

SVD

Orthogonality: Let $U = (u_1 \dots u_k) \in \mathbb{R}^{m \times k}$

$u_1 \dots u_k$ are orthogonal $u_i^T u_j = 0$ for $i \neq j \Leftrightarrow U^T U$ is diagonal

$u_1 \dots u_k$ are orthonormal $u_i^T u_j = 0$ $i \neq j$ $\Leftrightarrow U^T U = I$
 $u_i^T u_i = 1$

Historically:

Def: $U = (u_1 \dots u_m) \in \mathbb{R}^{m \times m}$ is orthogonal if $u_1 \dots u_m$ are orthonormal

Notation: $U \in O_m$

For this class:

Def: $U = (u_1 \dots u_m) \in \mathbb{R}^{m \times k}$ is an "orthonormal matrix" if $u_1 \dots u_m$ are orthonormal.
 $U \in \mathcal{V}_{k,m}$ (the Stiefel manifold)

$\Rightarrow$ a square orthonormal matrix is an orthogonal matrix.
 $\Rightarrow \mathcal{V}_{m,m} = O_m$

Thm: If $U_1 \in \mathbb{R}^{m \times r}$ is orthonormal, there exists $U_2 \in \mathbb{R}^{m \times (m-r)}$ orthonormal such that $U = (U_1, U_2)$ is orthogonal, i.e.

$$U^T U = \begin{bmatrix} u_1^T \\ \vdots \\ u_r^T \\ u_{r+1}^T \\ \vdots \\ u_m^T \end{bmatrix} \begin{bmatrix} u_1 & \dots & u_r & u_{r+1} & \dots & u_m \end{bmatrix} = \begin{bmatrix} I_r & 0 \\ 0 & I_{m-r} \end{bmatrix}$$

Interpretation

$U_1 \in \mathcal{V}_{r,m}$ defines an orthonormal basis for an r -dim subspace of $\mathbb{R}^m$
 $= \text{Col}(U_1) = \{x \in \mathbb{R}^m : x = a_1 u_1 + \dots + a_r u_r\}$
 $= \{x \in \mathbb{R}^m : x = U_1 a\}$

U_2 def orth basis for null space of $\text{Col}(U_1)$

$$\text{tr}(AB) = \text{tr}(BA) = \text{tr}(A^T B)$$

Norms:

(Frobenius) Norm: for $X \in \mathbb{R}^{m \times n}$, $\|X\|_F = \|X\| = \left(\sum_i \sum_j x_{ij}^2 \right)^{1/2}$

$$\|X\|^2 = \text{tr}(X^T X) = \text{tr}(X X^T)$$

if $n=1$, $X \in \mathbb{R}^{m \times 1}$ is a vector,

$$\|X\|_F^2 = \sum x_i^2 = X^T X : \left(\text{tr}(X X^T) = \text{tr}(X^T X) = X^T X \right)$$

Vector norm: for $X \in \mathbb{R}^{m \times n}$, $\|X\|_V = \max_{u \in \mathbb{R}^n: u^T u = 1} \|X u\|_F = \max_{u \in \mathbb{R}^n: u^T u = 1} (u^T X^T X u)^{1/2}$

$$= \max_{z \in \mathbb{R}^n} \frac{\|X z\|_F}{\|z\|_F}$$

for $X^T \in \mathbb{R}^{1 \times n}$, $\max_{z \in \mathbb{R}^n} \frac{\|X^T z\|_F}{\|z\|_F} = \max_{z \in \mathbb{R}^n} \left[\frac{(X^T z)^T z}{z^T z} \right]^{1/2} = (X^T X)^{1/2}$

$$x \in \text{Col}(U_1) \Rightarrow x = U_1 a$$

$$\text{Ex: Let } y \in \text{Col}(U_2) \Rightarrow y = U_2 b$$

$$\text{then } x^T y = a^T U_1^T U_2 b = a^T 0 b = 0$$

$= \dots \dots \dots r \times (m-r)$

$U = [U_1 \ U_2]$ is called an orthonormal basis for $\mathbb{R}^m$

Norms + Rotations

Def: The (F) norm of a vector $x \in \mathbb{R}^n$ is $\|x\| = (x^T x)^{1/2} = \left(\sum_{i=1}^n x_i^2 \right)^{1/2}$

Def: The (F) norm of a matrix $X \in \mathbb{R}^{n \times n}$ is $\|X\| = \left(\sum_{i,j} x_{ij}^2 \right)^{1/2} = \text{tr}(X^T X)^{1/2} = \text{tr}(X X^T)^{1/2}$

(for diagonal A , $\text{tr}(A) = \sum_{i=1}^n a_{ii}$)

The (F) norm of a matrix is sometimes called the "Frobenius norm".

