

①  
Correlation, Heteroscedasticity, GLS

H-tests, p-values, CIs, t-stats: rely on  $SE(\hat{\beta}_j)$

Recall,  $SE(\hat{\beta}_j) = SD(\hat{\beta}_j) = \left( V(\hat{\beta}_j) \right)^{1/2}$

How did we get  $V(\hat{\beta}_j)$ ?

Def:  $V(\hat{\beta}) = E[(\hat{\beta} - \beta)(\hat{\beta} - \beta)^T]$   
 $p \times 1 \quad 1 \times p$

$$\begin{aligned} \hat{\beta} &= (X^T X)^{-1} X^T y \\ &= (X^T X)^{-1} X^T [X\beta + \epsilon] \\ &= \beta + (X^T X)^{-1} X^T \epsilon \Rightarrow \hat{\beta} - \beta = (X^T X)^{-1} X^T \epsilon \end{aligned}$$

$$\begin{aligned} V(\hat{\beta}) &= E[(X^T X)^{-1} X^T \epsilon \epsilon^T X (X^T X)^{-1}] \\ &= (X^T X)^{-1} X^T E[\epsilon \epsilon^T] X (X^T X)^{-1} \\ &= (X^T X)^{-1} X^T V(\epsilon) X (X^T X)^{-1} \end{aligned}$$

Now recall, in the model  $\underset{n \times 1}{y} = \underset{n \times p}{X} \underset{p \times 1}{\beta} + \underset{n \times 1}{\epsilon}$ ,  $E(\epsilon) = 0$

Def:  $V(y) = E[(y - E(y))(y - E(y))^T]$   
 $= E[(y - X\beta)(y - X\beta)^T]$   
 $= E[\epsilon \epsilon^T]$   
 $= E[(\epsilon - 0)(\epsilon - 0)^T]$   
 $= V(\epsilon)$

so  $V(y) = V(\epsilon)$ .

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Up until now, we have assumed  $V(\epsilon) = \sigma^2 I \Rightarrow$  "iid errors"

$$V(\epsilon) = \sigma^2 I \Rightarrow V(\hat{\beta}) = (X^T X)^{-1} X^T (\sigma^2 I) X (X^T X)^{-1}$$

$$= \sigma^2 (X^T X)^{-1} X^T X (X^T X)^{-1}$$

$$= \underline{\underline{\sigma^2 (X^T X)^{-1}}}$$

If  $V(\epsilon) = \Sigma$

$$\left\{ \begin{array}{ll} \Sigma = \sigma^2 \begin{pmatrix} \rho_1^2 & \rho_1 \rho_2 & \dots & \rho_1 \rho_n \\ \rho_2 \rho_1 & \rho_2^2 & \dots & \rho_2 \rho_n \\ \vdots & \vdots & \ddots & \vdots \\ \rho_n \rho_1 & \rho_n \rho_2 & \dots & \rho_n^2 \end{pmatrix} & \text{autocorrelation} \\ \Sigma = \begin{pmatrix} v_1 & 0 & \dots & 0 \\ 0 & v_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & v_n \end{pmatrix} & v_i = f(x_i^T \beta) \quad \text{mean-var reln} \\ \Sigma = \sigma^2 \begin{pmatrix} 1/m_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1/m_n \end{pmatrix} & \text{different measurement variances.} \end{array} \right.$$

then in general,  $V(\hat{\beta}) = \underline{\underline{(X^T X)^{-1} (X^T \Sigma X) (X^T X)^{-1}}}$

How to get standard errors?

- 1) estimate  $\Sigma$  somehow from  $\hat{\epsilon} = y - \hat{y}$  (will depend on covariance model)
- 2) Compute  $\hat{V}(\hat{\beta}) = (X^T X)^{-1} X^T \hat{\Sigma} X (X^T X)^{-1}$
- 3) obtain  $\underline{\underline{SE(\hat{\beta}_j) = (\hat{V}(\hat{\beta})_{jj})^{1/2}}}$

Typically, need to do this "by hand".

Generalized least squares (includes weighted least squares)

An aside:

$$\text{if } V(\underset{\wedge \text{ scalar}}{\underline{\epsilon}}) = \sigma^2, \quad V((\sigma^2)^{-1/2} \underline{\epsilon}) = V(\underline{\epsilon}/\sigma)$$
$$= \frac{1}{\sigma^2} \sigma^2 = 1$$

similarly, if  $V(\underline{\underline{\epsilon}}) = \Sigma,$   $V(\Sigma^{-1/2} \underline{\underline{\epsilon}}) = \Sigma^{-1/2} \Sigma \Sigma^{-1/2}$

$$= \underline{\underline{I}}$$

$$Z = X\beta + \epsilon \quad \epsilon \sim N$$

$$\Sigma^{-1/2} y = \Sigma^{-1/2} X \beta + \Sigma^{-1/2} \epsilon$$

$$\tilde{y} = \tilde{X}\beta + \tilde{e}, \quad E[\tilde{e}] = 0, \quad V(\tilde{e}) = V(\Sigma^{-1/2}e) = I$$

OLS estimate based on  $\tilde{y}, \tilde{x}$  is

$$\begin{aligned}\hat{\beta} &= (\tilde{X}^T \tilde{X})^{-1} \tilde{X}^T \tilde{y} \\ &= (X^T \Sigma^{-1/2} \Sigma^{-1/2} X)^{-1} X^T \Sigma^{-1/2} \Sigma^{-1/2} y \\ &= \underline{(X^T \Sigma^{-1} X)^{-1} X^T \Sigma^{-1} y} = \underline{\underline{\hat{\beta}_{GLS}}}\end{aligned}$$

$\hat{\beta}_{GLS}$  is the generalized least-squares estimator of  $\beta$ .

Note: ① if  $\Sigma = I \sigma^2$ ,  $\hat{\beta}_{GLS} = \hat{\beta}_{OLS}$

if  $\Sigma \neq I_{\sigma^2}$ ,  $\hat{\beta}_{GLS} \neq \hat{\beta}_{OLS}$

②  $V(\hat{\beta}_{OLS}) \geq V(\hat{\beta}_{GLS})$  in general,  $\hat{\beta}_{GLS}$  is the BLUE  
"best linear unbiased estimator"