

# Metropolis-Hastings for Lévy Random Fields

Robert L. Wolpert  
Department of Statistical Science  
Duke University, Durham, NC, USA

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## 1 Hastings' Ratio

We begin with a derivation and review of the basic Metropolis Hastings approach to what is now called MCMC, on an abstract measurable space. In Section (2) we move to the case of reversible-jump MCMC schemes for Lévy processes with (nearly) arbitrary Lévy measures.

Let  $(\Theta, \mathcal{F}, P)$  be a probability space; we would like to construct an ergodic discrete-time Markov chain  $\{\theta^t\}_{t \in \mathbb{N}}$  taking values in  $\Theta$  such that

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{0 \leq t < T} \phi(\theta^t) = \int_{\Theta} \phi(\theta) P(d\theta) \quad (1)$$

for (at least) bounded continuous functions  $\phi(\cdot)$ . We begin in Section (1.1) with the simplest possible case: where  $\Theta$  is a finite set  $\Theta = \{\theta_1, \dots, \theta_n\}$  and where  $\mathcal{F} = 2^{\Theta}$  is all possible subsets; we then consider Euclidean space in Section (1.2), and finally Lévy random fields in Section (2).

### 1.1 Finite Spaces

Let  $P : 2^{\Theta} \rightarrow [0, 1]$  be a probability measure on a finite set  $\Theta = \{\theta_1, \dots, \theta_n\}$ ; our goal in this section is to construct a Markov chain on  $\Theta$  whose stationary distribution is  $P(d\theta)$ . We begin with a specified initial distribution  $P^0(d\theta)$ , an auxiliary transition kernel  $Q : 2^{\Theta} \times \Theta \rightarrow [0, 1]$  (so  $Q(\cdot | \theta)$  is a probability measure on  $\Theta$  for each fixed  $\theta \in \Theta$ ), and a  $[0, 1]$ -valued function  $A(\theta^*, \theta)$ , all to be specified later.

Our approach will be to construct a random walk  $\theta^t$  on  $\Theta$  by drawing  $\theta^0 \sim P^0(d\theta)$  from  $P^0(d\theta)$  and at time  $t = 0$  and then, at each time-step  $t$ ,

1. Propose a new value  $\theta^* \sim Q(d\theta^* | \theta^t)$ ;
2. With probability  $A(\theta^*, \theta^t)$ , *accept* the proposal and set  $\theta^{t+1} := \theta^*$ ;
3. Otherwise, *reject* the proposal and set  $\theta^{t+1} := \theta^t$ ;
4. Increment  $t \leftarrow t + 1$  and repeat.

Note that the distributions  $P^0(d\theta)$  and  $P(d\theta)$ , the transition kernel  $Q(d\theta^* | \theta)$ , and the function  $A(\theta^*, \theta)$  are all determined (respectively) by the  $n$ -vectors and  $n \times n$  matrices

$$\begin{aligned} p_i^0 &:= P^0(\{\theta_i\}) \\ p_i &:= P(\{\theta_i\}) \\ q_{ij} &:= Q(\{\theta_j\} | \theta_i) \\ a_{ij} &:= A(\theta_j | \theta_i) \end{aligned}$$

(note conventional ordering of  $i, j$  in  $q$  and  $a$  differ from that of  $\theta_j, \theta_i$  in  $Q$  and  $A$ ). We now turn to the selection of  $A$ .

To achieve Equation (1) we must approach equilibrium—*i.e.*, the probability distribution  $P^t(d\theta)$  of  $\theta^t$  must converge to  $P(d\theta)$ . Suppose we in fact *reach* (or even begin at) equilibrium—*i.e.*, have  $P[\theta^t = \theta_i] = p_i$  for each  $i$ . To maintain equilibrium with our proposed algorithm, we must have:

$$\begin{aligned} p_j &= \sum_i p_i R_{ij} \quad \text{where } R \text{ is our new chain's transition matrix,} \\ R_{ij} &= \begin{cases} q_{ij} a_{ij} & \text{for } i \neq j \\ q_{ii} a_{ii} + \sum_k q_{ik} [1 - a_{ik}] & \text{for } i = j \end{cases} \end{aligned}$$

Thus

$$\begin{aligned} p_j &= \sum_i p_i q_{ij} a_{ij} + \sum_k p_j q_{jk} [1 - a_{jk}] \\ &= \sum_i p_i q_{ij} a_{ij} + \sum_k p_j q_{jk} - \sum_k p_j q_{jk} a_{jk} \\ &= \sum_i p_i q_{ij} a_{ij} + p_j - \sum_i p_j q_{ji} a_{ji} \end{aligned}$$

and so

$$\sum_i p_i q_{ij} a_{ij} = \sum_i p_j q_{ji} a_{ji} \quad (2)$$

for each  $i, j$ . The simplest way to achieve this is to ensure that the stronger condition of “detailed balance” holds: for *every*  $i, j$ ,

$$\begin{aligned} p_i q_{ij} a_{ij} &= p_j q_{ji} a_{ji}, \quad \textit{i.e.}, \\ \frac{a_{ij}}{a_{ji}} &= \frac{p_j q_{ji}}{p_i q_{ij}}. \end{aligned} \quad (3)$$

