

G-Priors and Mixture Distributions

STA721 Linear Models Duke University

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Bayesian Estimation

Model

$$\mathbf{Y} \sim \mathcal{N}(\mathbf{X}\boldsymbol{\beta}, \mathbf{I}_n/\phi)$$

with precision $\phi = 1/\sigma^2$.

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Default Prior Choices:

- ▶ Independent Jeffreys' Priors
- ▶ Partitioned g-priors
- ▶ Zellner-Siow Cauchy Prior, mixtures and MCMC

Readings: Hoff Chapter 9

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Bayesian Credible Sets $p(\beta \in C_\alpha) = 1 - \alpha$ correspond to frequentist Confidence Regions

$$\frac{\lambda^T \beta - \lambda^T \hat{\beta}}{\sqrt{\hat{\sigma}^2 \lambda^T (\mathbf{X}^T \mathbf{X})^{-1} \lambda}} \sim t_{n-p}$$

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Cannot represent anyone's prior beliefs, but used as a reference posterior

Partitioned Zellner's g -prior

Zellner recognized that some parameters might have less information

$$\mathbf{Y} = \mathbf{X}_0\boldsymbol{\beta}_0 + \mathbf{X}_1\boldsymbol{\beta}_1 + \boldsymbol{\epsilon}$$

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- ▶ $p(\phi) \propto 1/\phi$

Special case $\mathbf{X}_0 = \mathbf{1}_n$ and let $g_0 \rightarrow \infty$

Bayesian Estimation with g prior

$$\begin{aligned}\mathbf{Y} &= \mathbf{1}\alpha_0 + \mathbf{X}_1\boldsymbol{\beta} + \boldsymbol{\epsilon} \\ p(\alpha_0, \phi) &\propto 1 \\ \boldsymbol{\beta} \mid \phi &\sim \text{N}(\mathbf{0}, \frac{g}{\phi}(\mathbf{X}^T(\mathbf{I}_n - \mathbf{P}_1)\mathbf{X})^{-1})\end{aligned}$$

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Equivalent to

$$\begin{aligned}\mathbf{Y} &= \mathbf{1}\beta_0 + (\mathbf{I} - \mathbf{P}_1)\mathbf{X}_1\boldsymbol{\beta} + \boldsymbol{\epsilon} \\ \beta_0 &= \alpha + \bar{\mathbf{x}}^T\boldsymbol{\beta} \\ p(\beta_0, \phi) &\propto 1 \\ \boldsymbol{\beta} \mid \phi &\sim \mathcal{N}(\mathbf{0}, \frac{g}{\phi}(\mathbf{X}^T(\mathbf{I}_n - \mathbf{P}_1)\mathbf{X})^{-1})\end{aligned}$$

Prior Data

Note

$$(\mathbf{X}^T(\mathbf{I}_n - \mathbf{P}_1)\mathbf{X}) = (\mathbf{X}^T(\mathbf{I}_n - \mathbf{P}_1)^T(\mathbf{I}_n - \mathbf{P}_1)\mathbf{X}) = (\mathbf{X} - \mathbf{1}_n\bar{\mathbf{X}}^T)^T(\mathbf{X} - \mathbf{1}_n\bar{\mathbf{X}})$$

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$$\text{Let } (\mathbf{X} - \mathbf{1}_n\bar{\mathbf{X}}^T)^T(\mathbf{X} - \mathbf{1}_n\bar{\mathbf{X}}) = SS_{\mathbf{X}} = \mathbf{U}^T\mathbf{U}$$

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Quadratic contribution to the log likelihood from prior after integrating out β_0

$$(\mathbf{Y}_c - \mathbf{X}_c\beta)^T(\mathbf{Y}_c - \mathbf{X}_c\beta) + (\beta^T \frac{\mathbf{U}^T\mathbf{U}}{g} \beta)$$

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Prior observations with $Y_c = 0$.

Example: $g=5$, $n=30$

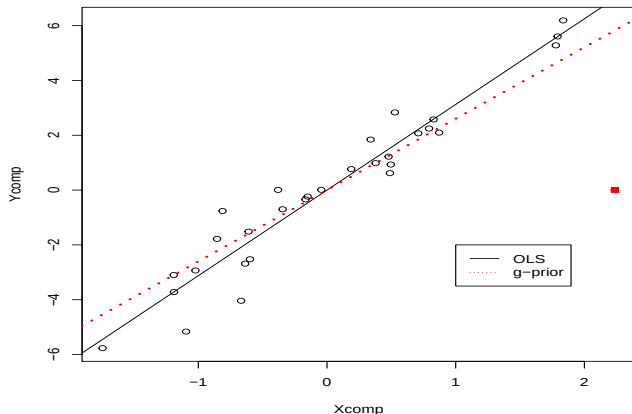
In SLR it is like an extra $Y_0 = 0$ at $\mathbf{X}_o = \sqrt{\frac{SS_x}{g}}$:

$$(\mathbf{Y}_c - \mathbf{X}_c\beta)^T(\mathbf{Y}_c - \mathbf{X}_c\beta) + (0 - \sqrt{\frac{SS_x}{g}}\beta)^T(0 - \sqrt{\frac{SS_x}{g}}\beta)$$

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- ▶ Problem potentially with all Normal priors, not just the g -prior.
- ▶ Cannot capture all possible prior beliefs
- ▶ Mixtures of Conjugate Priors

Mixtures of Conjugate Priors

Theorem (Diaconis & Ylvisaker 1985)

Given a sampling model $p(y \mid \theta)$ from an exponential family, any prior distribution can be expressed as a mixture of conjugate prior distributions

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Zellner-Siow prior (assume $\mathbf{X}$ is centered)

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- ▶ What about credible intervals?