Rotations: A rotation (or rot + ref) of a vector $x \in \mathbb{R}^n$ is a multiplication of x by an orthogonal matrix

$$Ux \text{ is a rotation of } x \text{ if } U \in O(n)$$

Rotations for matrices

$$\text{Let } A \in \mathbb{R}^{m \times n}$$

$$U \in O^m$$

$$V \in O^n$$

$$UA = U \begin{pmatrix} a_1 & a_2 & \dots & a_n \end{pmatrix} = (Ua_1 \ \dots \ Ua_n)$$

(rotation on the left rotates columns of A)

$$AV^T = \begin{pmatrix} a_1^T \\ \vdots \\ a_m^T \end{pmatrix} V^T = \begin{pmatrix} a_1^T V^T \\ \vdots \\ a_m^T V^T \end{pmatrix} = \begin{pmatrix} (Va_1)^T \\ \vdots \\ (Va_m)^T \end{pmatrix}$$

(rotation on right rotates the rows of A)

$$\tilde{Y} = U Y V^T$$

$$\begin{aligned} \|\tilde{Y}\|_V^2 &= \sup_{w: w^T w = I} \|U Y V^T w\|_F^2 = \sup_{w: w^T w = I} \text{tr}(U Y V^T w w^T V Y^T U^T) \\ &= \sup_{w: w^T w = I} \text{tr}(Y^T Y V^T w w^T V) \\ &= \sup_{w: w^T w = I} \text{tr}(Y^T Y \tilde{w} \tilde{w}^T) \\ &= \sup_{w: w^T w = I} \text{tr}(Y^T Y w w^T) \\ &= \sup_{w: w^T w = I} \text{tr}((Yw)^T (Yw)) \\ &= \sup_{w: w^T w = I} \|Yw\|_F^2 = \|Y\|_V^2 \end{aligned}$$

$$\|Y_{-1} \begin{pmatrix} d_1 \\ w \end{pmatrix}\| \geq d_1^2 + w^T w = (d_1^2 + w^T w)^{1/2} \left\| \begin{pmatrix} d_1 \\ w \end{pmatrix} \right\|$$

$$\frac{\|Y_{-1} \begin{pmatrix} d_1 \\ w \end{pmatrix}\|}{\left\| \begin{pmatrix} d_1 \\ w \end{pmatrix} \right\|} \geq (d_1^2 + w^T w)^{1/2} \geq d_1$$

as $Y_{-1} = U Y V$
Norm is invariant to rot.

$$\rightarrow \sup_{v^T v = I} \|Y_{-1} v\| \geq (d_1^2 + w^T w)^{1/2} \geq d_1 = \sup_{v^T v = I} \|Y v\| = \sup_{v^T v = I} \|Y_{-1} v\|$$

$$\rightarrow \underline{w = 0}$$

Norms under rotations

Norm preserved under Rotation

Let $\hat{x} = Ux$, $x \in \mathbb{R}^m$. Then $\|\hat{x}\|^2 = \hat{x}^T \hat{x} = x^T U^T U x = x^T x = \|x\|^2$

Let $\tilde{Y} = UYV^T$, Then $\|\tilde{Y}\|^2 = \text{tr}(\tilde{Y}\tilde{Y}^T)$
 $= \text{tr}(UYV^T V Y^T U^T)$
 $= \text{tr}(UY Y^T U^T)$
 $= \text{tr}(U^T U Y Y^T) = \text{tr}(Y Y^T) = \|Y\|^2$

Singular Value Decomposition

Then: for $Y \in \mathbb{R}^{m \times n}$, $m \geq n$, $\exists U \in \mathcal{O}_m$, $V \in \mathcal{O}_n$, $D \in \mathcal{D}(m)$ s.t.

