

Mixtures of Prior Distributions

Hoff Chapter 9, Liang et al 2007, Hoeting et al (1999), Clyde
& George (2004)

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Bartlett's Paradox

The Bayes factor for comparing \mathcal{M}_γ to the null model:

$$BF(\mathcal{M}_\gamma : \mathcal{M}_0) = (1 + g)^{(n-1-p_\gamma)/2} (1 + g(1 - R_\gamma^2))^{-(n-1)/2}$$

For $g \rightarrow \infty$, the $BF \rightarrow 0$ for fixed n and R_γ^2

Increasing vagueness in the prior leads to BF favoring the null model!

Information Paradox

The Bayes factor for comparing \mathcal{M}_γ to the null model:

$$BF(\mathcal{M}_\gamma : \mathcal{M}_0) = (1 + g)^{(n-1-p_\gamma)/2} (1 + g(1 - R^2))^{-(n-1)/2}$$

- ▶ Let g be a fixed constant and take n fixed.
- ▶ Let $F = \frac{R_\gamma^2 / p_\gamma}{(1 - R_\gamma^2) / (n - 1 - p_\gamma)}$
- ▶ As $R_\gamma^2 \rightarrow 1$, $F \rightarrow \infty$ LR test would reject \mathcal{M}_0 where F is the usual F statistic for comparing model \mathcal{M}_γ to \mathcal{M}_0
- ▶ BF converges to a fixed constant $(1 + g)^{-p_\gamma/2}$ (does not go to infinity)

“Information Inconsistency” see Liang et al JASA 2008

Mixtures of g priors & Information consistency

Need $BF \rightarrow \infty$ if $R^2 \rightarrow 1 \Leftrightarrow E_g[(1 + g)^{(n-1-p_\gamma)/2}]$ diverges (proof in Liang et al)

- ▶ Zellner-Siow Cauchy prior
- ▶ hyper- g prior (Liang et al JASA 2008)

$$p(g) = \frac{a-2}{2}(1+g)^{-a/2}$$

or $g/(1+g) \sim \text{Beta}(1, (a-2)/2)$ need $2 < a \leq 3$

- ▶ Hyper- g/n ($g/n)(1+g/n) \sim (\text{Beta}(1, (a-2)/2)$
- ▶ Jeffreys prior on g corresponds to $a = 2$ (improper)
- ▶ robust prior (Bayarri et al Annals of Statistics 2012)
- ▶ Intrinsic prior (Womack et al JASA 2015)

All have prior tails for β that behave like a Cauchy distribution and (the latter 4) marginal likelihoods that can be computed using special hypergeometric functions (${}_2F_1$, Appell F_1)

Desiderata - Bayarri et al 2012 AoS

- ▶ Proper priors on non-common coefficients
- ▶ If LR overwhelmingly rejects a model, Bayesian should also reject
- ▶ Selection Consistency: large samples probability of the true model goes to one.
- ▶ Intrinsic prior consistency (prior converges to a fixed proper prior as $n \rightarrow \infty$)
- ▶ Invariance (invariance under scale/location changes of data/model leads to $p(\beta_0, \phi) \propto 1/\phi$); other group invariance, rotation invariance.
- ▶ predictive matching: predictive distributions match under minimal sample sizes so that $BF = 1$

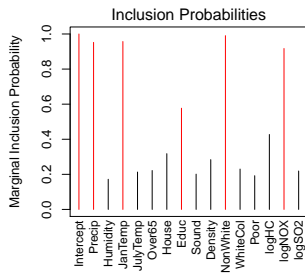
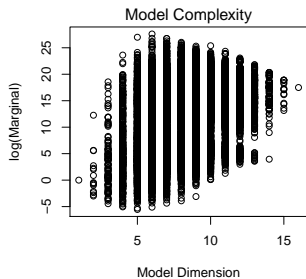
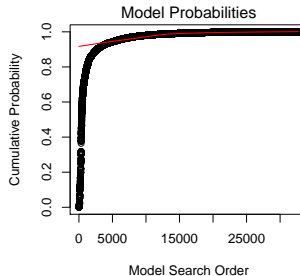
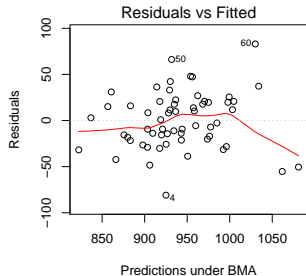
Mixtures of g priors like Zellner-Siow, hyper-g-n, robust, intrinsic

Mortality & Pollution

- ▶ Data from Statistical Sleuth 12.17
- ▶ 60 cities
- ▶ response Mortality
- ▶ measures of HC, NOX, SO2
- ▶ Is pollution associated with mortality after adjusting for other socio-economic and meteorological factors?
- ▶ 15 predictor variables implies $2^{15} = 32,768$ possible models
- ▶ Use Zellner-Siow Cauchy prior $1/g \sim G(1/2, n/2)$

```
mort.bma = bas.lm(MORTALITY ~ ., data=mortality,  
                  prior="ZS-null",  
                  alpha=60, n.models=2^15,  
                  update=100, initprobs="eplogp")
```

