

A specific example of Gibbs sampling - canonical Markov chain Monte Carlo method for calculations in Bayesian statistical models, as well as a key applied model class.

### ♠ Simulation of Posteriors

- For any statistical model, simulated values of posterior distributions are nowadays the standard in statistical computation: summarise large samples of parameter values from a posterior distribution to easily understand the information contained in that posterior about the parameters
- MCMC methods, such as Gibbs sampling, generate simulations sequentially using Markov chains
- Gibbs sampling represents an approach in which sets of coupled conditional posteriors derived from the model are used for these simulations
- Here's a key example

### ♠ Probit Model

- Expression level vector  $\mathbf{x}_j$  on array (tumor sample, etc)  $j = 1, \dots, n$
- Binary outcome:  $z_j = 0$  or  $1$
- Probit probability model:  $\pi_j = Pr(z_j = 1)$  (conditional on chosen predictor variables and model parameters: in full,  $\pi_j = Pr(z_j = 1 | \mathbf{x}_j, \boldsymbol{\beta})$ )
- Linear regression model based on regression function  $\mu_j = \mathbf{x}_j' \boldsymbol{\beta}$  (perhaps  $\mathbf{x}_j$  is extended with a leading 1 to include an intercept term  $\beta_0$ )
- Probit regression:

$$\pi_j = \Phi(\mu_j)$$

where  $\Phi$  is standard normal cumulative distribution function

### ♠ Prior and Posterior

- Example:  $\boldsymbol{\beta} \sim N(0, \mathbf{C}^{-1})$  and we'll take the precision as diagonal
- Posterior for regression parameters

$$p(\boldsymbol{\beta} | \mathbf{z}) \propto \exp(-\boldsymbol{\beta}' \mathbf{C} \boldsymbol{\beta}) \prod_{j=1}^n \Phi(\mu_j)^{z_j} (1 - \Phi(\mu_j))^{1-z_j}$$

which can be evaluated, numerically optimized (it is unimodal) using standard NR routines,

- *Exercise:* Write code (in C/C++ or other) to implement a Newton-Raphson search for the mode of the posterior density. As ALWAYS in such problems, work with the log-posterior, i.e., maximise the log of the target function for numerical stability
- Under vague reference prior ( $\mathbf{C} \rightarrow 0$ ) the posterior is the normalised likelihood function. The MLE and related information can be computed using R/Splus glm functions, Matlab glmfit function, or (quite easily) by user-written code as a special case

### ♠ Latent Variables and Data Augmentation

- For each sample, recognise an underlying latent variable  $\mathbf{y}_j$
- $\pi_j = Pr(y_j > 0)$  when  $y_j \sim N(\mu_j, 1) = N(\mathbf{x}_j' \boldsymbol{\beta}, 1)$
- $z_j = 1$  if and only if  $y_j > 0$ 
  - e.g., latent variable is positive for ER+ cases, negative for ER- cases

- could precisely classify cases if we could observe the latent  $y_j$ , but we do not; result is the binary probability model
- MCMC calculations impute these “missing” values along with values of the parameters  $\beta$

### ♠ Conditional Posteriors

- $p(\beta|\mathbf{y}, \mathbf{z})$

If  $\mathbf{y}$  were known, we have a linear regression of the  $y_j$  with regression variables  $\mathbf{x}_j$ , parameter  $\beta$  and error variance 1. The actual value of  $\mathbf{z}$  is at this point irrelevant – the information they contain is already there in the (current, imputed or candidate) values of  $\mathbf{y}$ : Formally,  $\beta$  is conditionally independent of  $\mathbf{z}$  given  $\mathbf{y}$ . The posterior (see earlier notes) is multivariate normal

$$\beta|\mathbf{y}, \mathbf{z} \sim N(\mathbf{b}, \mathbf{B}^{-1})$$

with  $\mathbf{B} = \mathbf{C} + \mathbf{H}'\mathbf{H}$  and  $\mathbf{b} = \mathbf{B}^{-1}\mathbf{H}'\mathbf{y}$  where  $\mathbf{H} = \mathbf{X}'$  is the  $n \times p$  design matrix.

For multivariate normals, use programmed functions (multivariate normal simulation is very standard - e.g., `rMNorm.m` or similar) or use direct Cholesky decomposition: e.g., by hand in matlab

$$\mathbf{b} + \text{chol}(\text{inv}(\mathbf{B})) * \text{randn}(p, 1)$$

for a single draw

- $p(\mathbf{y}|\beta, \mathbf{z})$

If  $\beta$  were known, then the  $y_j$  are independent normals but subject to the information provided by the  $z_j$  - in each case, we just condition the initial normal on the information that  $y_j$  must be positive (if  $z_j = 1$ ) or negative (if  $z_j = 0$ ). The result may be written simply in terms of the posterior cumulative distribution function, as

$$P(y_j|z_j = 1) = [\Phi(y_j - \mu_j) - (1 - \pi_j)]/\pi_j, \quad \text{for } y_j > 0,$$

and

$$P(y_j|z_j = 0) = \Phi(y_j - \mu_j)/(1 - \pi_j), \quad \text{for } y_j < 0$$

(check that you can derive this). Or, for any value of  $z_j = 0, 1$ ,

$$P(y_j|z_j) = [\Phi(y_j - \mu_j) - z_j(1 - \pi_j)]/[z_j\pi_j + (1 - z_j)(1 - \pi_j)].$$

Simulated values of the  $y_j$  are then drawn, independently, via the inverse CDF approach: generate  $u_j \sim U(0, 1)$  and solve for  $y_j$  in  $P(y_j|z_j) = u_j$ . It can be written trivially as

$$y_j = \mu_j + \Phi^{-1}\{z_j(1 - \pi_j) + u_j(z_j + (1 - \pi_j)(1 - 2z_j))\}$$

with  $\Phi^{-1}$  being the normal quantile function (inverse CDF - `qnorm` function).

### ♠ Including Additional Parameters

MCMC neatly extends to include other parameters. Here's a key example.

- Suppose  $\mathbf{C} = \text{diag}(\gamma_0, \gamma_1, \dots, \gamma_p)$  with prior variances  $\tau_i^2 = \gamma_i^{-1}$  defining element-wise shrinkage parameters for the individual predictor variables. The above discussion all applied now explicitly conditional on values of  $\mathbf{C}$ , so that the simulation iterations can run with simulations of  $\mathbf{C}$  coupled in too. That requires priors on elements of  $\mathbf{C}$ ; if these are independent gamma priors,  $\gamma_j \sim Ga(k/2, h/2)$  for each  $j$ , say, then the relevant conditional posteriors are also independent gammas, namely

$$\gamma_j \sim Ga((k + 1)/2, (h + \beta_j^2)/2).$$

This allows for learning on differential shrinkage parameters across variables.

- *Exercise:* Develop the MCMC with these priors.
- Think about choices of prior parameters: One general way to think about ranges of relevant parameter values in binary regression models is to consider how variation in  $\mu_j$  translates through to the probability scale  $\pi_j$ . Absolute values of  $\mu_j$  bigger than 2 or so lead to probabilities that are already very extreme.