

Predictive Distributions & Properties of MLES

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STA721 Linear Models

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September 12, 2017

Outline

Topics

- ▶ Predictive Distributions
- ▶ OLS/MLES Unbiased Estimation
- ▶ Gauss-Markov Theorem (if time)

Readings: Christensen Chapter 2, Chapter 6.3, (Appendix A, and Appendix B as needed)

Prediction

- ▶ Predict Y_* at $\mathbf{x}_*^T$ (could be new point or existing point)
 $\mathbf{Y}_* = \mathbf{x}_*^T \boldsymbol{\beta} + \epsilon_*$
- ▶ $E[Y_* | \mathbf{x}_*] = \mathbf{x}_*^T \boldsymbol{\beta} = \mu_*$ minimizes squared error loss for predicting Y_* at $\mathbf{X}_*$

$$\begin{aligned} E[Y_* - f(\mathbf{x}_*)]^2 &= E[Y_* - \mu_* + \mu_* - f(\mathbf{x}_*)]^2 \\ &= E[Y_* - \mu_*]^2 + E[\mu_* - f(\mathbf{x}_*)]^2 + \\ &\quad 2E[(Y_* - \mu_*)(\mu_* - f(\mathbf{x}_*))] \\ &\geq E[Y_* - \mu_*]^2 \end{aligned}$$

Crossproduct term is 0:

$$E[E[(Y_* - \mu_*)(\mu_* - f(\mathbf{x}_*)) | \mathbf{x}_*]] = E[0 \cdot (\mu_* - f(\mathbf{x}_*))]$$

- ▶ equality if $f(\mathbf{x}) = E[Y_* | \mathbf{x}_*]$, the “best” predictor of Y_*
- ▶ MLE of μ_* is $\mathbf{x}_*^T \hat{\boldsymbol{\beta}} = \hat{Y}_*$ (is this unique?)
- ▶ OLS Best Linear predictor of $\mathbf{Y}_*$
- ▶ Under joint Normality of $\mathbf{Y}, \mathbf{X}$ Best Predictor

Predictive Distribution

Look at

$$Y_* - \hat{Y}_* = \mathbf{x}_*^T \boldsymbol{\beta} - \mathbf{x}_*^T \hat{\boldsymbol{\beta}} + \epsilon_*$$

$$\text{var}(Y - \hat{Y}) = \text{var}(\mathbf{x}_*^T \boldsymbol{\beta} - \mathbf{x}_*^T \hat{\boldsymbol{\beta}}) + \text{var}(\epsilon_*)$$

Two Sources of variation:

- ▶ Variation of estimator around true regression
- ▶ Variation of error around true regression

Distribution

Distribution of pivotal quantity

$$\frac{Y_* - \mathbf{x}_*^T \hat{\boldsymbol{\beta}}}{\sqrt{\text{MSE}(1 + \mathbf{x}_*^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_*)}} \sim t(n - p, 0, 1)$$

Number of columns (rank) of $\mathbf{X}$ is p

$(1 - \alpha)100$ % Prediction Interval

$$\mathbf{x}_*^T \hat{\boldsymbol{\beta}} \pm t_{\alpha/2} \sqrt{\text{MSE}(1 + \mathbf{x}_*^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_*)}$$

Models & MLEs

- ▶ $\mathbf{Y} \sim N(\boldsymbol{\mu}, \sigma^2 \mathbf{I}_n)$ with $\boldsymbol{\mu} \in C(\mathbf{X}) \Leftrightarrow \boldsymbol{\mu} = \mathbf{X}\boldsymbol{\beta}$
- ▶ Maximum Likelihood Estimator (MLE) of $\boldsymbol{\mu}$ is $\mathbf{P}_\mathbf{X}\mathbf{Y}$
- ▶ $\mathbf{P}_\mathbf{X}$ is the orthogonal projection operator on the column space of $\mathbf{X}$; e.g. $\mathbf{X}$ full rank $\mathbf{P}_\mathbf{X} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T$
- ▶ If $\mathbf{X}^T\mathbf{X}$ is not invertible use a generalized inverse

A generalize inverse of $\mathbf{A}$: $\mathbf{A}^-$ satisfies $\mathbf{A}\mathbf{A}^-\mathbf{A} = \mathbf{A}$

Lemma (B.43)

If $\mathbf{G}$ and $\mathbf{H}$ are generalized inverses of $(\mathbf{X}^T\mathbf{X})$ then

