

(1)

Multilinear Models

Multivariate linear model:

$$y_i = Bx_i + \Sigma^{1/2}z_i, z_1, \dots, z_n \sim N(0, I_p)$$

$B \in \mathbb{R}^{p \times q}$, $\Sigma \in \mathbb{R}^q$ unknown, $x_1, \dots, x_n \in \mathbb{R}^q$ observed

$$\Rightarrow y_i \sim N(Bx_i, \Sigma) \quad y_1, \dots, y_n \text{ indep.}$$

Matrix form: $Y = \begin{pmatrix} y_1^T \\ \vdots \\ y_n^T \end{pmatrix} = \begin{pmatrix} x_1^T B^T \\ \vdots \\ x_n^T B^T \end{pmatrix} + \begin{pmatrix} z_1^T \Sigma^{1/2} \\ \vdots \\ z_n^T \Sigma^{1/2} \end{pmatrix}$

$$= \begin{pmatrix} x_1^T \\ \vdots \\ x_n^T \end{pmatrix} B^T + \begin{pmatrix} z_1^T \\ \vdots \\ z_n^T \end{pmatrix} \Sigma^{1/2}$$

$$Y = X B^T + Z \Sigma^{1/2}$$

Model Extensions: Addit. func $Y = A w^T + X B^T + \Sigma^{1/2} E + Z \Sigma^{1/2}$

Multiplicative $Y = A X B^T + \Sigma^{1/2} Z \Sigma^{1/2}$

Reps : $y_i = A x_i B^T + \Sigma^{1/2} z_i \Sigma^{1/2} \quad i=1, \dots, n$
independently

Extending to tensors: Matrices $E(Y) = A X B^T =$



(2)

Vec & Kronecker product

$$Y = \underset{n \times q}{XB} + \underset{q \times p}{Z\Sigma^{1/2}}$$

(note writing as XB , not XB^T)

$$\text{ut } y = \text{vec}(Y) = \begin{bmatrix} y_{11} \\ y_{21} \\ \vdots \\ y_{n1} \\ y_{12} \\ \vdots \\ y_{n2} \\ \vdots \\ y_{1p} \\ \vdots \\ y_{np} \end{bmatrix} \quad \left. \begin{array}{l} \text{1st col} \\ \text{2nd col} \\ \vdots \\ \text{pth col} \end{array} \right\}$$

$$\text{vec}(XB) = \begin{bmatrix} x_1^T b_1 \\ x_2^T b_1 \\ x_3^T b_1 \\ \vdots \\ x_p^T b_1 \\ \vdots \\ x_n^T b_p \end{bmatrix} = \begin{bmatrix} x_1^T & 0 & 0 & 0 \\ x_2^T & 0 & \cdots & - \\ x_3^T & 0 & 0 & \cdots \\ \vdots & \vdots & \vdots & \vdots \\ 0 & x_1^T & 0 & 0 \\ 0 & x_2^T & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & x_n^T & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \\ x_1^T & & & x_1^T \\ x_2^T & & & x_2^T \\ x_3^T & & & x_3^T \\ \vdots & & & \vdots \\ x_p^T & & & x_p^T \\ \vdots & & & \vdots \\ x_n^T & & & x_n^T \end{bmatrix} \begin{bmatrix} b_{11} \\ b_{12} \\ \vdots \\ b_{1p} \\ \vdots \\ b_{p1} \\ \vdots \\ b_{pp} \end{bmatrix}$$

$$= (I \otimes X) \text{vec}(B)$$

Def (Kronecker Product) for $A \in \mathbb{R}^{n_1 \times p_1}$, $B \in \mathbb{R}^{n_2 \times p_2}$ then

$$A \otimes B = \begin{bmatrix} a_{11}B & a_{12}B & \dots & a_{1p_1}B \\ a_{21}B & \ddots & \ddots & a_{2p_1}B \\ \vdots & \ddots & \ddots & \ddots \\ a_{n_11}B & a_{n_12}B & \dots & a_{n_1p_1}B \end{bmatrix} \in \mathbb{R}^{n_1 n_2 \times p_1 p_2}$$

Thm (vec-Kronecker Identity)

$$\text{vec}(AXB^T) = (B \otimes A)x, \quad x = \text{vec}(X)$$

Tricks: $\text{vec}(AB) = \text{vec}(A B I) = (I \otimes A) \text{vec}(B)$
 $= \text{vec}(I A B) = (B^T \otimes I) \text{vec}(A)$

Demo: OLS MV Regression estimator:

find B to minimize $\|Y - XB^T\|^2$ $b = \text{vec}(B^T)$

$$\|y - (I \otimes x)b\|^2$$

$n_p \times 1$

$$= y^T y - 2 b^T (I \otimes x)^T y + b^T (I \otimes x)^T (I \otimes x) b$$

Identity: $(A \otimes B)^T = (A^T \otimes B^T)$ $\hookrightarrow y^T y - b^T (I \otimes x^T) y + b^T (I \otimes x^T x) b$
 $(A \otimes B)(C \otimes D) = (AC \otimes BD)$