Evidently anything of the form  $a_{ij} = p_j q_{ji} / c_{ij}$  with  $c_{ij} = c_{ji} > 0$  symmetric will work, provided  $c_{ij} \geq p_j q_{ji}$  (necessary to ensure that  $a_{ij} \leq 1$  and  $a_{ji} \leq 1$ , as required for acceptance probabilities!). One suitable choice is  $c_{ij} := p_i q_{ij} + p_j q_{ji}$ ; the smallest possible choice, leading to the largest possible acceptance probabilities (and so the most mobile chain  $\{\theta^t\}$ ), is  $c_{ij} := \max(p_i q_{ij}, p_j q_{ji})$ , leading to

$$a_{ij} := \frac{p_j q_{ji}}{p_i q_{ij} \vee p_j q_{ji}} = 1 \wedge H_{ij}, \quad H_{ij} := \frac{p_j q_{ji}}{p_i q_{ij}}. \quad (4)$$

The general idea of constructing such a Markov chain is usually attributed to Metropolis et al. (1953), in the course of designing the first hydrogen bomb, who only considered symmetric proposals

$q_{ij} = q_{ji}$  leading to a simpler acceptance probability of  $a_{ij} = 1 \wedge (p_j/p_i)$ . The more general form is due to Hastings (1970), who studied failure probabilities for dams and in honor of whom  $H$  is called the *Hastings ratio*. The special case in which  $H \equiv 1$  (now called “Gibbs sampling”) was (re)discovered in an image reconstructing context by Geman and Geman (1984) and in a more general context by Gelfand and Smith (1990) (several others had similar ideas independently—*e.g.*, Tanner and Wong (1987) and Besag et al. (1995)). Tierney (1994) offers a particularly lucid exposition of the different ways to construct such chains.

By construction,  $\{\theta^t\}$  is a stationary Markov chain on  $\Theta$  with initial distribution  $P^0(\theta_i) = p_i^0$  and transition probability matrix  $R_{ij}$ . It is easy to show that  $R$  will be transitive, irreducible, and aperiodic if  $Q$  is on  $\text{supp}(P) \equiv \{\theta \mid P(\{\theta\}) > 0\}$  (and if  $P^0(\text{supp}(P)) = 1$ ), so by the Perron-Frobenius theorem (see, for example, Horn and Johnson 1990, chap. 8)

$$\sup_j \left| p_j - P[\theta^t = \theta_j] \right| \leq r^t$$

for some  $0 < r < 1$  (namely, the second-largest eigenvalue of  $R$ ). This implies geometric convergence in Equation (1).

## 1.2 Euclidean Spaces

A similar approach holds for state spaces  $\Theta \subset \mathbb{R}^d$  with Borel sets  $\mathcal{F} = \mathcal{B}(\Theta)$ . Here we must specify an initial distribution  $P^0(d\theta)$  on  $\mathcal{F}$  and transition kernel  $Q(d\theta^* \mid \theta)$  on  $\mathcal{F} \times \Theta$ ; we begin with initial value  $\theta^0 \sim P^0(d\theta)$  and accept each proposed move from  $\theta^t$  to  $\theta^* \sim Q(d\theta^* \mid \theta^t)$  with probability  $1 \wedge H(\theta^* \mid \theta^t)$  where

$$H(\theta^* \mid \theta) := \frac{P(d\theta^*) Q(d\theta \mid \theta^*)}{P(d\theta) Q(d\theta^* \mid \theta)},$$

the Radon-Nikodym derivative of two measures on  $\Theta \times \Theta$ —the denominator is the joint equilibrium probability distribution of  $(\theta, \theta^*) = (\theta^t, \theta^{t+1})$ , while the numerator is that of  $(\theta, \theta^*) = (\theta^{t+1}, \theta^t)$ . When  $P$  and  $Q$  have densities with respect to a common reference measure (such as Lebesgue measure  $d\theta$  on  $\mathbb{R}^d$ ), this reduces to a ratio of densities

$$H(\theta^* \mid \theta) := \frac{P(\theta^*) Q(\theta \mid \theta^*)}{P(\theta) Q(\theta^* \mid \theta)}. \tag{5}$$

Note that  $H(\theta^* \mid \theta)$  depends on  $P$  only through the ratio  $P(\theta^*)/P(\theta)$ ; this is an important feature for Bayesian posterior statistical inference, where the posterior distribution

$$\pi(d\theta \mid \mathbf{X}) \propto \pi(d\theta) L(\theta \mid \mathbf{X})$$

is often given only up to an unknown proportionality constant that cancels in Equation (5).