1. $\mathbf{XG}\mathbf{X}^T\mathbf{X} = \mathbf{XH}\mathbf{X}^T\mathbf{X} = \mathbf{X}$
2. $\mathbf{XG}\mathbf{X}^T = \mathbf{XH}\mathbf{X}^T$

$\mathbf{P}_\mathbf{X} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-}\mathbf{X}^T$ is the orthogonal projection operator onto $C(\mathbf{X})$ (does not depend on choice of generalized inverse!) [See proof in Theorem B.44]

Generalize Inverses

A generalize inverse of $\mathbf{A}$: $\mathbf{A}^-$ satisfies $\mathbf{A}\mathbf{A}^-\mathbf{A} = \mathbf{A}$

Special Case: Moore-Penrose Generalized Inverse

- ▶ Decompose symmetric $\mathbf{A} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^T$
- ▶ $\mathbf{A}_{MP}^- = \mathbf{U}\mathbf{\Lambda}^-\mathbf{U}^T$
- ▶ $\mathbf{\Lambda}^-$ is diagonal with

$$\lambda_i^- = \begin{cases} 1/\lambda_i & \text{if } \lambda_i \neq 0 \\ 0 & \text{if } \lambda_i = 0 \end{cases}$$

- ▶ Symmetric $\mathbf{A}_{MP}^- = (\mathbf{A}_{MP}^-)^T$
- ▶ Reflexive $\mathbf{A}_{MP}^-\mathbf{A}\mathbf{A}_{MP}^- = \mathbf{A}_{MP}^-$

If $\mathbf{P}$ is an orthogonal projection matrix, the generalized inverse of $\mathbf{P}$, $\mathbf{P}^- = \mathbf{P}$

MLE of β

$$\begin{aligned}\mathbf{P}_\mathbf{X}\mathbf{Y} &= \mathbf{X}\hat{\beta} \\ \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-}\mathbf{X}^T\mathbf{Y} &= \mathbf{X}\hat{\beta}\end{aligned}$$

- ▶ MLE of β iff $\mathbf{P}_\mathbf{X}\mathbf{Y} = \mathbf{X}\hat{\beta}$
- ▶ If $\mathbf{X}^T\mathbf{X}$ is invertible, then

$$\hat{\beta} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{Y}$$

and is unique

- ▶ But if $\mathbf{X}^T\mathbf{X}$ is not invertible,

$$\hat{\beta} = (\mathbf{X}^T\mathbf{X})^{-}\mathbf{X}^T\mathbf{Y}$$

is one solution which depends on choice of generalized inverse

What can we estimate uniquely?

Identifiability

$$\mathbf{Y} \sim N(\boldsymbol{\mu}, \sigma^2 \mathbf{I})$$

- ▶ Distribution of $\mathbf{Y}$ determined by $\boldsymbol{\mu}$ and σ^2
- ▶ $\boldsymbol{\mu} = \mathbf{X}\boldsymbol{\beta} = \mu(\boldsymbol{\beta})$

Identifiability

$\boldsymbol{\beta}$ and σ^2 are identifiable if distribution of $\mathbf{Y}$,

$$f_{\mathbf{Y}}(\mathbf{y}; \boldsymbol{\beta}_1, \sigma_1^2) = f_{\mathbf{Y}}(\mathbf{y}; \boldsymbol{\beta}_2, \sigma_2^2) \text{ implies that } (\boldsymbol{\beta}_1, \sigma_1^2)^T = (\boldsymbol{\beta}_2, \sigma_2^2)^T$$

For linear models, equivalent definition is that $\boldsymbol{\beta}$ is identifiable if for any $\boldsymbol{\beta}_1$ and $\boldsymbol{\beta}_2$ $\mu(\boldsymbol{\beta}_1) = \mu(\boldsymbol{\beta}_2)$ implies that $\boldsymbol{\beta}_1 = \boldsymbol{\beta}_2$. If $r(\mathbf{X}) = p$ then $\boldsymbol{\beta}$ is identifiable. If $\mathbf{X}$ is not full rank, there exists

$\boldsymbol{\beta}_1 \neq \boldsymbol{\beta}_2$, but $\mathbf{X}\boldsymbol{\beta}_1 = \mathbf{X}\boldsymbol{\beta}_2$ and hence $\boldsymbol{\beta}$ is not identifiable

