Gauss Markov & Predictive Distributions Merlise Clyde

STA721 Linear Models

Duke University

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Outline

Topics

- Gauss-Markov Theorem
- Estimability and Prediction

Readings: Christensen Chapter 2, Chapter 6.3, (Appendix A, and Appendix B as needed)

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Theorem Under the assumptions:

 $E[\mathbf{Y}] = \mu$



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$$E[\mathbf{Y}] = \boldsymbol{\mu}$$

Cov(\mathbf{Y}) = $\sigma^2 \mathbf{I}_n$

every estimable function $\psi = \lambda^T \beta$ has a unique unbiased linear estimator $\hat{\psi}$ which has minimum variance in the class of all unbiased linear estimators. $\hat{\psi} = \lambda^T \hat{\beta}$ where $\hat{\beta}$ is any set of ordinary least squares estimators.

Lemma

If ψ = λ^Tβ is estimable, there exists a unique linear unbiased estimator of ψ = a^{*T}Y with a^{*} ∈ C(X).

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Lemma

If ψ = λ^Tβ is estimable, there exists a unique linear unbiased estimator of ψ = a^{*T}Y with a^{*} ∈ C(X).

If a^TY is any unbiased linear estimator of ψ then a^{*} is the projection of a onto C(X), i.e. a^{*} = P_Xa.

Proof

• Since ψ is estimable, there exists an $\mathbf{a} \in \mathbb{R}^n$ for which $\mathsf{E}[\mathbf{a}^T \mathbf{Y}] = \boldsymbol{\lambda}^T \boldsymbol{\beta} = \psi$ with $\boldsymbol{\lambda}^T = \mathbf{a}^T \mathbf{X}$

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▶ Let $\mathbf{a} = \mathbf{a}^* + \mathbf{u}$ where $\mathbf{a}^* \in C(\mathbf{X})$ and $\mathbf{u} \in C(\mathbf{X})^{\perp}$

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- Let $\mathbf{a} = \mathbf{a}^* + \mathbf{u}$ where $\mathbf{a}^* \in C(\mathbf{X})$ and $\mathbf{u} \in C(\mathbf{X})^{\perp}$
- Then

$$\psi = \mathsf{E}[\mathbf{a}^{\mathsf{T}}\mathbf{Y}] = \mathsf{E}[\mathbf{a}^{*\mathsf{T}}\mathbf{Y}] + \mathsf{E}[\mathbf{u}^{\mathsf{T}}\mathbf{Y}]$$

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Then

$$\psi = \mathsf{E}[\mathbf{a}^T \mathbf{Y}] = \mathsf{E}[\mathbf{a}^{*T} \mathbf{Y}] + \mathsf{E}[\mathbf{u}^T \mathbf{Y}]$$
$$= \mathsf{E}[\mathbf{a}^{*T} \mathbf{Y}] + \mathbf{0}$$

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$$\begin{split} \mathsf{E}[\mathbf{u}^{\mathsf{T}}\mathbf{Y}] &= \mathbf{u}^{\mathsf{T}}\mathbf{X}\boldsymbol{\beta}\\ \text{since } \mathbf{u} \perp \mathcal{C}(\mathbf{X}) \text{ (i.e. } \mathbf{u} \in \mathcal{C}(\mathbf{X})^{\perp}) \; \mathsf{E}[\mathbf{u}^{\mathsf{T}}\mathbf{Y}] = \mathbf{0} \end{split}$$

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$$\mathsf{E}[\mathbf{u}^{\mathsf{T}}\mathbf{Y}] = \mathbf{u}^{\mathsf{T}}\mathbf{X}\boldsymbol{\beta}$$

since $\mathbf{u} \perp C(\mathbf{X})$ (i.e. $\mathbf{u} \in C(\mathbf{X})^{\perp}) E[\mathbf{u}^{\mathsf{T}}\mathbf{Y}] = 0$

▶ Thus $\mathbf{a}^{*T}\mathbf{Y}$ is also an unbiased linear estimator of ψ with $\mathbf{a}^{*} \in C(\mathbf{X})$

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Proof.

Suppose that there is another $\mathbf{v} \in C(\mathbf{X})$ such that $E[\mathbf{v}^T \mathbf{Y}] = \psi$. Then for all β

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Suppose that there is another $\mathbf{v} \in C(\mathbf{X})$ such that $E[\mathbf{v}^T \mathbf{Y}] = \psi$. Then for all β

$$0 = \mathsf{E}[\mathbf{a}^{*T}\mathbf{Y}] - \mathsf{E}[\mathbf{v}^{T}\mathbf{Y}]$$



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- Implies $(\mathbf{a}^* \mathbf{v}) \in C(\mathbf{X})^{\perp}$
- ▶ but by assumption $(\mathbf{a}^* \mathbf{v}) \in C(\mathbf{X})$ ($C(\mathbf{X})$ is a vector space)

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Therefore $\mathbf{a}^{*T}\mathbf{Y}$ is the unique linear unbiased estimator of ψ with $\mathbf{a}^{*} \in C(\mathbf{X})$.