## 2 Poisson and Lévy Random Fields

We now turn our attention to constructing an ergodic Markov chain  $\{\theta^t\}$  whose stationary distribution is absolutely continuous with respect to a Poisson random measure  $\theta \sim \text{Po}(\nu(dx))$  on some

measure space  $(\mathcal{X}, \mathcal{B}, \nu(dx))$ , with some density function  $L(\theta)$ . For  $\mathcal{X}$  of the form  $\mathcal{X} = \mathbb{R} \times \mathcal{S}$  this will let us generate from the posterior distribution of a Lévy random field

$$\Gamma[\phi] = \int_{\mathcal{S}} \phi(\sigma) \Gamma(d\sigma) = \iint_{\mathcal{X}} \phi(\sigma) \nu \theta(d\nu d\sigma) = \sum \phi(\sigma_i) \nu_i$$

upon observing any data  $\mathbf{Y}$  related by a measurement-error model to  $\theta$  (represented through a likelihood function  $L(\theta)$ ), such as:

$$\begin{array}{ll} \text{Normal Regression:} & Y(t) \sim \text{No}(f(t), \sigma^2), \quad f(t) := \Gamma[k(t), \cdot] \\ \text{Gamma Regression:} & Y(t) \sim \text{Ga}(f(t)\phi, \phi), \quad f(t) := \Gamma[k(t), \cdot] \\ \text{Poisson Regression:} & Y(t) \sim \text{Po}(f(t) dt), \quad f(t) := \Gamma[k(t), \cdot] \\ \text{Survival:} & S(t) \sim e^{-H(t)} \quad H(t) := \Gamma[\mathbf{1}_{\{(0,t]\}}(\cdot)] \end{array}$$

The new wrinkle is that the space  $\Theta$  of possible value of  $\theta$  is more complicated than  $\mathbb{R}^d$ . One representation is to identify a finite integer-valued measure on  $\mathcal{X}$  with the (superfluous but convenient) label  $J$  along with an ordered vector  $\{x_j\}_{0 \leq j < J}$  of the  $J$  (not necessarily distinct) points to which it assigns unit mass; thus

$$\Theta := \bigcup_{J=0}^{\infty} \mathcal{X}^J \ni \theta := (J; \{x_j\}_{0 \leq j < J}),$$

the disjoint union of the  $J^{\text{th}}$  Cartesian power  $\mathcal{X}^J$  over all integers  $J \geq 0$ .

## 2.1 Densities

Finding “densities” is more subtle here. If  $dx$  is a fixed reference measure on  $\mathcal{X}$  (perhaps Lebesgue measure, if  $\mathcal{X} \subset \mathbb{R}^d$ ), one possibility is to use

$$d\theta := \sum_{J=0}^{\infty} \mathbf{1}_{\{\Theta^J\}}(\theta) dx_0 dx_2 \cdots dx_{J-1}$$

as a reference measure on  $\Theta$ . The  $\text{Po}(\nu(dx))$  distribution with mean measure  $\nu(dx) = \nu(x)dx$  can then be represented

$$P(d\theta) = \frac{(\nu^+)^J}{J!} e^{-\nu^+} \prod_{0 \leq j < J} \frac{\nu(dx_j)}{\nu^+} = \frac{e^{-\nu^+}}{J!} \prod_{0 \leq j < J} \nu(dx_j)$$

where  $\nu^+ \equiv \nu(\mathcal{X})$ , with density function (w.r.t.  $d\theta$ )

$$P(\theta) = \exp \left\{ -\nu(\mathcal{X}) - \log J! + \sum_{0 \leq j < J} \log \nu(x_j) \right\} \quad (6)$$

Notice that in this representation the  $\{x_j\}$  are *ordered*, even though  $P(d\theta)$  is symmetric; the  $J!$  factor accounts for the multiple labelings the same point might have.

## 2.2 Transitions

To implement MCMC in a multi-dimensional space like  $\Theta$  we must “jump” back and forth among the disjoint subspaces  $\mathcal{X}^J$ . The first implementation of such a scheme (and the name “reversible jump MCMC”, or RJ-MCMC) appeared in (Green 1995), although our treatment is rather different.

We must build a transition probability kernel  $Q(d\theta^* | \theta)$  to generate proposed moves on  $\Theta$  that is transitive, irreducible, and aperiodic. Transitivity requires that we be able to reach any level  $\mathcal{X}^J$  from any other  $\mathcal{X}^I$ ; obviously it’s enough to be able to increment  $J \geq 0$  and decrement  $J \geq 1$  by one. Incrementing entails a probability distribution  $\beta(dx)$  for the “birth,” which we take to have density function  $\beta(x)$ ; movement within  $\mathcal{X}^J$  can be built from any convenient Markov kernel  $q(dx^* | x)$  on  $\mathcal{B} \times \mathcal{X}$ , or even from a *sub*-Markov kernel (*i.e.*, one for which  $q(\mathcal{X} | x) \leq 1$ — we just one can always extend it to be a Markov kernel on some  $\tilde{\mathcal{X}} \supset \mathcal{X}$ ) if we regard a step “outside” of  $\mathcal{X}$  as a “death.” Specify a strictly probability triplet<sup>1</sup>  $\mathbf{p} = (p_-, p_+, p_+)$  with  $p_- + p_- + p_+ = 1$ , a birth probability density  $\beta(x)$  on  $\mathcal{X}$ , and a sub-Markov kernel  $q(dx^* | x)$ ; with these in hand we describe transitions on  $\Theta$  as follows. Beginning at  $\theta = (J; \{x_j\}_{0 \leq j < J})$ ,