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$$p(\tau \mid \beta, \phi, \mathbf{Y}) \propto \mathcal{L}(\beta_0, \beta, \phi) \tau^{p/2} e^{(-\tau \frac{\phi}{2} \beta^T (\mathbf{X}^T \mathbf{X}) \beta)} \tau^{1/2-1} e^{-\tau n/2}$$

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- ▶ alternate sampling from full conditional distributions given current values of other parameters. (STA 601)
- ▶ JAGS or STAN

JAGS Code: library(R2jags)

```
model = function(){  
  for (i in 1:n) {  
    Y[i] ~ dnorm(beta0+ (X[i] -Xbar)*beta, phi)  
  }  
  beta0 ~ dnorm(0, .000001*phi) #precision is 2nd arg  
  beta ~ dnorm(0, phi*tau*SSX) #precision is 2nd arg  
  phi ~ dgamma(.001, .001)  
  tau ~ dgamma(.5, .5*n)  
  g <- 1/tau  
  sigma <- pow(phi, -.5)  
}  
data = list(Y=Y, X=X, n=length(Y), SSX=sum(Xc^2),  
            Xbar=mean(X))  
ZSout = jags(data, inits=NULL,  
              parameters.to.save=c("beta0", "beta", "g",  
                                   "sigma"),  
              model=model, n.iter=10000)
```


HPD intervals

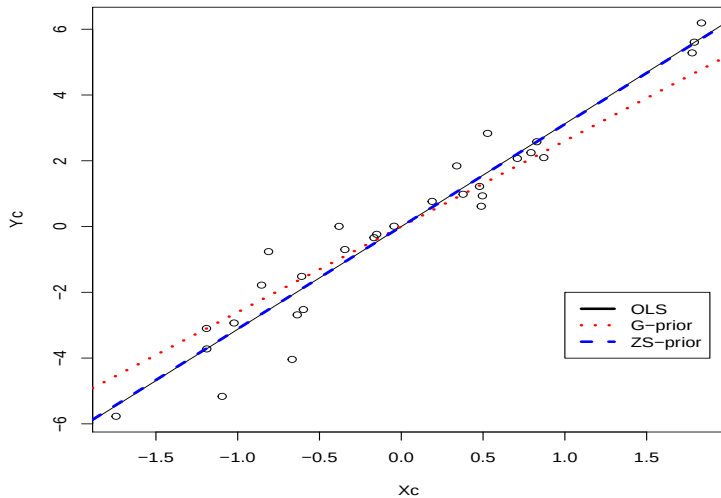
```
confint(lm(Y ~ Xc))
```

```
##                2.5 %    97.5 %  
## (Intercept) -0.3985359 0.2048303  
## Xc           2.7945824 3.4555162
```

```
HPDinterval(as.mcmc(ZSout$BUGSoutput$sims.matrix))
```

```
##                lower      upper  
## beta           2.7823047    3.4453690  
## beta0         -0.3764027    0.2095465  
## deviance      70.2043917    78.4813041  
## g             19.4503373 3782.7134974  
## sigma         0.6171029    1.0504892  
## attr("Probability")  
## [1] 0.95
```

Compare



ZSout

```
## Inference for Bugs model at "/var/folders/n4/nj1122xj6bn5_xgbptv7bml40000gp/T//Rtmpe7h40r/model1784a581
## 3 chains, each with 10000 iterations (first 5000 discarded), n.thin = 5
## n.sims = 3000 iterations saved
##      mu.vect    sd.vect    2.5%    25%    50%    75%    97.5%  Rhat
## beta          3.112     0.170  2.782   2.997   3.115   3.225   3.445  1.001
## beta0         -0.099     0.152 -0.384  -0.204  -0.099   0.001   0.204  1.002
## g            2263.147 38967.029 48.273 146.129 282.298 697.063 9018.709 1.001
## sigma         0.827     0.114  0.636   0.747   0.816   0.896   1.079  1.001
## deviance      73.347     2.563 70.390  71.458  72.680  74.500  79.882  1.002
##      n.eff
## beta          3000
## beta0         1200
## g             3000
## sigma         3000
## deviance      1600
##
## For each parameter, n.eff is a crude measure of effective sample size,
## and Rhat is the potential scale reduction factor (at convergence, Rhat=1).
##
## DIC info (using the rule, pD = var(deviance)/2)
## pD = 3.3 and DIC = 76.6
## DIC is an estimate of expected predictive error (lower deviance is better).
```

Cauchy Summary

- ▶ Cauchy rejects prior mean if it is an "outlier"
- ▶ robustness related to "bounded" influence (more later)
- ▶ numerical integration or Monte Carlo sampling (MCMC)