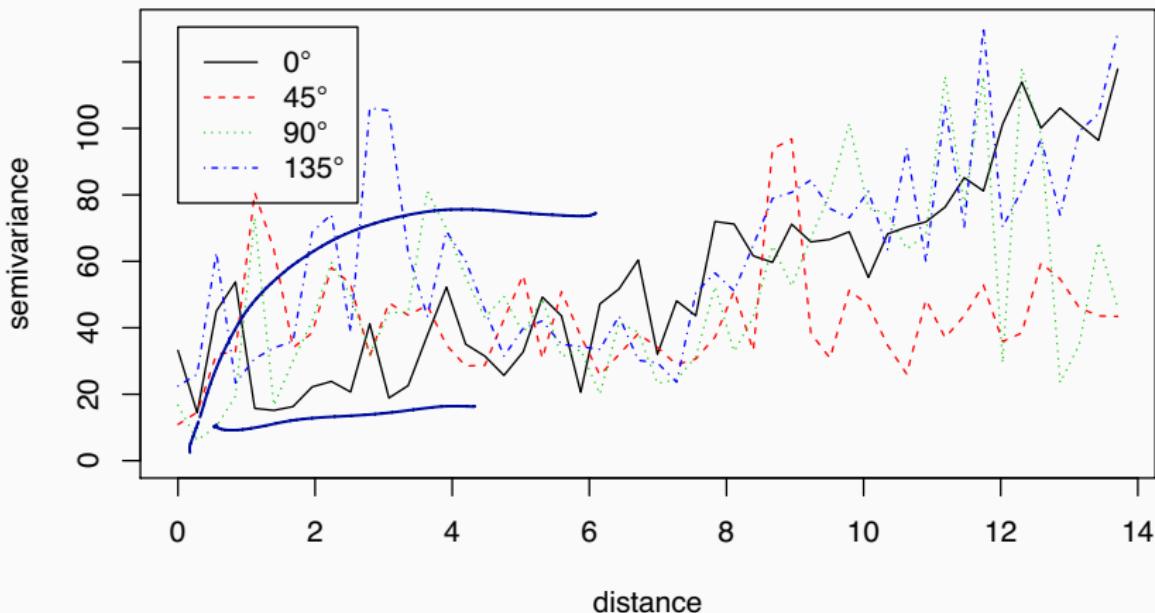


```
geoR::variog(coords = coords, data = csn$pm25, messages = FALSE,  
uvec = seq(0, max(d)/4, length.out=50)) %>% plot()
```



## Isotropy / Anisotropy

```
v4 = geoR:::variog4(coords = coords, data = csn$pm25, messages = FALSE,  
                      uvec = seq(0, max(d)/4, length.out = 50))  
plot(v4)
```



## GP Spatial Model

If we assume that our data is *stationary* and *isotropic* then we can use a Gaussian Process model to fit the data. We will assume an exponential covariance structure.

$$\mathbf{y} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$$

$$\{\Sigma\}_{ij} = \sigma^2 \exp(-r \|s_i - s_j\|) + \sigma_n^2 \mathbf{1}_{i=j}$$

## GP Spatial Model

If we assume that our data is *stationary* and *isotropic* then we can use a Gaussian Process model to fit the data. We will assume an exponential covariance structure.

$$\mathbf{y} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$$

$$\{\Sigma\}_{ij} = \sigma^2 \exp(-r \|s_i - s_j\|) + \sigma_n^2 \mathbf{1}_{i=j}$$