**B** Birth step: with probability  $p_+$ , draw an index  $0 \leq j \leq J$  uniformly and a new point  $x^* \sim \beta(x)dx$ ; set

$$\theta^* = (J+1; \{x_0, \dots, x_{j-1}, x^*, x_j, \dots, x_{J-1}\}).$$

**D** Death step: with probability  $p_-$  and  $J \geq 1$ , “kill” a point— draw an index  $0 \leq j < J$  uniformly and set

$$\theta^* = (J-1; \{x_0, \dots, x_{j-1}, \quad x_{j+1}, \dots, x_{J-1}\}).$$

**M** Movement step: with probability  $p_+$  and  $J \geq 1$ , draw  $0 \leq j < J$  uniformly and a new point  $x^* \sim q(x^* | x_j) dx$ . If  $x^* \in \mathcal{X}$  and  $\nu(x^*) > 0$ , set

$$\theta^* = (J; \{x_0, \dots, x_{j-1}, x^*, x_{j+1}, \dots, x_{J-1}\});$$

if  $x^* \notin \mathcal{X}$  (recall the *sub*-Markov transition may have  $q(\mathcal{X} | x_j) < 1$ ) or  $\nu(x^*) = 0$ , treat this as the death of  $x_j$ , as in step **D** above.

Altogether the transition density w.r.t.  $d\theta$  is:

$$Q(\theta^* | \theta) = \begin{cases} \mathbf{B} : & \frac{1}{J+1} p_+ \beta(x^*) \\ \mathbf{D} : & \frac{1}{J} [p_- + p_- q^-(x_j)] \\ \mathbf{M} : & \frac{1}{J} p_+ q(x^* | x_j) \end{cases} \quad (7)$$

where  $q^-(x) := [1 - q(\mathcal{X} | x)]$ .

## 2.3 Hastings Ratio

We now construct the Hastings ratio  $H(\theta^* | \theta)$  of Equation (5) from the ingredients in Equations (6, 7). If  $L(\theta)$  is a likelihood function (or other expression for which  $L(\theta)P(d\theta)$  is proportional

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<sup>1</sup>Actually it’s possible to have  $\mathbf{p} = \mathbf{p}(J)$  depend on  $J$ ... convenient to arrange  $p_-(0) = p_+(0) = 0$ , for example.

to the intended stationary distribution for our chain— *e.g.*,  $L \equiv 1$  to draw samples from the prior distribution itself), the Hastings ratio is:

$$H(\theta^* | \theta) = \begin{cases} \mathbf{B} : & \frac{\nu(x^*)}{J+1} \frac{L(\theta^*)}{L(\theta)} \frac{[p_- + p_- q^-(x^*)]}{p_+ \beta(x^*)} \\ \mathbf{D} : & \frac{J}{\nu(x_j)} \frac{L(\theta^*)}{L(\theta)} \frac{p_+ \beta(x_j)}{[p_- + p_- q^-(x_j)]} \\ \mathbf{M} : & \frac{\nu(x^*)}{\nu(x_j)} \frac{L(\theta^*)}{L(\theta)} \frac{q(x_j|x^*)}{q(x^*|x_j)}. \end{cases} \quad (8)$$

Note that we needn't have required that  $\nu(dx)$ ,  $\beta(dx)$ , and  $q(dx | x^*)$  all have densities with respect to some specific measure  $dx$ , but we do need  $\beta(dx) \ll \nu(dx)$ ; to allow “death” moves from anywhere in  $\mathcal{X}$ , the birth distribution  $\beta(dx)$  must also have full support (so  $\beta(dx) \equiv \nu(dx)$ ). Also note that the  $\mathbf{M}$  step is simply the ratio of posterior densities in the (common) case of a symmetric proposal distribution with  $q(y | x) = q(x | y)$ .