Minimize w.r.t. b : $\frac{\partial}{\partial b} \quad = -2(I \otimes x^T) y + 2(I \otimes x^T x) b$

$$\hat{b} = (I \otimes x^T x)^{-1} (I \otimes x^T) y$$

$$= (I \otimes (x^T x)^{-1}) (I \otimes x^T) y$$

Identity
 $(A \otimes B)^{-1} = (A^{-1} \otimes B^{-1})$ $\therefore (I \otimes (x^T x)^{-1} x^T) y$

$$\hat{b} = (I \otimes (x^T x)^{-1} x^T) y \Rightarrow \hat{B}^T = (x^T x)^{-1} x^T Y$$

$$\hat{B} = Y^T K (x^T x)^{-1}$$

$p \times q$

Exercise: Find MLE of B for case $y_i \sim N_p(Bx_i, \Sigma)$, Σ known.

i.e. minimize $\| (Y - XB^T) \Sigma^{-1} \|$

Kronecker Covariance

Let $y_1, \dots, y_n \sim \text{iid } N_p(0, \Sigma)$

Then $y_i = \Sigma^{1/2} z_i$ $z_1, \dots, z_n \sim \text{iid } N(0, I)$

$$Y = Z \Sigma^{1/2} \quad \{z_{ij}\} \sim \text{iid } N(0, 1)$$

Covariance of Y : Intuitively, $\text{Cov}(y_{ij}, y_{i'j'}) = \sigma_{jj'}$, $\text{Cov}(y_{ij}, y_{i'j'}) = 0$

Cov of $\text{vec}(Y)$: $\text{vec}(Y) = y = (\Sigma^{1/2} \otimes I) z$, $z = \text{vec}(Z)$

$$\begin{aligned} E[y] &= 0, \text{ so } \text{Cov}(y) = E[yy^T] \\ &= E[(\Sigma^{1/2} \otimes I) z z^T (\Sigma^{1/2} \otimes I)] \end{aligned}$$

$$\begin{aligned} &= (\Sigma^{1/2} \otimes I) E(z z^T) (\Sigma^{1/2} \otimes I) \\ &= (\Sigma^{1/2} \otimes I) (\Sigma^{1/2} \otimes \Sigma) \\ &= \underbrace{\Sigma \otimes I}_{\text{row covariance}} \quad \underbrace{\Sigma \otimes I}_{\text{column covariance}} \end{aligned}$$

$$\Rightarrow \text{Cov} \left(\begin{array}{c} y_{11} \\ y_{12} \\ y_{13} \\ \vdots \\ y_{1n} \\ \vdots \\ y_{np} \end{array} \right) = \Sigma \otimes I = \left[\begin{array}{cc} \sigma_{11} I & \sigma_{12} I \\ \sigma_{21} I & \sigma_{22} I \\ \vdots & \vdots \end{array} \right]$$

Row + Column covariance:

$$Y = \Psi^{1/2} Z \Sigma^{1/2}, \quad \Psi \in \mathcal{S}_n^+, \quad \Sigma \in \mathcal{S}_p^+$$

What is $\text{Cov}(y_{ij}, y_{i'j'})$?

$$\text{Let } \gamma = \text{vec}(Y), \text{ so } \gamma = (\Sigma^{1/2} \otimes \Psi^{1/2}) z$$

$$\begin{aligned} C(\gamma) &= E(\gamma\gamma^T) = (\Sigma^{1/2} \otimes \Psi^{1/2}) E(zz^T) (\Sigma^{1/2} \otimes \Psi^{1/2}) \\ &= (\Sigma^{1/2} \otimes \Psi^{1/2}) (\Sigma^{1/2} \otimes \Psi^{1/2}) \\ &\stackrel{*}{=} \Sigma \otimes \Psi \end{aligned}$$

$$= \begin{bmatrix} \sigma_{11} \Psi & \sigma_{12} \Psi \\ \sigma_{21} \Psi & \ddots \\ & \ddots \\ & & \sigma_{pp} \Psi \end{bmatrix}$$

$$\rightarrow \text{Cov}(y_{ij}, y_{i'j'}) = \Psi_{ii'} \sigma_{jj'}$$

Ψ represents covariance of the rows

Σ represents covariance of the columns

Kronecker / Separable / Multilinear Covariance model

If Z is normal, sometimes called "matrix normal mode" (David 19..)
but this isn't a great name.

$$\text{Note (Nonidentifiability)} \quad \Psi \otimes \Sigma = (\Psi/a) \otimes (a\Sigma)$$

so scales of Ψ, Σ not separably identifiable.

Estimation: First consider moments, MLE, then Bayes

Observe $Y \sim N_{n,p}(0, \Sigma \otimes \Psi)$. Goal: estimate Σ, Ψ or $\Sigma \otimes \Psi$.