we can also view this as a spatial random effects model where

$$y(\mathbf{s}) = \mu(\mathbf{s}) + w(\mathbf{s}) + \epsilon(\mathbf{s})$$

$$w(\mathbf{s}) \sim \mathcal{N}(0, \Sigma')$$

$$\epsilon(s_i) \sim \mathcal{N}(0, \sigma_n^2)$$

$$\{\Sigma'\}_{ij} = \sigma^2 \exp(-r \|s_i - s_j\|)$$

## Fitting with spBayes

```
n = nrow(csn)
n_samp = 20000
coords = select(csn, longitude, latitude) %>% as.matrix()
max_range = max(dist(coords)) / 4

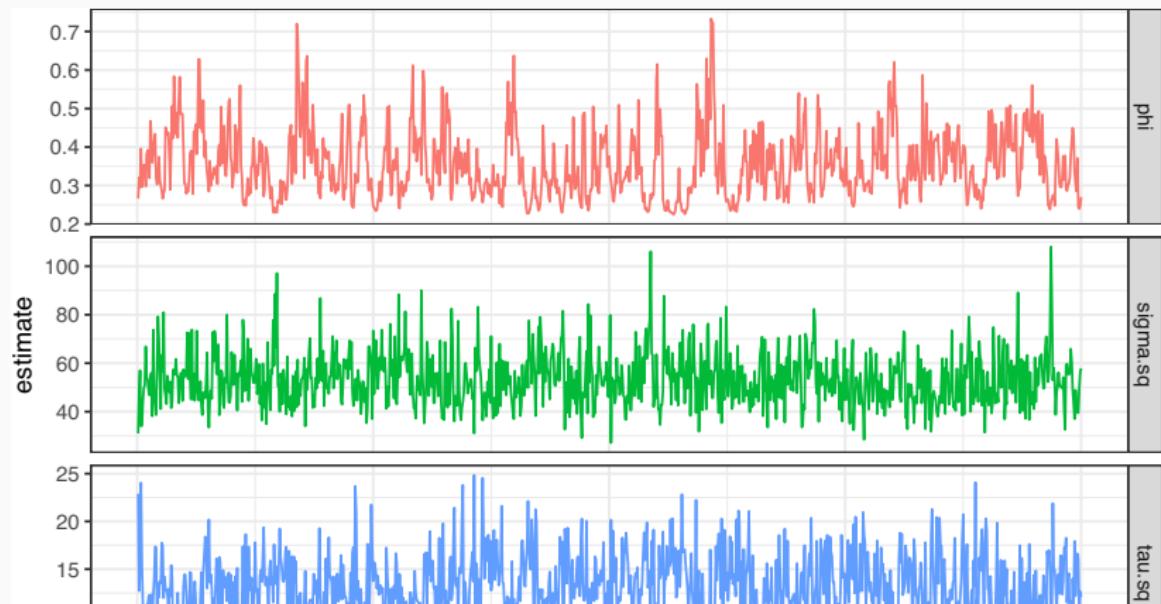
starting = list(phi = 3/3, sigma.sq = 33, tau.sq = 17)
tuning = list("phi"=0.1, "sigma.sq"=0.1, "tau.sq"=0.1)
priors = list(
  beta.Norm = list(0, 1000),
  phi.Unif = c(3/max_range, 3/(0.5)),
  sigma.sq.IG = c(2, 2),
  tau.sq.IG = c(2, 2)
)
```

```
m = spBayes::spLM(pm25 ~ 1, data = csn, coords = coords, starting = starting, priors = priors,
                  cov.model = "exponential", n.samples = n_samp, tuning = tuning,
                  n.report = n_samp/2)
## -----
## General model description
## -----
## Model fit with 191 observations.
##
## Number of covariates 1 (including intercept if specified).
##
## Using the exponential spatial correlation model.
##
## Number of MCMC samples 20000.
##
## Priors and hyperpriors:
## beta normal:
## mu: 0.000
## cov:
## 1000.000
##
## sigma.sq IG hyperpriors shape=2.00000 and scale=2.00000
## tau.sq IG hyperpriors shape=2.00000 and scale=2.00000
## phi Unif hyperpriors a=0.21888 and b=6.00000
## -----
## Sampling
## -----
## Sampled: 10000 of 20000, 50.00%
## Report interval Metrop. Acceptance rate: 32.56%
## Overall Metrop. Acceptance rate: 32.56%
## -----
## Sampled: 20000 of 20000, 100.00%
## Report interval Metrop. Acceptance rate: 32.82%
## Overall Metrop. Acceptance rate: 32.69%
## -----
```