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• Let $\mathbf{a}^{*T}\mathbf{Y}$ be the unique unbiased linear estimator of ψ with $\mathbf{a}^* \in C(\mathbf{X})$.

▶ Let $\mathbf{a}^T \mathbf{Y}$ be any unbiased estimate of ψ ; $\mathbf{a} = \mathbf{a}^* + \mathbf{u}$ with $\mathbf{a}^* \in C(\mathbf{X})$ and $\mathbf{u} \in C(\mathbf{X})^{\perp}$

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= $\sigma^{2}(||\mathbf{a}^{*}||^{2} + ||\mathbf{u}||^{2}) + 0$
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$$\begin{aligned}
\text{Var}(\mathbf{a}^T \mathbf{Y}) &= \mathbf{a}^T \text{Cov}(\mathbf{Y}) \mathbf{a} \\
&= \sigma^2 ||\mathbf{a}||^2 \\
&= \sigma^2 (||\mathbf{a}^*||^2 + ||\mathbf{u}||^2 + 2\mathbf{a}^{*T} \mathbf{u}) \\
&= \sigma^2 (||\mathbf{a}^*||^2 + ||\mathbf{u}||^2) + 0 \\
&= \text{Var}(\mathbf{a}^{*T} \mathbf{Y}) + \sigma^2 ||\mathbf{u}||^2 \\
&\geq \text{Var}(\mathbf{a}^{*T} \mathbf{Y})
\end{aligned}$$

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with equality if and only if $\mathbf{a}=\mathbf{a}^*$

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Hence $\mathbf{a}^{*T}\mathbf{Y}$ is the unique linear unbiased estimator of ψ with minimum variance

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with equality if and only if $\mathbf{a} = \mathbf{a}^*$

Hence $\mathbf{a}^{*T}\mathbf{Y}$ is the unique linear unbiased estimator of ψ with minimum variance "BLUE" = Best Linear Unbiased Estimator

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Continued

Proof. Show that $\hat{\psi} = \mathbf{a}^{*T}\mathbf{Y} = \boldsymbol{\lambda}^{T}\hat{\boldsymbol{\beta}}$



Continued

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Continued

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for $\boldsymbol{\lambda}^{\mathcal{T}} = \mathbf{a}^{*\mathcal{T}} \mathbf{X}$ or $\boldsymbol{\lambda} = \mathbf{X}^{\mathcal{T}} \mathbf{a}$



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Requires just first and second moments

- Gauss-Markov Theorem says that OLS has minimum variance in the class of all Linear Unbiased estimators
- Requires just first and second moments
- Additional assumption of normality, OLS = MLEs have minimum variance out of ALL unbiased estimators (MVUE); not just linear estimators

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Prediction

For predicting at new x_{*} is there always a unique unbiased estimator of E[Y | x_{*}]?

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Prediction

- For predicting at new x_{*} is there always a unique unbiased estimator of E[Y | x_{*}]?
- If one does exist, how do we know that if we are given λ ?

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• $\mathbf{x}_* \boldsymbol{\beta}$ has a unique unbiased estimator if $\mathbf{x}_* \equiv \boldsymbol{\lambda} = \mathbf{X}^T \mathbf{a}$



Existence

- ▶ $\mathbf{x}_* \boldsymbol{\beta}$ has a unique unbiased estimator if $\mathbf{x}_* \equiv \boldsymbol{\lambda} = \mathbf{X}^T \mathbf{a}$
- Clearly if x_{*} = x_i (*i*th row of observed data) then it is estimable with a equal to the vector with a 1 in the *i*th position even if X is not full rank!

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What about out of sample prediction?

Existence

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What about out of sample prediction?