Moment estimators: "Typical" estimator of Σ is $Y^T Y / n$

$$\text{Recall } Y = \Psi^{1/2} Z \Sigma^{1/2}, \quad E[Y^T Y] = E[\Sigma^{1/2} Z^T \Psi^{-1} \Psi Z \Sigma^{1/2}] \\ = \Sigma^{1/2} E[Z^T \Psi Z] \Sigma^{1/2}$$

Exercise: Show $E[Z^T \Psi Z] = I \times \text{tr}(\Psi)$

$$\text{so } E[Y^T Y] = \Sigma^{1/2} (I \times \text{tr}(\Psi)) \Sigma^{1/2} = \Sigma \times \text{tr}(\Psi) \underset{\text{scale}}{\sim}$$

Exercise: Show $E[YY^T] = 2 \times \text{tr}(\Sigma)$

so: $Y^T Y$ is an unbiased est of Σ (up to scale)
 YY^T " " "

However: $YY^T \in \mathbb{R}^{n \times n}$, but $\text{rank}(YY^T) = p!$

Related to this, $\log p(Y | \Sigma, \Psi)$ is unbounded in (Σ, Ψ)
(unless $n=p$)

\Rightarrow No MLE

Need a proper prior to do Bayes inference.

(7)

Replications: Suppose $y_1, \dots, y_r \sim_{iid} N_{np}(0, \Sigma \Psi)$

What is the likelihood?

$$y_1, \dots, y_r \sim_{iid} N_{np}(0, \Sigma \Psi) \Rightarrow$$

$$p(y_1, \dots, y_r) \propto |\Sigma \Psi|^{-r/2} \exp\left\{-\frac{1}{2} \sum_{i=1}^r y_i^\top (\Sigma \Psi)^{-1} y_i\right\}$$

$$\text{Identity: } |A \otimes B| = |A|^n |B|^p$$

$$\begin{aligned} \text{Also, } y_i^\top (\Sigma \Psi)^{-1} y_i &= y_i^\top (\Sigma^{-1/2} \Psi^{-1/2}) (\Sigma^{-1/2} \Psi^{-1/2}) y_i \\ &= \|(\Sigma^{-1/2} \Psi^{-1/2}) y_i\|^2 \\ &= \|Y^{-1/2} Y \Sigma^{-1/2}\|^2 \\ &= \text{tr}((Y^{-1/2} Y \Sigma^{-1/2})(\Sigma^{-1/2} Y^\top \Psi^{-1/2})) \\ &= \text{tr}(Y^{-1/2} \Psi \Sigma^{-1} Y \Psi^{-1/2}) \\ &= \text{tr}(Y^\top \Sigma^{-1} Y) \end{aligned}$$

$$p(y_1, \dots, y_r | \Sigma, \Psi) \propto |\Sigma|^{-\frac{n+r}{2}} |Y|^{-\frac{pr}{2}} \text{etr}\left(-\frac{1}{2} \sum_{i=1}^r Y_i^\top \Sigma^{-1} Y_i\right)$$

Iterative estimation:

$$p(Y_1, \dots, Y_n | \Sigma, \Psi) \propto |\Sigma|^{-\frac{n+r}{2}} \text{etr}(-\tilde{\Sigma}^\top S_\Sigma), \quad S_\Sigma = \sum_{i=1}^r Y_i^\top \Psi^{-1} Y_i$$

\Rightarrow optimizer in Σ is $\tilde{\Sigma} = S_\Sigma / nr$, ^{total # of rows}

\Rightarrow $C_i R_i$ is prop. to inverse-wishart dist in Σ

$$p(Y_1, \dots, Y_n | \Sigma, \Psi) \propto |Y|^{-\frac{pr}{2}} \text{etr}(-Y^\top S_\Psi / 2), \quad S_\Psi = \sum_{i=1}^r Y_i^\top \Sigma^{-1} Y_i$$

\Rightarrow optimizer in Ψ is $\hat{\Psi} = S_\Psi / pr$, ^{total # of cols}

\Rightarrow $C_i R_i$ is prop. to inv. wish. dist in Ψ .

Comments:

* MLE via block coordinate descent ("flip flop algorithm")

$$\tilde{\boldsymbol{\gamma}} = \frac{1}{pr} \sum_{i=1}^r \underbrace{\mathbf{Y}_i \Sigma^{-1} \mathbf{Y}_i^\top}_{\text{n} \times \text{n}} \quad \text{is generally of rank pr}$$

will need $pr \geq n$ for $\tilde{\boldsymbol{\gamma}}$ to have an inverse
 $r \geq n/p$ (needed to update Σ).

However: $r = n/p$ is not generally enough to guarantee var. is bounded

$r \geq n+p$ is, but results for $\frac{1}{p} < r < n+p$ are available
 (see, e.g. Røis et al. 2016 JMV)

* Bayes: No sample size limitations if proper priors are used.

* Reduced models: y_{ij} = observation of variable j at time i

$$\Rightarrow \text{may restrict } \boldsymbol{\gamma} = \boldsymbol{\gamma}(\boldsymbol{\theta}) = \begin{bmatrix} 1 & e & e^2 & \dots \\ p & 1 & p & \\ e^2 & e & 1 & \\ \vdots & & & \end{bmatrix}$$

In this case, MLEs may exist,
 but estimation procedure is a bit
 more complicated.