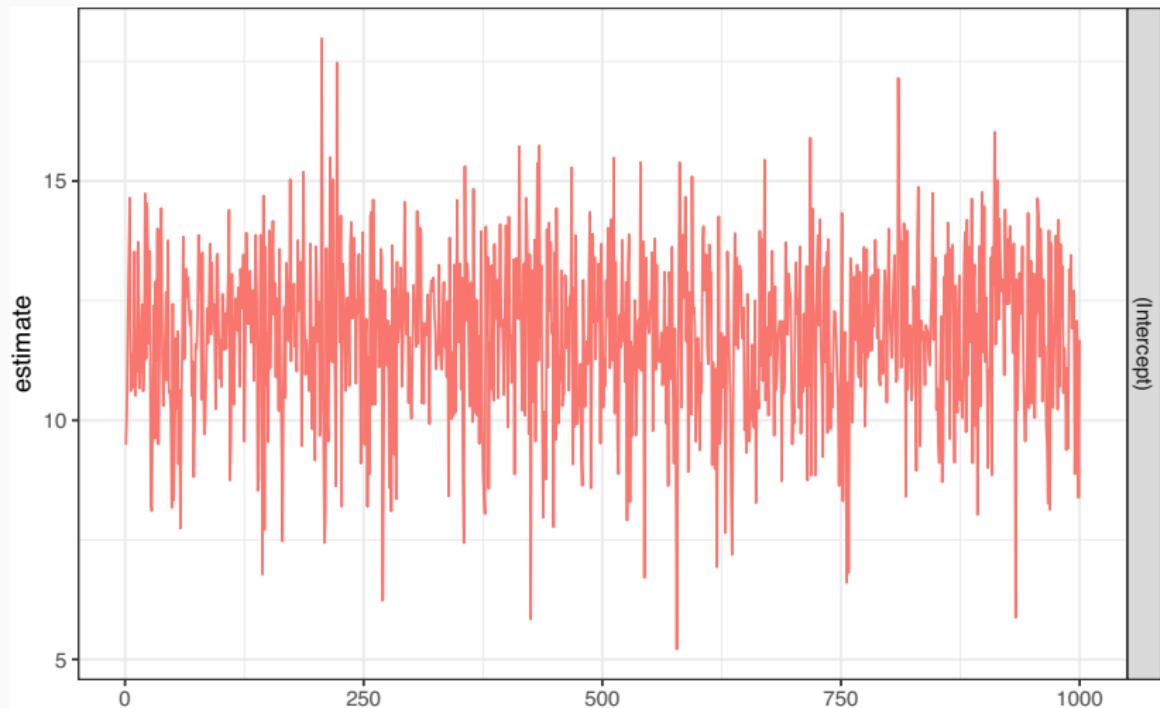
```
m = spBayes::spRecover(m, start=n_samp/2+1, thin = (n_samp/2)/1000)
## -----
##      Recovering beta and w
## -----
## Sampled: 99 of 1000, 9.90%
## Sampled: 199 of 1000, 19.90%
## Sampled: 299 of 1000, 29.90%
## Sampled: 399 of 1000, 39.90%
## Sampled: 499 of 1000, 49.90%
## Sampled: 599 of 1000, 59.90%
## Sampled: 699 of 1000, 69.90%
## Sampled: 799 of 1000, 79.90%
## Sampled: 899 of 1000, 89.90%
## Sampled: 999 of 1000, 99.90%
```

## Parameter values

```
m$p.theta.recover.samples %>%  
tidybayes::gather_samples(sigma.sq, tau.sq, phi) %>%  
ggplot(aes(x=.iteration, y=estimate, color=term)) +  
geom_line() +  
facet_grid(term~, scales = "free_y") +  
guides(color=FALSE)
```