Example

```
x1 = -4:4
x^2 = c(-2, 1, -1, 2, 0, 2, -1, 1, -2)
x_3 = 3 \times x_1 - 2 \times x_2
x4 = x2 - x1 + 4
Y = 1 + x1 + x2 + x3 + x4 + c(-.5, .5, .5, -.5, 0, .5, -.5, -.5, .5)
dev.set = data.frame(Y, x1, x2, x3, x4)
lm1234 = lm(Y ~ x1 + x2 + x3 + x4, data=dev.set)
round(coefficients(lm1234), 4)
## (Intercept)
                          x1
                                         x2
                                                      xЗ
                                                                    x4
                            3
                                                                    NA
##
              5
                                          0
                                                      NA
lm3412 = lm(Y ~ x3 + x4 + x1 + x2, data = dev.set)
round(coefficients(lm3412), 4)
## (Intercept)
                          xЗ
                                        x4
                                                      x1
                                                                    x2
##
            -19
                            3
                                          6
                                                      NA
                                                                    NA
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```

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In Sample Predictions

<pre>cbind(dev.set, predict(lm1234), predict(lm3412))</pre>												
##		Y	x1	x2	x3	x4	predict(lm1234)	predict(lm3412)				
##	1	-7.5	-4	-2	-8	6	-7	-7				
##	2	-3.5	-3	1	-11	8	-4	-4				
##	3	-0.5	-2	-1	-4	5	-1	-1				
##	4	1.5	-1	2	-7	7	2	2				
##	5	5.0	0	0	0	4	5	5				
##	6	8.5	1	2	-1	5	8	8				
##	7	10.5	2	-1	8	1	11	11				
##	8	13.5	3	1	7	2	14	14				
##	9	17.5	4	-2	16	-2	17	17				

Both models agree for estimating the mean at the observed ${\boldsymbol{\mathsf{X}}}$ points!

Out of Sample

```
out = data.frame(test.set,
     Y1234=predict(lm1234, new=test.set),
     Y3412=predict(lm3412, new=test.set))
out
    x1 x2 x3 x4 Y1234 Y3412
##
## 1
    3 1 7 2
                 14
                      14
## 2 6 2 14 4 23 47
## 3 6 2 14 0 23
                      23
##
  4 0 0 0 4 5
                       5
## 5 0 0 0 0
              5 -19
## 6
     1 2 3
             4
                  8
                       14
```

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```
out = data.frame(test.set,
     Y1234=predict(lm1234, new=test.set),
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out
## x1 x2 x3 x4 Y1234 Y3412
## 1 3 1 7 2
                14
                     14
## 2 6 2 14 4 23 47
## 3 6 2 14 0 23 23
## 4 0 0 0 4 5
                      5
## 5 0 0 0 0 5 -19
## 6 1 2 3 4
                 8
                      14
```

Agreement for cases 1, 3, and 4 only! Can we determine that without finding the predictions and comparing?

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• Estimable means that $\lambda^T = \mathbf{a}^T \mathbf{X}$ for $\mathbf{a} \in C(\mathbf{X})$



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- Transpose: $\lambda = \mathbf{X}^T \mathbf{a}$ for $\mathbf{a} \in C(\mathbf{X})$

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- $\blacktriangleright \lambda \perp N(\mathbf{X})$
- ▶ if **P** is a projection onto $C(\mathbf{X}^T)$ then $\mathbf{I} \mathbf{P}$ is a projection onto $N(\mathbf{X})$ and therefore $(\mathbf{I} \mathbf{P})\lambda = \mathbf{0}$ if λ is estimable

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Take $\mathbf{P}_{\mathbf{X}^{T}} = (\mathbf{X}^{T}\mathbf{X})(\mathbf{X}^{T}\mathbf{X})^{-}$ as a projection onto $C(\mathbf{X}^{T})$ and show $(\mathbf{I} - \mathbf{P}_{\mathbf{X}^{T}})\lambda = \mathbf{0}_{p}$

Example

<pre>library("estimability")</pre>												
<pre>cbind(epredict(lm1234,</pre>					<pre>test.set),</pre>	<pre>epredict(lm3412,</pre>	test.set					
##		[,1]	[,2]									
##	1	14	14									
##	2	NA	NA									
##	3	23	23									
##	4	5	5									
##	5	NA	NA									
##	6	NA	NA									

Rows 2, 5, and 6 are not estimable! No linear unbiased estimator

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Eliminate redundancies by removing variables (variable selection)

- When BLUEs exist, under normality they are MVUE (ditto for prediction - BLUP)
- BLUE/BLUP do not always for estimation/prediction if X is not full rank
- may occur with redundancies for modest p < n and of course p > n

- Eliminate redundancies by removing variables (variable selection)
- Consider alternative estimators (Bayes and related)

Other Estimators

What about some estimator $g(\mathbf{Y})$ that is not unbiased?



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where $\mathsf{Bias} = \mathsf{E}[g(\mathbf{Y})] - \lambda^T eta$

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- Bias vs Variance tradeoff
- Can have smaller MSE if we allow some Bias!

- Next Class Bayes Theorem & Conjugate Normal-Gamma Prior/Posterior distributions
- Read Chapter 2 in Christensen or Wakefield 5.7
- Review Multivariate Normal and Gamma distributions