Non-Identifiable

Recall the One-way ANOVA model

$$\mu_{ij} = \mu + \tau_j \quad \boldsymbol{\mu} = (\mu_{11}, \dots, \mu_{n_1 1}, \mu_{12}, \dots, \mu_{n_2 2}, \dots, \mu_{1J}, \dots, \mu_{n_J J})^T$$

- ▶ Let $\boldsymbol{\beta}_1 = (\mu, \tau_1, \dots, \tau_J)^T$
- ▶ Let $\boldsymbol{\beta}_2 = (\mu - 42, \tau_1 + 42, \dots, \tau_J + 42)^T$
- ▶ Then $\boldsymbol{\mu}_1 = \boldsymbol{\mu}_2$ even though $\boldsymbol{\beta}_1 \neq \boldsymbol{\beta}_2$
- ▶ $\boldsymbol{\beta}$ is not identifiable
- ▶ yet $\boldsymbol{\mu}$ is identifiable, where $\boldsymbol{\mu} = \mathbf{X}\boldsymbol{\beta}$ (a linear combination of $\boldsymbol{\beta}$)

Identifiability and Estimability

Theorem

A function $g(\beta)$ is identifiable if and only if $g(\beta)$ is a function of $\mu(\beta)$

In linear models, historical focus on linear functions. Identifiable linear functions are called *estimable* functions

Definition

A vector valued function $\mathbf{L}\beta$ is *estimable* if $\mathbf{L}\beta = \mathbf{A}\mathbf{X}\beta$ for some matrix $\mathbf{A}$

Equivalently

Definition

A vector valued function $\mathbf{L}\beta$ is *estimable* if it has an unbiased linear estimator, i.e. there exists an $\mathbf{A}$ such that $E(\mathbf{A}\mathbf{Y}) = \mathbf{L}\beta$ for all β

Estimability

Work with scalar functions $\psi = \boldsymbol{\lambda}^T \boldsymbol{\beta}$

Theorem

The function $\psi = \boldsymbol{\lambda}^T \boldsymbol{\beta}$ is estimable if and only if $\boldsymbol{\lambda}^T$ is a linear combination of the rows of $\mathbf{X}$. i.e. there exists $\mathbf{a}^T$ such that $\boldsymbol{\lambda}^T = \mathbf{a}^T \mathbf{X}$

Proof.

The function $\psi = \boldsymbol{\lambda}^T \boldsymbol{\beta}$ is estimable if there exists an $\mathbf{a}^T$ such that $E[\mathbf{a}^T \mathbf{Y}] = \boldsymbol{\lambda}^T \boldsymbol{\beta}$

$$\begin{aligned} E[\mathbf{a}^T \mathbf{Y}] &= \mathbf{a}^T E[\mathbf{Y}] \\ &= \mathbf{a}^T \mathbf{X} \boldsymbol{\beta} \\ &= \boldsymbol{\lambda}^T \boldsymbol{\beta} \end{aligned}$$

if and only if $\boldsymbol{\lambda}^T = \mathbf{a}^T \mathbf{X}$ for all $\boldsymbol{\beta}$



Estimability of Individual β_j

Proposition

For

$$\mu = \mathbf{X}\beta = \sum_j \mathbf{X}_j \beta_j$$

β_j is not identifiable if and only if there exists α_j such that

$$\mathbf{X}_j = \sum_{i \neq j} \mathbf{X}_i \alpha_i$$

One-way Anova Model:

$$Y_{ij} = \mu + \tau_j + \epsilon_{ij}$$

$$\mu = \begin{bmatrix} \mathbf{1}_{n_1} & \mathbf{1}_{n_1} & \mathbf{0}_{n_1} & \cdots & \mathbf{0}_{n_1} \\ \mathbf{1}_{n_2} & \mathbf{0}_{n_2} & \mathbf{1}_{n_2} & \cdots & \mathbf{0}_{n_2} \\ \vdots & \vdots & \ddots & \vdots & \\ \mathbf{1}_{n_J} & \mathbf{0}_{n_J} & \mathbf{0}_{n_J} & \cdots & \mathbf{1}_{n_J} \end{bmatrix} \begin{pmatrix} \mu \\ \tau_1 \\ \tau_2 \\ \vdots \\ \tau_J \end{pmatrix}$$

Are any parameters μ or τ_j identifiable?