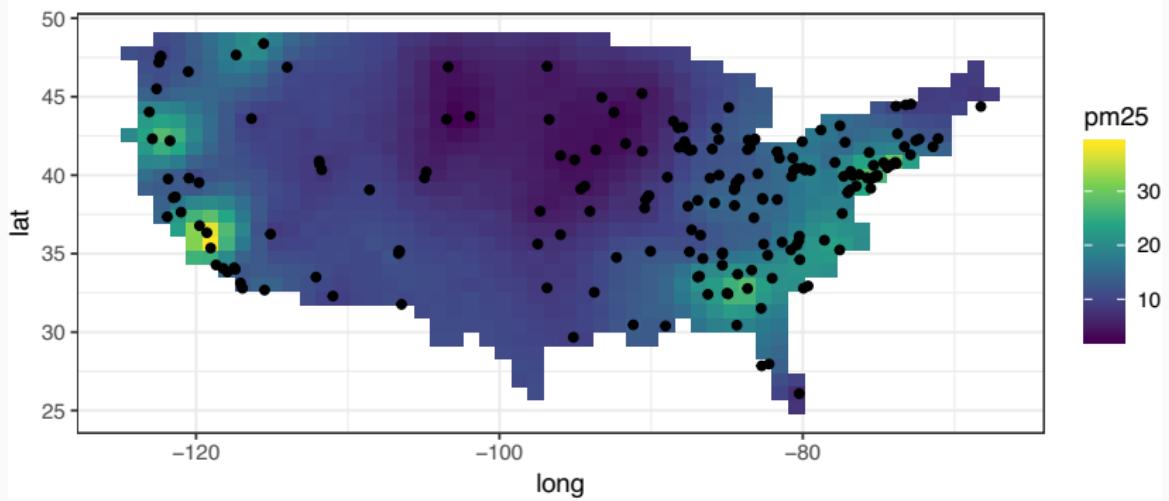
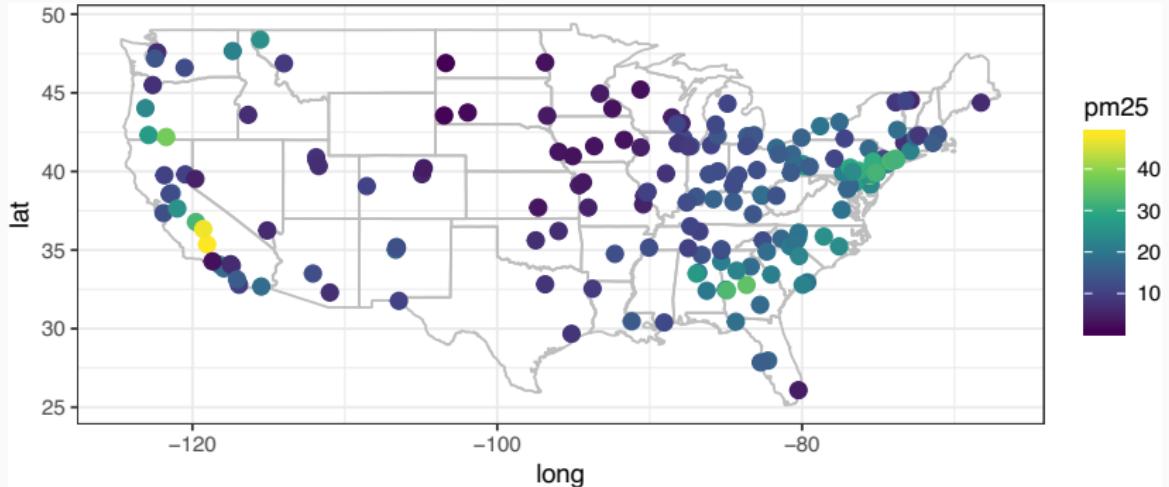


```
m$p.beta.recover.samples %>%
  tidybayes::gather_samples(`(Intercept)`) %>%
  ggplot(aes(x=.iteration, y=estimate, color=term)) +
  geom_line() +
  facet_grid(term~, scales = "free_y") +
  guides(color=FALSE)
```



# Predictions

```
m_pred = spBayes::spPredict(m, pred_coords, pred.covars = matrix(1, nrow=nrow(pred_coords)),
                           start=n_samp/2+1, thin=(n_samp/2)/1000)
## -----
## General model description
## -----
## Model fit with 191 observations.
##
## Prediction at 900 locations.
##
## Number of covariates 1 (including intercept if specified).
##
## Using the exponential spatial correlation model.
##
## -----
## Sampling
## -----
## Sampled: 100 of 1000, 9.90%
## Sampled: 200 of 1000, 19.90%
## Sampled: 300 of 1000, 29.90%
## Sampled: 400 of 1000, 39.90%
## Sampled: 500 of 1000, 49.90%
## Sampled: 600 of 1000, 59.90%
## Sampled: 700 of 1000, 69.90%
## Sampled: 800 of 1000, 79.90%
## Sampled: 900 of 1000, 89.90%
## Sampled: 1000 of 1000, 99.90%
m_pred_summary = post_summary(t(m_pred$p.y.predictive.samples))
```