Posterior Distributions



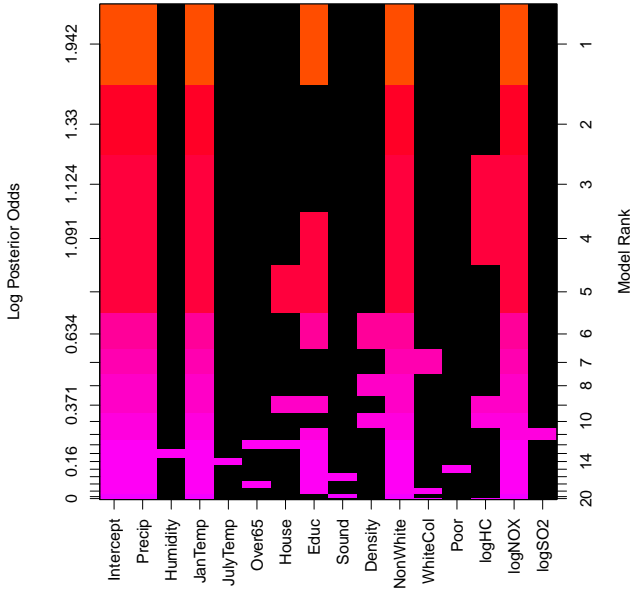
Posterior Probabilities

- ▶ What is the probability that there is no pollution effect?
- ▶ Sum posterior model probabilities over all models that include no pollution variables

```
> which.mat = list2matrix.which(mort.bma,1:(2^15))
> poll.in = (which.mat[, 14:16] %*% rep(1, 3)) > 0
> sum(poll.in * mort.bma$postprob)
[1] 0.9889641
```
- ▶ Posterior probability no effect is 0.011
- ▶ Posterior Odds that there is an effect $(1 - .011)/(.011) = 89$.
- ▶ Prior Odds $7 = (1 - .5^3)/.5^3$
- ▶ Bayes Factor for a pollution effect $89.9/7 = 12.8$
- ▶ Bayes Factor for NOX based on marginal inclusion probability $0.917/(1 - 0.917) = 11.0$
- ▶ Marginal inclusion probability for logHC = 0.427144
($BF = .745$)
- ▶ Marginal inclusion probability for logSO2 = 0.218978
($BF = .280$)

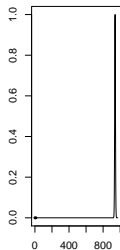
Bayes Factors are not additive!

Model Space

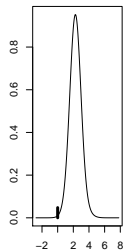


Coefficients

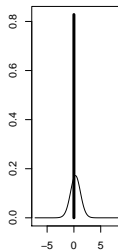
Intercept



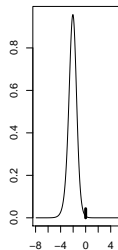
Precip



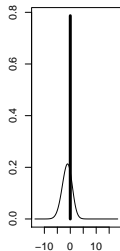
Humidity



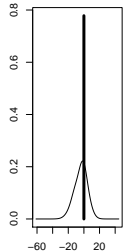
JanTemp



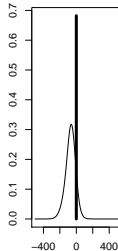
JulyTemp



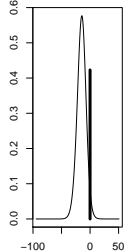
Over65



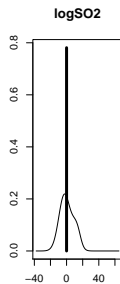
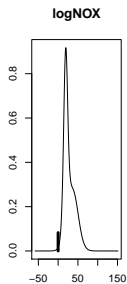
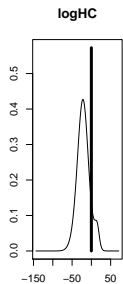
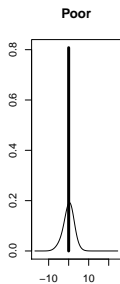
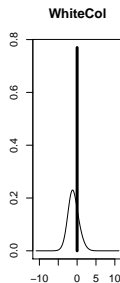
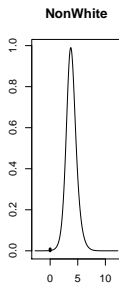
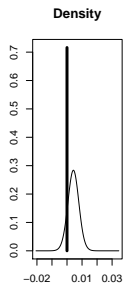
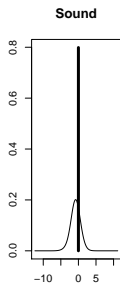
House



Educ



Coefficients



Effect Estimation

- ▶ Coefficients in each model are adjusted for other variables in the model
- ▶ OLS: leave out a predictor with a non-zero coefficient then estimates are biased!
- ▶ Model Selection in the presence of high correlation, may leave out "redundant" variables;
- ▶ improved MSE for prediction (Bias-variance tradeoff)
- ▶ Bayes is biased anyway so should we care?

With confounding, should not use plain BMA. Need to change prior to include potential confounders (advanced topic)

Computational Issues

- ▶ Computational if $p > 35$ enumeration is difficult
 - ▶ Gibbs sampler or Random-Walk algorithm on γ
 - ▶ poor convergence/mixing with high correlations
 - ▶ Metropolis Hastings algorithms more flexibility (method="MCMC")
 - ▶ "Stochastic Search" (no guarantee samples represent posterior)
 - ▶ Variational, EM, etc to find modal model
 - ▶ in BMA all variables are included, but coefficients are shrunk to 0; alternative is to use Shrinkage methods
 - ▶ Models with Non-estimable parameters? (use generalized inverse)
- ▶ Prior Choice: Choice of prior distributions on β and on γ

Model averaging versus Model Selection – what are objectives?

BAS Algorithm - Clyde, Ghosh, Littman - JCGS

- ▶ Sampling w/out Replacement `method="BAS"`
- ▶ MCMC Sampling `method="MCMC"`

See package Vignette