### 3 Examples

#### 3.1 Gamma RF in $\mathbb{R}^2$

The homogeneous Gamma random field  $\Gamma(ds) \sim \text{Ga}(\alpha ds, \beta)$  on the unit square  $\mathcal{S} = [0, 1]^2$  has infinite Lévy measure

$$\nu(du ds) = \alpha e^{-\beta u} u^{-1} \mathbf{1}_{\{u>0\}} du ds$$

on  $\mathbb{R} \times \mathcal{S}$ . To use the methods of Section (2) we must first approximate the distribution by one with finite Lévy measure. One way is to select a small number  $\epsilon > 0$  and construct a random field with Lévy measure

$$\nu_\epsilon(du ds) = \alpha e^{-\beta u} u^{-1} \mathbf{1}_{\{u>\epsilon\}} du ds$$

on  $\mathbb{R} \times \mathcal{S}$ , with finite mass

$$\nu_\epsilon^+ := \nu_\epsilon(\mathbb{R} \times \mathcal{S}) = \alpha \int_\epsilon^\infty e^{-\beta u} u^{-1} du = \alpha E_1(\beta \epsilon),$$

where  $E_1(z) := \int_z^\infty x^{-1} e^{-x} dx$  denotes Gauss's exponential integral function (Abramowitz and Stegun 1964, *p.* 228). We may view  $\nu_\epsilon$  as a measure on  $\mathcal{X} := \mathbb{R}_+ \times \mathcal{S}$  and, from a Poisson random measure  $H \sim \text{Po}(\nu_\epsilon(dx))$ , construct an approximate Gamma RF by setting

$$\begin{aligned} \Gamma(A) &= \int_A \Gamma(ds) = \iint_{\mathbb{R}_+ \times A} u N(du ds) \\ \Gamma[\phi] &= \int_{\mathcal{S}} \phi(s) \Gamma(ds) = \iint_{\mathbb{R}_+ \times \mathcal{S}} \phi(s) u N(du ds) \end{aligned}$$

##### 3.1.1 Birth Steps

With a birth distribution  $\beta(dx)$  for  $x = (u, s)$  assigning independent exponentially distributed magnitudes  $u \sim \epsilon + \text{Ex}(\lambda)$  and uniformly distributed locations  $s \sim \text{Un}(\mathcal{S})$ , the Lévy measure  $\nu$  and birth distribution  $\beta$  are mutually absolutely continuous, with Lebesgue density functions

$$\nu(x) = \alpha e^{-\beta u} u^{-1} \mathbf{1}_{\{[\epsilon, \infty) \times \mathcal{S}\}}(x) \quad \beta(x) = \lambda e^{-\lambda(u-\epsilon)} \mathbf{1}_{\{[\epsilon, \infty) \times \mathcal{S}\}}(x)$$

### 3.1.2 Movement Steps and Hastings Ratios

Any symmetric Markov random walk on  $[\epsilon, \infty) \times \mathcal{S}$  (for example, one taking independent Gaussian steps in each of the three dimensions, with reflecting boundary conditions at  $u \geq \epsilon$  and at  $0 \leq s_i \leq 1$ ) yields  $q^-(x) \equiv 0$  and a symmetric  $q(x^* | x) = q(x | x^*)$ ; with unit likelihood  $L(x) \equiv 1$  this leads to

$$H(\theta^* | \theta) = \begin{cases} \mathbf{B} : & \frac{\alpha p_-}{\lambda \exp(\lambda\epsilon) p_+} \frac{\exp((\lambda-\beta)u^*)}{(J+1) u^*} \\ \mathbf{D} : & \frac{\lambda \exp(\lambda\epsilon) p_+}{\alpha p_-} \frac{J u_j}{\exp((\lambda-\beta)u_j)} \\ \mathbf{M} : & \exp(\beta(u_j - u^*)) (u_j/u^*) \end{cases}$$

Conversely, independent normal random walks  $s_i^* | s_i \sim \text{No}(s_i, \sigma_s^2)$  for locations (which might step outside  $\mathcal{S}$ , leading to a “death”) and log-normal  $u^* | u \sim \text{LN}(\log u, \sigma_u^2)$  for magnitudes (which might step below  $u < \epsilon$ , again leaving the domain), renders a subMarkov transition with

$$\begin{aligned} q^-(x) &= 1 - \Phi\left(\log(u/\epsilon)/\sigma_u\right) \times \left[ \Phi\left(\frac{1-s_1}{\sigma_s}\right) - \Phi\left(\frac{s_1}{\sigma_s}\right) \right] \\ &\quad \times \left[ \Phi\left(\frac{1-s_2}{\sigma_s}\right) - \Phi\left(\frac{s_2}{\sigma_s}\right) \right] \\ q(x^* | x) &= \frac{1}{\sigma_u u^*} \varphi\left(\frac{1}{\sigma_u} \log\left(\frac{u^*}{u}\right)\right) \times \frac{1}{\sigma_s} \varphi\left(\frac{s_1^* - s_1}{\sigma_s}\right) \times \frac{1}{\sigma_s} \varphi\left(\frac{s_2^* - s_2}{\sigma_s}\right) \end{aligned}$$

where  $x = (u, s)$  and  $x^* = (u^*, s^*)$ ; here  $\varphi(z)$  and  $\Phi(z)$  denote the pdf and CDF of the standard  $\text{No}(0, 1)$  distribution, respectively. Note our transition kernel  $q(x^* | x)$  is subMarkov; we treat random walk steps that lead  $x^* \notin \mathcal{S}$  or  $u^* < \epsilon$  as the death of a point at  $x$ . These (along with  $L(x) \equiv 1$ ) let us calculate the Hastings ratio  $H(\theta^* | \theta)$  of Equation (8), all that’s needed to generate a Markov chain  $\{\theta^t\}$  and hence  $\{\Gamma^t\}$  from the intended distribution:

$$H(\theta^* | \theta) = \begin{cases} \mathbf{B} : & \frac{\alpha [p_- + p_- q(x^*)]}{\lambda \exp(\lambda\epsilon) p_+} \frac{\exp((\lambda-\beta)u^*)}{(J+1) u^*} \\ \mathbf{D} : & \frac{\lambda \exp(\lambda\epsilon) p_+}{\alpha [p_- + p_- q(x_j)]} \frac{J u_j}{\exp((\lambda-\beta)u_j)} \\ \mathbf{M} : & \exp(\beta(u_j - u^*)) \end{cases}$$

## 4 Posterior ILM Sampling

As an alternative to the RJ-MCMC  $\epsilon$ -truncation approach of Section (2), we can use the Inverse Lévy Measure algorithm of Wolpert and Ickstadt (1998a,b) in which a fixed number  $J$  of mass points are generated. The classic ILM approach begins by writing a Lévy measure  $\nu$  on  $\mathcal{X} = \mathbb{R}_+ \times \mathcal{S}$  in semidirect product form

$$\begin{aligned} \nu(dx) &= \nu_u(dr) \nu_s(ds | u) \\ \nu^+(r) &= \nu_u((u, \infty)) \\ \nu^{\leftarrow}(t) &= \inf\{r > 0 : \nu^+(r) \leq t\}. \end{aligned}$$

Now fix  $J \in \mathbb{N}$  and draw the first  $J$  event times  $0 < \tau_1 < \tau_2 < \dots < \tau_J$  of a unit-rate Poisson process. Set

$$\begin{aligned} r_j &= \nu^\leftarrow(\tau_j) \\ s_j &\sim \nu_s(ds \mid r_j) \\ \Gamma(ds) &= \sum_{j=1}^J r_j \delta_{s_j}(ds). \end{aligned}$$

This sum with  $J = \infty$  would have exactly the target Lévy distribution; since the  $\{r_j\}$  are drawn in decreasing order, with finite  $J < \infty$ , it includes the  $J$  largest mass points and for that reason can be more efficient than some other approximate methods. For *posterior* sampling, a Metropolis-Hastings approach will be required— but, this time, with a fixed number  $J$  of mass points and so without need for reversible jumps.

When both  $\nu_u(dr) = \nu_u(r) dr$  and  $\nu_s(ds \mid u) = \nu_s(s \mid u) ds$  have density functions (wrt arbitrary reference measures  $dr$  and  $ds$  on  $\mathbb{R}_+$  and  $\mathcal{S}$ , respectively), the prior pdf is available by change of variables from that of the  $\{\tau_j = \nu^+(r_j)\}$ :

$$\begin{aligned} \tau_1, \dots, \tau_J &\sim e^{-\tau_J} \mathbf{1}_{\{0 < \tau_1 < \dots < \tau_J\}} d\tau_1 \cdots d\tau_J &\Rightarrow \\ r_1, \dots, r_J &\sim \exp(-\nu^+(r_J)) |\nu^{+'}(r_1) \cdots \nu^{+'}(r_J)| \mathbf{1}_{\{0 < r_J < \dots < r_1\}} dr_1 \cdots dr_J \\ s_1, \dots, s_J &\sim \nu_s(s_1 \mid r_1) \cdots \nu_s(s_J \mid r_J) ds_1 \cdots ds_J. \end{aligned}$$

With this and the likelihood ratio in hand, a M-H scheme can be constructed with only conventional moves of the  $\{r_j\}$  (preserving order) and the  $\{s_j\}$ . Block moves (in which the entire vector  $\vec{u}$  is replaced with another of the form  $\nu^\leftarrow(\vec{r})$ ) are a good choice in some problems. The Hastings ratio for a move  $\theta \rightarrow \theta^*$  for  $\theta = (\vec{u}, \vec{s})$  is

$$H(\theta^* \mid \theta) = \frac{L(\theta^*)}{L(\theta)} \left\{ e^{\nu^+(r_J) - \nu^+(r_J^*)} \prod_{j=1}^J \frac{\nu^{+'}(r_j^*) \nu_s(s_j^* \mid r_j^*)}{\nu^{+'}(r_j) \nu_s(s_j \mid r_j)} \right\} \frac{Q(\theta \mid \theta^*)}{Q(\theta^* \mid \theta)}.$$

#### 4.1 Explicit Example: ILM for Gamma Random Fields

Again we consider the Gamma  $\text{Ga}(\alpha ds, \beta)$  random field on  $\mathcal{S} = [0, 1]^2$ . This time we use the ILM algorithm, with reflecting symmetric Gaussian random walk steps in  $s_j \in \mathcal{S}$  and log-scale Gaussian random walk steps in  $r_j \in \mathbb{R}_+$ . For this example  $\nu^+(r) = \alpha E_1(\beta r)$  with derivative  $\nu^{+'}(r) = -\alpha r^{-1} e^{-\beta r}$ , while  $Q(\theta \mid \theta^*)/Q(\theta^* \mid \theta) = \prod (r_j^*/r_j)$ , so

$$H(\theta^* \mid \theta) = \frac{L(\theta^*)}{L(\theta)} \exp\left(\alpha [E_1(\beta r_J) - E_1(\beta r_J^*)] + \beta \sum (r_j - r_j^*)\right).$$