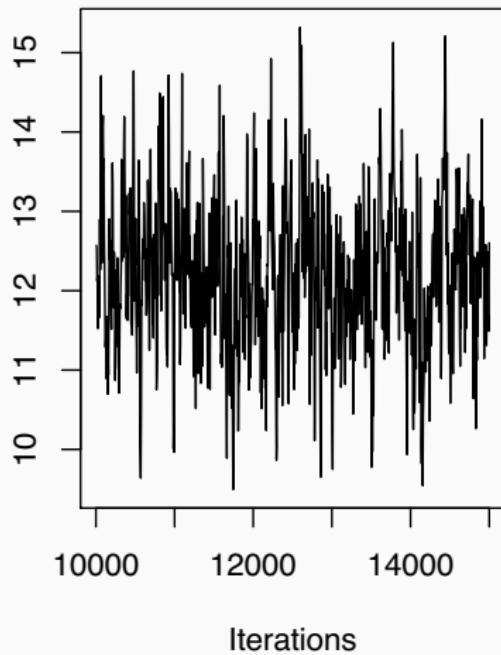
## JAGS Model

```
gplm = "model{
  for(i in 1:length(y)){
    y[i] ~ dnorm(beta + w[i], tau)
    mu_w[i] = 0
  }

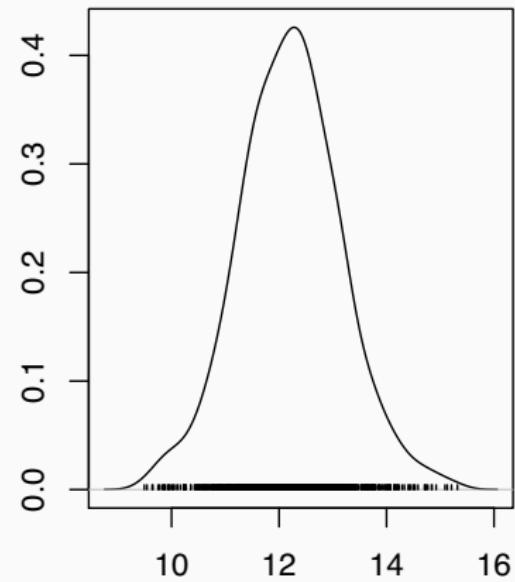
  for(i in 1:length(y)){
    for(j in 1:length(y)){
      Sigma_w[i,j] = sigma2_w * exp(-phi * d[i,j])
    }
  }
  w ~ dmnorm(mu_w, inverse(Sigma_w))

  beta ~ dnorm(0, 1/1000)
  sigma2_w ~ dgamma(2, 2)
  sigma2 ~ dgamma(2, 2)
  tau = 1/sigma2
  phi ~ dunif(3/14, 3/0.5)
}"
```

**Trace of beta**

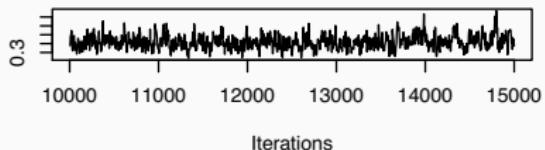


**Density of beta**

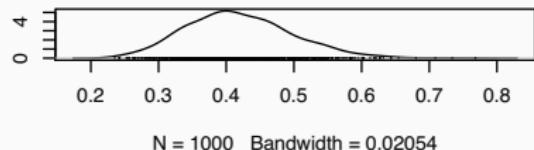


$N = 1000$  Bandwidth = 0.2477

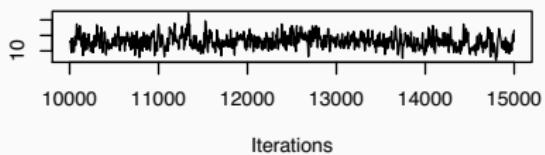
**Trace of phi**



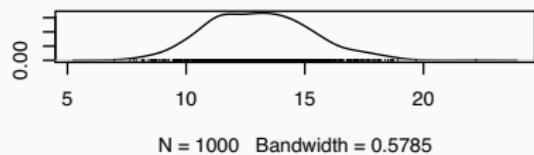
**Density of phi**



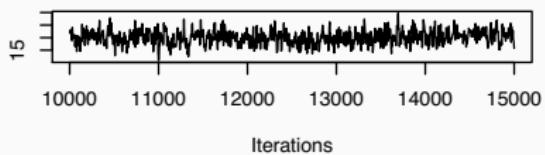
**Trace of sigma2**



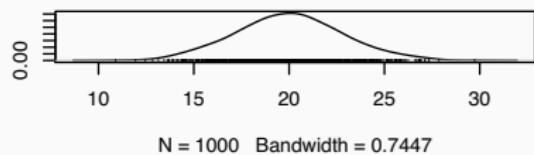
**Density of sigma2**



**Trace of sigma2\_w**



**Density of sigma2\_w**



# Comparing Model Results