$$Y = U D V^T$$

Pf (Golub + van Loan, p. 70)

Let $V_1 = \arg \min_{V \in \mathbb{R}^n: V^T V = I} \|YV\|$, let $d_1 = \|YV_1\|$

Then $YV_1 = d_1 U_1$ for some $U_1 \in \mathbb{R}^m: U_1^T U_1 = I$

$\rightarrow$ let $U = (U_1, U_2) \in \mathcal{O}(m)$
 $V = (V_1, V_2) \in \mathcal{O}(n)$

then $U^T Y V = \begin{pmatrix} U_1^T Y V_1 & \overbrace{U_1^T Y V_2}^{w^T} \\ \underbrace{U_2^T Y V_1}_B & \underbrace{U_2^T Y V_2}_B \end{pmatrix} = Y_1$

now $U_1^T Y V_1 = U_1^T (d_1 U_1) = d_1$
 $U_2^T Y V_1 = U_2^T (d_1 U_1) = 0$

Claim: $U_1^T Y V_2 = 0$: Pf: $\|Y_1 \begin{pmatrix} d_1 \\ w \end{pmatrix}\| = \left\| \begin{pmatrix} d_1 & w^T \\ 0 & B \end{pmatrix} \begin{pmatrix} d_1 \\ w \end{pmatrix} \right\|$
 $\left\| \begin{pmatrix} d_1^2 + w^T w \\ B w \end{pmatrix} \right\| \geq d_1^2 + w^T w$

$$\|Y\|_V^2$$

$$\|Y_{-1}\|_V^2$$

$$\|Y_{-1} \begin{pmatrix} d_1 \\ w \end{pmatrix}\|^2 \geq d_1^2 + w^T w \geq d_1^2 = \sup_{v: v^T v = 1} \|Y v\|^2 = \sup_{v: v^T v = 1} \|Y_{-1}\|^2$$

$$\rightarrow u = \underline{0}$$

$$\rightarrow U^T Y V = \begin{pmatrix} d_1 & 0 \\ 0 & Y'_{-1} \end{pmatrix} \rightarrow Y = U \begin{bmatrix} d_1 & 0 \\ 0 & Y'_{-1} \end{bmatrix} V^T$$

$$\text{now repeat argument on } Y'_{-1} \rightarrow Y = U \begin{bmatrix} d_1 & 0 \\ 0 & \tilde{U} \begin{pmatrix} d_2 & 0 \\ 0 & Y'_{-2} \end{pmatrix} \tilde{V}^T \end{bmatrix} V^T$$

$$= U \begin{bmatrix} 1 & 0 \\ 0 & \tilde{U} \end{bmatrix} \begin{bmatrix} d_1 & 0 \\ 0 & \begin{bmatrix} d_2 & 0 \\ 0 & \tilde{U} \end{bmatrix} \end{bmatrix} \begin{bmatrix} V \begin{bmatrix} 1 & 0 \\ 0 & \tilde{V} \end{bmatrix} \end{bmatrix}^T$$

$\in \mathcal{O}(m)$ $\in \mathcal{O}(n)$

Uniqueness: The representation is not unique Why?

$$\left(\begin{aligned} Y &= U D V^T = U P^T P D P^T P V^T = \tilde{U} \tilde{D} \tilde{V}^T, \text{ where } P = \text{permutation matrix} \\ &= U S S D S S V^T = \hat{U} \tilde{D} \hat{V}^T, \text{ where } S = \text{diag}(\pm 1) \end{aligned} \right)$$

for $Y \in \mathbb{R}^{m \times n}$ The ^(thin) SVD of Y is the triple (U, D, V) where
 $m \geq n$ $Y = U D V^T$
 $U \in \mathbb{R}^{m \times n}$
 $V \in \mathbb{R}^{n \times n}$
 $D = \text{diag}(d_1, \dots, d_n), \quad d_1 \geq d_2 \geq \dots \geq d_n \geq 0$

$U = (u_1, \dots, u_n)$ are the left singular vectors

$V = (v_1, \dots, v_n)$ are the right singular vectors

$d_1, \dots, d_n$ are the singular values.