Random walk steps are allowed to change the ordering of the  $\{r_j\}$ ; just sort after the proposed move, to ensure that  $r_J^* = \min\{r_j^*\}$ . Since  $E_1(z) \approx -\log z - \gamma_e$  for small  $z$ ,

$$h(\theta^* \mid \theta) \equiv \log H(\theta^* \mid \theta) \approx [\ell(\theta) - \ell(\theta^*)] + \alpha \log(r_J^*/r_J) + \beta \sum (r_j - r_j^*)$$

where  $\ell(\theta) = -\log L(\theta)$ . A good starting point is  $\vec{u} = \{r_j\}$ ,  $r_j = \exp(-\gamma_e - j/\alpha)/\beta$  (why?).



## 4.2 Explicit Example: ILM for $\alpha$ -Stable Random Fields

For  $0 < \alpha < 1$ ,  $\beta \in [-1, 1]$ ,  $\gamma \in \mathbb{R}_+$ , and  $\delta = 0$ , a random measure  $\zeta(ds) \sim \text{St}_\Lambda(\alpha, \beta, \gamma ds, 0)$  can be constructed on (say) the unit interval  $[0, 1]$  by the ILM algorithm as

$$\zeta(ds) = \sum_{j < \infty} r_j \sigma_j \delta_{s_j}(ds)$$

for  $\tau_0 = 0$  and

$$\begin{aligned} r_j &= (\tau_j / \gamma c_\alpha)^{-1/\alpha}, \quad [\tau_j - \tau_{j-1}] \stackrel{\text{iid}}{\sim} \text{Ex}(1) \\ \sigma_j &= (2\zeta_j - 1), \quad \zeta_j \stackrel{\text{iid}}{\sim} \text{Bi}(1, (1 + \beta)/2) \\ s_j &\stackrel{\text{iid}}{\sim} \text{Un}(\mathcal{S}) \end{aligned}$$

where  $c_\alpha = \frac{2}{\pi} \Gamma(\alpha) \sin \frac{\pi\alpha}{2}$ , or may be approximated by the first  $J$  terms of that sum. Here  $\mathcal{S} = (0, 1) \times \{\pm 1\}$  with elements  $(s_j, \sigma_j)$ . For *posterior* sampling as in Section (4), note  $\nu_u^{+\prime}(r) = \gamma c_\alpha \alpha r^{-\alpha-1}$ . For independent symmetric random walk (say, Gaussian) steps in  $r_j$  on a log scale, and srw steps in  $s_j$  (say, Gaussian w/ reflecting bc), and  $\sigma_j = \pm 1$ , the log Hastings ratio becomes

$$h(\theta^* | \theta) = \ell(\theta) - \ell(\theta^*) + \gamma c_\alpha (r_J^{-\alpha} - r_J^{*\alpha}) + \alpha \sum_{j=1}^J \log(r_j / r_j^*) + \log \left( \frac{1+\beta}{1-\beta} \right) \sum_{j=1}^J (\sigma_j^* - \sigma_j) / 2,$$

with  $r_j = (\gamma c_\alpha / j)^{1/\alpha}$  and  $\sigma_j = (2\zeta_j - 1)$ ,  $\zeta_j \sim \text{Bi}(1, (1 + \beta)/2)$  a good starting point.

## 5 Dirichlet Random Fields

For any finite partition  $\mathcal{S} = \cup \Lambda_j$  of a finite measure space  $(\mathcal{S}, \mathcal{F}, \alpha(ds))$  with  $\alpha^+ \equiv \alpha(\mathcal{S}) < \infty$ , the Dirichlet random field  $\mathcal{D} \sim \text{Di}(\alpha(ds))$  assigns random variables  $p_j = \mathcal{D}(\Lambda_j)$  whose joint distribution is Dirichlet  $\vec{p} \sim \text{Di}(\vec{\alpha})$  with parameter vector  $\vec{\alpha} = \{\alpha_j\}$ ,  $\alpha_j = \alpha(\Lambda_j)$ . Dirichlet RFs are frequently used to model uncertain probability distributions, because they're easy to interpret (the mean and variance are  $\text{E}\mathcal{D}(A) = \alpha(A)/\alpha(\mathcal{X})$  and  $\text{V}\mathcal{D}(A) = \alpha(A)\alpha(A^c)/\alpha(\mathcal{X})^2(1 + \alpha(\mathcal{X}))$ , so  $\alpha/\alpha^+$  is the “prior mean” and  $\alpha^+$  quantifies prior precision) and trivial to compute with (they're conjugate for observations  $X_j \sim \mathcal{D}$ ).

A Dirichlet random field can be constructed by normalizing the Gamma RF of Sec. (3.1) or (4.1):

$$\mathcal{D}(A) = \Gamma(A) / \Gamma(\mathcal{S})$$

for  $A \subset \mathcal{S}$ , with  $\Gamma(ds) \sim \text{Ga}(\alpha(ds), \beta)$  for any constant  $\beta > 0$  (say, one)— the constant cancels when we normalize.

BUT— the Dirichlet has several unfortunate features that limit its utility. One is its discreteness ( $\mathcal{D}$  is a discrete distribution with probability one, so even if  $\alpha$  has a density it is certain that observations  $\{X_n\} \sim \mathcal{D}$  will feature ties), and another is the constancy of its precision  $\alpha^+$ , which precludes assigning “vaguer” prior distributions in some parts of  $\mathcal{S}$  than in others. The discreteness can be overcome by taking kernel mixtures  $\int k(x, s) \mathcal{D}(ds)$ , at the expense of losing the computational triviality, while the uniform precision can be overcome by replacing the constant  $\beta$  by a function  $\beta(s)$  above; the same computational approach described in Section (3.1) with Lebesgue measure replaced by  $\alpha(ds)$  and the constant  $\beta$  by a function  $\beta(s)$ , leading to

$$\nu(dr ds) = \alpha(ds) e^{-\beta(s)r} r^{-1} \mathbf{1}_{\{r > 0\}} dr$$

will suffice to generate prior and posterior distributions for a generalization of  $\mathcal{D}(ds)$ .

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## Appendix: Inference for Poisson Random Measures

Let  $\nu_\theta(dx)$  be a family of *finite* nonnegative Borel measures on a complete separable metric space (“Polish” space)  $\mathcal{X}$ , indexed by  $\theta \in \Theta$ . In this section we consider the problem of finding a likelihood function for  $\theta$ , upon observing a Poisson random field  $N(dx) \sim \text{Po}(\nu(dx))$ . Begin with the assumption that some single  $\sigma$ -finite Borel reference measure  $\mu(dx)$  dominates  $\nu_\theta(dx)$  for *each*  $\theta \in \Theta$ , and that a regular conditional probability density function exists so that

$$\nu_\theta(dx) = \nu(x, \theta) \mu(dx)$$

for a Borel measurable function  $\nu : \mathcal{X} \times \Theta \rightarrow \mathbb{R}_+$ .

For any partition  $\mathcal{X} = \cup \Lambda_j$  into disjoint Borel sets with  $\bar{\Lambda}_j$  compact, each  $\lambda_j(\theta) \equiv \nu_\theta(\Lambda_j)$  and  $\mu_j \equiv \mu(\Lambda_j)$  is finite. The random variables  $N_j \equiv N(\Lambda_j)$  are independent, each Poisson distributed with mean  $\nu_j(\theta)$ , so the likelihood  $L(\theta)$  upon observing all the  $\{N_j\}$  would be any nonnegative multiple of

$$\begin{aligned} L(\theta) &= \prod_j \left\{ \frac{\nu_j(\theta)^{N_j}}{N_j!} e^{-\nu_j(\theta)} \right\} \\ &\propto \left\{ \prod_j \left( \frac{\nu_j(\theta)}{\mu_j} \right)^{N_j} \right\} e^{-\sum \nu_j(\theta)} \end{aligned}$$

Enumerate the (random and countable) support  $\{x_n\}$  of  $N(dx)$ , and let  $j_n$  be the index of the partition element  $\Lambda_{j_n}$  containing  $x_n$ . Then

$$L(\theta) = \left\{ \prod_n \left( \frac{\nu_{j_n}(\theta)}{\mu_{j_n}} \right)^{N_{j_n}} \right\} e^{-\nu_\theta(\mathcal{X})}$$

Now take successive refinements of the partition  $\{\Lambda_j\}$  with  $\text{diam}(\Lambda_j) \rightarrow 0$ . Since every Polish space is Radon, it follows that  $\nu_{j_n}(\theta)/\mu_{j_n} = \nu_\theta(\Lambda_{j_n})/\mu(\Lambda_{j_n})$  converges to  $\nu(x_n, \theta)$ , so

$$\rightarrow e^{-\nu_\theta(\mathcal{X})} \prod_n \nu(x_n, \theta).$$

Note that our requirement that each  $\nu^+(\theta) \equiv \nu_\theta(\mathcal{X}) < \infty$  was necessary for this to be well-defined. Also the formula remains correct even if, for some  $\theta$ ,  $\nu_\theta$  (and hence  $\mu$ ) has atoms; in that case some of the  $\{x_n\}$  may coincide. Both Bayesian and sampling-based inference about  $\theta$  now depend on the data only through the negative log likelihood function,

$$\ell(\theta) = -\log L(\theta) = \nu^+(\theta) - \sum \log \nu(x_n, \theta).$$